# Separations inside a cube 

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#### Abstract

Two points are randomly selected inside a threedimensional euclidian cube. The value $l$ of their separation lies somewhere between zero and the length of a diagonal of the cube. The probability density $\mathcal{P}(l)$ of the separation is constructed analytically. Also a M onte Carlo computer simulation is performed, showing good agreement with the formulas obtained.


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## 1 Introduction

An important problem in geometry and statistics is: given a convex compact space endowed with a metric, and randomly choosing two points in the space, find the probability density $\mathcal{P}(l)$ that these points have a specified separation $l$. The study of this problem has a long history [1], and recently gained considerable impetus from researchers in cosmic crystallography [2]-[19].

In a recent paper the functions $\mathcal{P}(l)$ corresponding to $2 D$ disks and rectangles were obtained [20]. The methodology introduced in that work is here extended to a $3 D$ euclidian cube.

## 2 Preliminaries

An euclidian cube with side $a$ is assumed, occupying the location $0<x, y, z<a$ in a cartesian frame. Randomly choosing two points $A$ and $B$ in the cube, we want the probability $\mathcal{P}(l) d l$ that the separation between the points lie between $l$ and $l+d l$. The probability density $\mathcal{P}(l)$ has to satisfy the normalization condition

$$
\begin{equation*}
\int_{0}^{\sqrt{3} a} \mathcal{P}(l) d l=1 . \tag{1}
\end{equation*}
$$

The calculation can be shortened if one considers the symmetries of the cube. Really, if the points $A$ and $B$ have been chosen, imagine the oriented segment $A^{\prime} B^{\prime}$ parallel to $A B$, with the tip $A^{\prime}$ coinciding with the origin $O$. The other tip $B^{\prime}$ then lies inside a larger cube, with side $2 a$. Since the probability density $\mathcal{P}(l)$ clearly does not depend on which octant of the large cube contains $B^{\prime}$, there is no loose in generality in restricting the calculation to the cases where $B^{\prime}$ is in the octant $0<x, y, z<a$.

With this assumption, the point $B^{\prime}$ has cartesian coordinates

$$
B^{\prime}=(l \cos \theta \cos \phi, l \cos \theta \sin \phi, l \sin \theta),
$$

where both angles $\theta, \phi$ are bound to the interval $[0, \pi / 2]$; here $\phi$ is the azimuthal angle, while $\theta$ is the polar angle measured from the $z=0$ plane. The corresponding tip $B$ in
the original segment must lie inside a parallelepiped with sides (see figure 1)

$$
\begin{equation*}
l_{x}:=a-l \cos \theta \cos \phi, \quad l_{y}:=a-l \cos \theta \sin \phi, \quad l_{z}:=a-l \sin \theta \tag{2}
\end{equation*}
$$



Figure 1 The endpoint $B$ of the segment $A B$ must lie inside the parallelepiped with a corner at $B^{\prime}(l, \phi, \theta)$.

The probability $\mathcal{P}(l, \theta, \phi) d l d \theta d \phi$ that the segment $A B$ has length between $l$ and $l+d l$, azimuth between $\phi$ and $\phi+d \phi$, and polar angle between $\theta$ and $\theta+d \theta$ is then

$$
\begin{equation*}
\mathcal{P}(l, \theta, \phi) d l d \theta d \phi=k l_{x} l_{y} l_{z} l^{2} \cos \theta d l d \theta d \phi \tag{3}
\end{equation*}
$$

where $k$ is a constant and where the assumption $0<\phi, \theta<\pi / 2$ stands. Performing the angular integrations we shall obtain

$$
\begin{equation*}
\mathcal{P}(l)=\iint \mathcal{P}(l, \theta, \phi) d \theta d \phi \tag{4}
\end{equation*}
$$

and we finally fix $k$ using the condition (1).
To calculate $\mathcal{P}(l)$, three cases need be separately considered, depending on the value of $l$ relative to $a$ : namely the cases $0<l<a, a<l<\sqrt{2} a$, and $\sqrt{2} a<l<\sqrt{3} a$.

## 3 The case $0<l<a$

As is seen in the figure 2, in this case we effectively have $\phi_{\min }=\theta_{\min }=0$, and $\phi_{\max }=$ $\theta_{\max }=\pi / 2$. Then

$$
\begin{align*}
\mathcal{P}(l<a) & =k l^{2} \int_{0}^{\pi / 2} l_{z} \cos \theta d \theta \int_{0}^{\pi / 2} l_{x} l_{y} d \phi  \tag{5}\\
& =\frac{k l^{2}}{8}\left[4 \pi a^{3}-6 \pi a^{2} l+8 a l^{2}-l^{3}\right], \tag{6}
\end{align*}
$$

where $k=8 / a^{6}$ as will be fixed later on.


Figure 2 T he triangular intersection of the $2 D$ sphere with radius $l$ and centre $O$ with the $3 D$ cube having side $a>l$.

## 4 The case $a<l<\sqrt{2} a$

In this case the intersection of the $2 D$ sphere (with radius $l$ ) with the $3 D$ cube (with side $a)$ is an hexagonal surface as in figure 3 .


Figure 3 T he hexagonal intersection of a $2 D$ sphere with radius $l$ and centre $O$ with a $3 D$ cube with a vertex in $O$ and having side $a$ such that $a<l<\sqrt{2} a$.

We note that the arcs of circle drawn on the faces $x, y, z=0$ have radius $l$, while those drawn on the faces $x, y, z=a$ have radius $\sqrt{l^{2}-a^{2}}$.

For convenience of integration we divide the intersection into two regions. In region $I$ we have $\cos ^{-1}(a / l)<\theta<\sin ^{-1}(a / l)$ and $0<\phi<\pi / 2$.

In region $I I$ we have $\theta_{\text {min }}=0$ and $\theta_{\text {max }}=\cos ^{-1}(a / l)$. To have $\phi_{\text {min }}(\theta)$ we note that
the circle drawn on the face $x=a$ satisfies the equation $\cos \phi \cos \theta=a / l$, so

$$
\begin{equation*}
\phi_{\min }(\theta)=\cos ^{-1}\left(\frac{a}{l \cos \theta}\right)=: \phi_{1}(\theta) . \tag{7}
\end{equation*}
$$

On the other hand, the circle drawn on the face $y=a$ satisfies $\sin \phi \cos \theta=a / l$, so we have

$$
\begin{equation*}
\phi_{\max }(\theta)=\sin ^{-1}\left(\frac{a}{l \cos \theta}\right)=: \phi_{2}(\theta) . \tag{8}
\end{equation*}
$$

We then find

$$
\begin{array}{r}
\mathcal{P}(a<l<\sqrt{2} a) \\
=k l^{2}\left[\int_{\cos ^{-1}(a / l)}^{\sin ^{-1}(a / l)} \cos \theta d \theta \int_{0}^{\pi / 2} d \phi+\int_{0}^{\cos ^{-1}(a / l)} \cos \theta d \theta \int_{\phi_{1}(\theta)}^{\phi_{1}(\theta)} d \phi\right] l_{x} l_{y} l_{z} \\
=\frac{k l}{8}\left[2 l^{4}+6 a^{2} l^{2}-a^{4}-2 \pi a^{3}(4 l-3 a)-8 a\left(2 l^{2}+a^{2}\right) \sqrt{l^{2}-a^{2}}\right. \\
\left.+24 a^{2} l^{2} \cos ^{-1}(a / l)\right], \tag{10}
\end{array}
$$

where $k=8 / a^{6}$ as will be fixed later on.

## 5 The case $\sqrt{2} a<l<\sqrt{3} a$

In this case the $2 D$ sphere with radius $l$ intersects the $3 D$ cube with side $a$ in the triangular surface shown in figure 4.


Figure 4 The triangular intersection of a $2 D$ sphere with radius $l$ and centre $O$ with a $3 D$ cube with a vertex in $O$ and having side $a$ such that $\sqrt{2} a<l<\sqrt{3} a$.

As before, the circles drawn on the faces $x, y, z=a$ have radius $\sqrt{l^{2}-a^{2}}$. The azimuthal integration is performed between $\phi_{1}(\theta)$ and $\phi_{2}(\theta)$ as in the region $I I$ of the preceding
case, and again $\sin \theta_{\text {max }}=a / l$; but now $\cos \theta_{\text {min }}=\sqrt{2} a / l$. We then find

$$
\begin{array}{r}
\mathcal{P}(\sqrt{2} a<l<\sqrt{3} a)=k l^{2} \int_{\cos ^{-1}(\sqrt{2} a / l)}^{\sin ^{-1}(a / l)} l_{z} \cos \theta d \theta \int_{\phi_{1}(\theta)}^{\phi_{2}(\theta)} l_{x} l_{y} d \phi \\
=\frac{k l}{8}\left[8 a\left(l^{2}+a^{2}\right) \sqrt{l^{2}-2 a^{2}}-\left(l^{2}+a^{2}\right)\left(l^{2}+5 a^{2}\right)+2 \pi a^{2}\left(3 l^{2}-4 a l+3 a^{2}\right)\right. \\
\left.+24 a^{3} l \sec ^{-1}\left(l^{2} / a^{2}-1\right)-24 a^{2}\left(l^{2}+a^{2}\right) \sec ^{-1} \sqrt{l^{2} / a^{2}-1}\right], \tag{12}
\end{array}
$$

where $k=8 / a^{6}$.
This value for the constant $k$ derives from the normalization condition (1), namely,

$$
\begin{equation*}
\int_{0}^{a} \mathcal{P}(l<a) d l+\int_{a}^{\sqrt{2} a} \mathcal{P}(a<l<\sqrt{2} a) d l+\int_{\sqrt{2} a}^{\sqrt{3} a} \mathcal{P}(\sqrt{2} a<l<\sqrt{3} a) d l=1 . \tag{13}
\end{equation*}
$$

## 6 Graphs of $\mathcal{P}(l)$

In figure 5 we present a graph of the dimensionless function $a \mathcal{P}(l)$ against the dimensionless variable $l / a$.


Figure 5 The probability density $\mathcal{P}(l)$ of separation $l$ of pairs of randomly distributed points inside a cube with side $a$. The irregular curve is the output of a corresponding computer simulation.

We note that the function and its first derivative are continuous in the whole interval $0<$ $l<\sqrt{3} a$. Nevertheless the second derivative is discontinuous at $l=a$, as discussed in the next section. In the figure a normalized histogram corresponding to 150,000 separations between pairs of points randomly selected in the cube is superimposed, for comparison; the agreement of the two curves evinces the correctness of the calculation.

## 7 Comments

The integration to find $\mathcal{P}(l)$ in eqs. (5)-(6) is almost trivial; however, not the same can be said about the two other cases, namely in going from (9) to (10) and from (11) to (12). A computer assistance appears paramount in these two cases, to confirm every short step in the calculation and simplification of expressions.

Similarly as in [20], the probability density $\mathcal{P}(l)$ and its first derivative are continuous throughout the entire range $0<l<\sqrt{3} a$. But the second derivative shows a finite discontinuity at $l=a$, although it is continuous at $l=\sqrt{2} a$.

A remarkable feature of $\mathcal{P}(l)$ is its behaviour for large values of $l$; really, near $l=\sqrt{3} a$ we find

$$
\begin{equation*}
a \mathcal{P}(l)=\frac{9}{5}(\sqrt{3}-l / a)^{5}+O\left((\sqrt{3}-l / a)^{6}\right), \tag{14}
\end{equation*}
$$

so $\mathcal{P}(l)$ is essentially a fifth power of $\sqrt{3}-l / a$. We find that $91 \%$ of the separations lie in the range $l \in(0, a), 9 \%$ lie in the interval $l \in(a, \sqrt{2} a)$, and only $0.04 \%$ have $l>\sqrt{2} a$.

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