CBPF-NF-027/82 NON-HOLONOMY AND THE DIFFUSION OF PARTICLES-II

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P. Carrilho Soares' and L.C.Gomes

Centro Brasileiro de Pesquisas Físicas Rua Xavier Sigaud, 150 22290 - Rio de Janeiro, RJ - Brasil

' Departamento de Física Nuclear Instituto de Física Universidade Federal do Rio de Janeiro Rio de Janeiro, RJ - Brasil

NON-HOLONOMY AND THE DIFFUSION OF PARTICLES - II

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P. Carrilho Sogres

Departamento de Física Nuclear, I.F./U.F.R.J.

and

L.C. Gomes

Centro Brasileiro de Pesquisas Físicas, Rio de Janeiro

ABSTRACT

We have obtained the equilibrium solution of the Fokker-Planck equation for both liouvillian and non-liouvillian systems. We have exhibited the procedure to solve the diffusion equation for non-holonomic systems. We presented a suggestion to where such systems may be found in nature, at the microscopic level.

RESUMO

Obtivemos a solução de equilibrio da equação de Fokker--Planck tanto para sistemas liouvillianos quanto para não-liouvillianos. Mostramos o procedimento para resolver a equação de difusão para sistemas não-holônomos. Foi sugerido onde tais sistemas poderão ser encontrados na natureza ao nível microscópico.

1 - INTRODUCTION

In a previous paper (1) we have derived the Fokker-Planck equation for a system of particles subject to non-holonomic constraints. We have proved that the equation obtained is invariant under general point transformations and we derived from it the equation for the diffusion of particles.

Discussing the diffusion equation we were able to show that systems subject to constraints can be classified in two general classes: (i) the liouvillian systems which contain all holonomic as well as some non-holonomic systems whose major property is to exhibit a static equilibrium state and (ii) the non-liouvillian systems which are necessarily non-holonomic and exhibit in their equilibrium state permanent solenoidal currents. These currents are a direct manifestation of the structure of the non-holonomic constraints and it is independent of how the system was prepared except perhaps for the influence of the shape of the container on the current pattern. This stricking result for non-liouvillian systems was obtained by the intermediation of the diffusion equation.

In this paper we derived this same result by exhibiting the structure of the equilibrium solution of the Fokker-Planck equation thus avoiding the intermediate step of obtaining the diffusion equation. We have shown that while for liouvillian systems the equation obtained for the equilibrium density is exact, for non-liouvillian systems we could only obtain it approximately by expanding the density in powers of the square of the mean free path of the particles.

The classical result that gives the energy per particle

proportional to the number of degrees of freedom could only be proved if one includes besides the random motion of the particles also the energy associated to the permanent currents. In particular, this result says that the permanent currents are proportional to the temperature of the system.

Having therefore stabilished the diffusion equation by two independent methods we proceeded discussing the Green's formalism for obtaining its solutions with given boundary conditions on the surface of the container of the system. We were able to show that the equilibrium solution is unique in both liouvillian and non-liouvillian systems. However, the transient behaviour of these two kind of systems may be substantially different: while liouvillian systems behave as a normal fluid approaching its equilibrium monotonically, non-liouvillian systems may approach its equilibrium by intermediation of an oscillatory regimen.

Before steping into the formalism, we would like to ponder on the physical realization of such systems at the microscopic level. To fix our ideas we may imagine the particles under consideration to be electrons with the molecules being responsible for the non-holonomic structure of their constrained motion.

Such systems has not been observed so far. However the holonomic and non-holonomic molecular organization can be identified with certain mesomorphic phases of liquid crystals as we will show presently.

Let us first consider the smectic-A mesomorphic phase (2). In this case, the rod like molecules organize themselves in layers with their mean directions perpendicular to the surface

of the layers. If we identify this mean direction with the vector $\mathbf{a}(\vec{r})$, the form $\vec{a}.d\vec{r}$ is integrable, the foliation corresponding to the layers. These are examples of holonomic molecular organizations.

We now consider the cholesteric mesomorphic phase. Here, the organization of the rod like molecules are tangential to the plane layers and rotates when one moves from one layer to the other. Calling again $\vec{a}(\vec{r})$ the mean direction of the molecules, their organization is described by

$$a_{x} = \cos (q_{0}z + \phi)$$

$$a_{y} = \sin (q_{0}z + \phi)$$

$$a_{z} = 0$$

with the z-axis perpendicular to the layers. Writing

$$w = \overrightarrow{a} \cdot \overrightarrow{dr}$$

we have

$$w \ V \cdot q M = -d^0 \qquad .$$

This is an example of non-holonomic organization. As \vec{a} is parallel to curl \vec{a} , this system is also liouvillian.

Liquid crystals are layered molecular organizations and we do not believe that they can exhibit, as such, a non-liouvillian structure. Besides, the electrons in the molecules are free to move, as in the cholesteric mesomorphic phase, in the direction of $\vec{a}(\vec{r})$ and not perpendicular to $\vec{a}(\vec{r})$. Therefore, the field $\vec{a}(\vec{r})$ does not represent a constraint to the motion of the electrons in the sense that will be considered in this paper.

To observe the systems we have in mind one would have

to consider building blocks in the form of discs and not of rods as it is common with liquid crystals. Actually, only recently liquid crystals with disc like molecules has been observed (3). These disc like building blocks would have to articulate themselves in a twisted three-dimensional non-holonomic structure to produce a true non-liquid system.

We therefore believe that the realization of non-liouvillian system would come about in large molecular structures possibly of biological origin. We may even speculate that
the permanent currents we have predicted will exhibit a kind of
superconducting behaviour at room temperature and the magnetic
field created could be used by the molecules as a specificity
device for its functioning in the biological environment.

2 - THE FOKKER-PLANCK EQUATION

We will summarize in this section some of the results we have previously obtained $(\frac{1}{2})$. We assume that the particles move in a n-dimensional riemannian space with kinetic energy T given by

$$T = \frac{1}{2} g_{ij} \dot{q}^{i}\dot{q}^{j} \qquad (2.1)$$

We call this the free system. We add to it, first by a set of m independent scleronomic constraints

$$a_{i}^{\alpha}(q)dq^{i} = 0$$
 $\alpha = 1,...,m$. (2.2)

We observe that the vectors \mathbf{a}^{α} can always be chosen such that

$$a_{\alpha}^{i}a_{i}^{\alpha'} = \delta_{\alpha}^{\alpha'}$$
,

where

$$a_{\alpha}^{i} = g^{ij}a_{j}^{\alpha}$$
.

Secondly we add a viscous force - ξv^i with constant coefficient ξ of viscosity and a Langevin force $F_i(t)$ with constant strength i.e.,

$$= 0$$

 $= 2K g_{ij} \delta(t-t')$

where K is a constant.

Under these assumptions we may speak of the distribution of probability W(q,v;t) of particles in the phase space of the system. To mantain W(q,v;t) invariant under general point transformations of the configuration space we have introduced the measure weight $\mu(q,v)$ of probability given by

$$\mu(q,v) = g(q) \prod_{\alpha=1}^{m} \delta(a_{i}^{\alpha}v^{i})$$

with $g = det(g_{ij})$.

In particular, the normalization of W(q,v;t) is given by

$$1 = \int d^{n}q d^{n}v g(q) \prod_{\alpha=1}^{m} \delta(a_{i}^{\alpha}v^{i}) W(q,v;t) .$$

The equation that W(q,v;t) satisfies is a straight-forward generalization of the Fokker-Planck equation (4) and we have obtained (1)

$$\frac{\partial W}{\partial t} + v^{i} \left(\frac{\partial W}{\partial q^{i}} - \Gamma^{j}_{ik} \frac{\partial W}{\partial v^{j}} v^{k} \right) = \frac{\partial}{\partial v^{i}} \left(\xi v^{i}W + \Delta^{i}_{jk} v^{j}v^{k}W + KQ^{ij} \frac{\partial W}{\partial v^{j}} \right)$$
(2.3)

where (*)

$$\Gamma_{ik}^{j} = \frac{1}{2} g^{j\ell} \left[-\frac{\partial g_{\ell i}}{\partial q^{k}} + \frac{\partial g_{\ell k}}{\partial q^{i}} - \frac{\partial g_{ik}}{\partial q^{\ell}} \right] ,$$

$$\Delta_{jk}^{i} = \sum_{\alpha=1}^{m} a_{\alpha}^{i} a_{j,k}^{\alpha}$$
 (2.4)

and

$$Q^{ij} = g^{ij} - \sum_{\alpha=1}^{m} a_{\alpha}^{i} a_{\alpha}^{j} . \qquad (2.5)$$

We proved in reference $(\underline{1})$ that eq. (2.3) is invariant under the following transformation:

$$\overline{q}^{i} = \overline{q}^{i}(q)$$

$$\overline{v}^{i} = \frac{\partial \overline{q}^{i}}{\partial \alpha^{j}} v^{j} .$$

Our purpose in this paper is to exhibit a static solution W(q,v) of eq. (2.3).

3 - THE STRUCTURE OF THE STATIC SOLUTION

We assume that the static solution of eq. (2.3) has the form

^(*) We use the semi-colon to denote the covariant derivative associated to the affine conexion Γ^{j}_{ik} .

$$W = \exp(\psi) \tag{3.1}$$

where ψ is a real function of q and v. This hypothesis is sufficient to guarantee that W is a positive function.

We take for ψ the general form

$$\psi = A(q) + \sum_{v=1}^{\infty} \frac{\beta^{v/2}}{v!} A_{\ell_1, \dots, \ell_v} (q) v^{\ell_1} \dots v^{\ell_v}$$
 (3.2)

where β , the inverse of the temperature of the system, is introduced in eq. (3.2) to make $A_{\ell_1, \dots, \ell_{\nu}}$ dimensionless.

We will assume, without loss of generality for ψ , that $\mathbf{A}_{\ell_1,\dots,\ell_{\nu}}$ is symmetric in all its indices and satisfies the following equation:

$$a_{\alpha}^{1} A_{\ell_{1}, \dots, \ell_{\gamma}} = 0$$
 for $\alpha = 1, \dots, m$.

Under these restrictions one observes that ψ is independent of v if and only if $A_{\ell_1,\dots,\ell_N} = 0$.

Making use of eqs. (3.1) and (3.2) we arrive at the following results:

$$\left(\frac{\partial W}{\partial q^{i}} - \Gamma_{ik}^{j} \frac{\partial W}{\partial v^{j}} v^{k}\right) v^{i} = W \left(v^{i} \frac{\partial A}{\partial q^{i}} + \sum_{v=2}^{\infty} \frac{\beta^{(v-1)/2}}{(v-1)!} A_{l_{1}, \dots, l_{v-1}; l_{v}} v^{l_{1}, \dots, l_{v}}\right) \tag{3.3}$$

and

$$\frac{\partial}{\partial v^{i}} \left(\xi \ v^{i}W + \Delta^{i}_{jk} \ v^{j}v^{k}W \right) = W \left[(n-m)\xi + b_{i}v^{i} + \xi \sum_{\nu=1}^{\infty} \frac{\beta^{\nu/2}}{(\nu-1)!} \right]$$

$$A_{\ell_1,\ldots,\ell_{\nu}} v^{\ell_1} \ldots v^{\ell_{\nu}}] , \qquad (3.4)$$

where

$$b_i = \Delta_{ik}^k$$
.

We further have

$$Q^{ij} \frac{\partial^{2}W}{\partial v^{i}\partial v^{j}} = Q^{ij} \left(\frac{\partial \psi}{\partial v^{i}} \frac{\partial \psi}{\partial v^{j}} + \frac{\partial^{2}\psi}{\partial v^{i}\partial v^{j}} \right) W \tag{3.5}$$

$$Q^{ij} \frac{\partial^{2} \psi}{\partial v^{i} \partial v^{j}} = \sum_{\nu=1}^{\infty} \frac{\beta^{(\nu+2)/2}}{\nu!} A^{i}_{i\ell_{1}, \dots, \ell_{\nu}} v^{\ell_{1}, \dots v^{\ell_{\nu}}} + \beta A^{i}_{i}$$
 (3.6)

$$Q^{ij} \frac{\partial \psi}{\partial v^{i}} \frac{\partial \psi}{\partial v^{j}} = \beta A^{i} A_{i} + 2 \sum_{v=1}^{\infty} \frac{\beta^{(v+2)/2}}{v!} A^{i} A_{il_{1}, \dots, l_{v}} v^{l_{1}, \dots v^{l_{v}}} +$$

$$+ \sum_{\nu=2}^{\infty} \sum_{\nu'=1}^{\nu-1} \frac{\beta^{(\nu+2)/2}}{\nu'! (\nu-\nu')!} A_{\ell_{1}, \dots \ell_{\nu}}^{\ell_{\nu}} A_{\ell_{\nu'+1} \dots \ell_{\nu}}^{\ell_{\nu}} v^{\ell_{1} \dots v^{\ell_{\nu}}}.$$
(3.7)

Let us now observe that for any tensor $\mathbf{B}_{\ell_1 \dots \ell_{\mathcal{V}}}$ which satisfies

$$B_{\ell_1 \dots \ell_{\nu}} v^{\ell_1} \dots v^{\ell_{\nu}} = 0 \quad ,$$

we must have

$$PB_{\ell_1 \dots \ell_N} = 0$$

where P is the projector

$$P_{\ell_1 \dots \ell_{\nu}}^{\ell_1 \dots \ell_{\nu}} = \frac{1}{\nu!} \sum_{\text{perm}(\ell_1 \dots \ell_{\nu})} Q_{\ell_1}^{\ell_1} Q_{\ell_2}^{\ell_2} \dots Q_{\ell_{\nu}}^{\ell_{\nu}}$$

with the sum in the above expression running over all ν ! permutations of the set of indices $(\ell_1' \dots \ell_\nu')$.

Geometrically P extracts for B its symmetric part which is orthogonal to the subspace spanned by the \vec{a}_{α} vectors.

Substituing eqs. (3.3) to (3.7) into eq. (2.3) and identifying equal powers of v we obtain and infinite set of coupled equations for the tensors A_{ℓ_1,\ldots,ℓ_N} .

The term independent of v gives

$$(n-m)\xi + K\beta(A^{i}_{i} + A^{i}A_{i}) = 0$$
 (3.8)

Let us set

$$A^{i}_{j} = -Q^{i}_{j} + B^{i}_{j}$$

and

$$\xi = K\beta$$
 (3.9)

From eq. (3.8), we obtain

$$B_{i}^{i} + A_{i}^{i} = 0$$
 . (3.10)

The term linear in v gives:

$$A_{i} = \Lambda (b_{i} - Q^{j}_{i} \frac{\partial A}{\partial \alpha^{j}}) + 2B_{ij}A^{j} + A^{j}_{ji}$$
 (3.11)

where

$$\Lambda = \frac{1}{\xi\sqrt{8}} \tag{3.12}$$

is the mean free path of the particles.

We also have

$$B_{\ell_1 \ell_2} = - \Lambda P A_{\ell_1; \ell_2} + A^{j} A_{j \ell_1 \ell_2} + B_{\ell_1}^{j} B_{j \ell_2} + \frac{1}{2} A_{j \ell_1 \ell_2}^{j}$$
 (3.13)

and in general we obtain (for $v \ge 3$):

$$^{\Lambda P A} _{\ell_{1} \dots \ell_{v-1}; \ell_{v}} = - ^{\Lambda} _{\ell_{1} \dots \ell_{v}} + \frac{1}{v} A^{j} _{j \ell_{1} \dots \ell_{v}} + \frac{2}{v} (B^{j} _{\ell_{1}} A_{j \ell_{2} \dots \ell_{v}} +$$

+ cyclic terms)+
$$\sum_{v'=2}^{v-2} \frac{(v-1)!}{v'!!(v-v')!} P \begin{bmatrix} A_{\ell_1}^{j} \dots \ell_{v}, A_{j\ell_{v'+1}} \dots \ell_{v} \end{bmatrix}$$
(3.14)

We may look for solutions of eqs. (3.11), (3.13) and (3.14) as power expansions in Λ . By an iterative procedure we can show that if such solutions exist they have the following structure

$$A_{\ell_{1}...\ell_{v}} = \Lambda^{v} \sum_{\alpha=0}^{\infty} \Lambda^{2\alpha} A_{\ell_{1}...\ell_{v}}^{\alpha} , \quad v \neq 2$$

$$B_{ij} = \Lambda^{2} \sum_{\alpha=0}^{\infty} \Lambda^{2\alpha} B_{ij}^{\alpha} .$$

$$(3.15)$$

In particular we have

$$A_{i}^{0} = b_{i} - \frac{\partial A}{\partial q^{j}} Q_{i}^{j}$$
 (3.16)

$$B_{ij}^{0} = \frac{1}{2} (b_{k} - \frac{\partial A}{\partial q^{\ell}} Q_{k}^{\ell});_{m} (Q_{i}^{k} Q_{j}^{m} + Q_{j}^{k} Q_{i}^{m}) \qquad (3.17)$$

Let us now observe that if

$$A_{i}^{0} = 0$$
 , (3.18)

then every

$$A_{\ell_1 \cdots \ell_{\nu}} = 0 \qquad \qquad \nu \neq 2$$

and

$$B_{ij} = 0$$
.

Thus W(q,v) takes the simple form

$$W(q,v) = \exp(A - \frac{\beta}{2} Q_{ij} v^{i} v^{j})$$
 (3.19)

Eq. (3.18) defines the Liouvillian systems and W(q,v) given by eq. (3.19) is the equilibrium solution for such systems. This is an exact solution.

In the case where it is impossible to find A such that eq. (3.18) is fulfilled, the structure of W(q,v) is more complicated and we have to resort to the Λ^2 power expansion.

4 - THE Λ^2 APPROXIMATION

We will now discuss the approximation for W in which one includes only terms up to Λ^2 . Therefore we have

$$A_{i} = \Lambda A_{i}^{0} = \Lambda (b_{i} - \frac{\partial A}{\partial \sigma^{j}} Q^{j}_{i}) + O (\Lambda^{3})$$
 (4.1)

$$B_{ij} = \Lambda^{2} B_{ij}^{0} = \frac{1}{2} \Lambda^{2} (Q_{i}^{k} Q_{j}^{m} + Q_{j}^{k} Q_{i}^{m}) (b_{k} - \frac{\partial A}{\partial q^{k}} Q_{k}^{k})_{;m} + O(\Lambda^{4})$$
(4.2)

and all other tensors are of order equal to or larger than Λ^3 .

The solution W(q,v) of the Fokker-Planck equation takes

then the form of a gaussian in its dependence on v:

$$W(q,v) = \exp \left(A + \frac{1}{2} A_{i} A^{i} - \frac{\beta}{2} (Q_{ij} - B_{ij}) (v^{j} - \frac{A^{j}}{\sqrt{\beta}}) (v^{i} - \frac{A^{i}}{\sqrt{\beta}}) \right).$$

Let us calculate ρ , j^{i} and P^{ij} . We have

$$\rho(q) = \int d^{n}v \sqrt{g} \sum_{\alpha=1}^{m} \delta(a_{i}^{\alpha}v^{i})W(q,v) = \frac{\text{const}}{(1-B_{i}^{i})^{1/2}} \exp(A + \frac{1}{2}A_{i}A^{i})$$

which, due to eq. (3.10) gives, preserving only terms up to Λ^2 :

$$\rho(q) = const exp(A)$$

from where we conclude that

$$A = \log \rho(q) + const . \qquad (4.3)$$

Similarly we have

$$j^{i} = \begin{cases} v^{i} \sqrt{g} & \prod_{\alpha=1}^{m} \delta(a^{\alpha}_{i}v^{i}) W d^{n}v = \frac{A^{i}}{\sqrt{\beta}} \rho & . \end{cases} (4.4)$$

Making use of eqs. (4.1) and (4.3) we arrive at

$$j^{i} = D \left(b^{i}\rho - Q^{ij} \frac{\partial \rho}{\partial q^{j}}\right) \tag{4.5}$$

where $D = \Lambda/\sqrt{\beta}$ is the diffusion coefficient of the system. One observes therefore that in the equilibrium state, j^i is in general not zero^(*).

We also have

This is the same current obtained elsewhere (1).

$$P^{ij} = \int v^{i}v^{j} \sqrt{g} \prod_{\alpha=1}^{m} \delta(a_{i}^{\alpha}v^{i}) W d^{n}v$$

thus

$$P^{ij} = -\frac{1}{\beta} A^{i}A^{j}\rho + \int (v^{i} - \frac{A^{i}}{\sqrt{\beta}}) (v^{j} - \frac{A^{j}}{\sqrt{\beta}}) \sqrt{g} \prod_{\alpha=1}^{m} \delta(a^{\alpha}_{i}v^{i}) W d^{n}v =$$

$$= \frac{1}{\beta} A^{i}A^{j}\rho + \frac{1}{\beta} (Q^{ij} + B^{ij})\rho \qquad (4.6)$$

It is interesting to observe that the first term of the second member of the above equation comes from the local collective motion of the particles given by j^{i} while the second term is the contribution for the random motion of the particles with respect to the local current.

The local density of energy is given by $\frac{1}{2}$ P $_{\dot{1}}^{\dot{1}}$ and, making use of eq. (3.10), we obtain

$$\frac{1}{2} P^{i}_{i} = \frac{(n-m)\rho}{2\beta} ,$$

therefore stablishing the general result of kinetic theory of gases which states that the average energy by particle is $\frac{1}{2\beta}$ times the number of degrees of freedom (n-m).

One should emphasize that this result is correct in the case of non-Liouvillian systems because we have taken into account also the energy associated with the collective motion described by the local currents, coming from the first term of the left hand side of eq. (4.6).

We still have to examen eq. (3.10) within the Λ^2 approximation. This is an equation for A. Substituting eq.(4.3) into eqs. (4.1) and (4.2) and these latter into eq. (3.10) we obtain:

$$\frac{1}{\rho^2} \left(\rho b_{\dot{\mathbf{i}}} - Q_{\dot{\mathbf{i}}}^{\dot{\mathbf{j}}} \frac{\partial \rho}{\partial q^{\dot{\mathbf{j}}}} \right) \left(\rho b^{\dot{\mathbf{i}}} - Q^{\dot{\mathbf{i}}k} \frac{\partial \rho}{\partial q^{\dot{k}}} \right) - \frac{1}{\rho} \left(\rho b_{\dot{\mathbf{i}}} - Q^{\dot{\mathbf{j}}} \frac{\partial \rho}{\partial q^{\dot{\mathbf{j}}}} \right)_{\dot{\mathbf{j}}k} Q^{\dot{\mathbf{i}}k} = 0 .$$

After some tedious calculations we finally arrive at

$$(\rho b^{k} - Q^{jk} \frac{\partial \rho}{\partial q^{j}})_{;k} = 0 \qquad (4.7)$$

which is the same equation for the equilibrium density for the diffusion of particles, in the Λ^2 approximation, obtained previously (eq. (5.5) of reference (1)). One should observe that this equation is nothing else that the expression of the conservation of the current.

5 - THE LIOUVILLIAN CASE

We have now come to the point where we should discuss the solutions of eq. (4.7). To simplify the discussion we will consider only the case of a single non-holonomic constraint (*). We further assume in this section that the constraint is liouvillian, i.e., there exists a function ψ such that

$$b^{i} \equiv a^{j}a^{i}; j = Q^{ij} \frac{\partial \psi}{\partial q^{j}} . \qquad (5.1)$$

We set

$$\rho = \overline{\rho} \exp \psi$$

and eq. (4.7) takes the form

$$\frac{\partial}{\partial q^{i}} \left(Q^{ij} \sqrt{g} \exp \psi \frac{\partial \overline{\rho}}{\partial q^{j}} \right) = 0 . \qquad (5.2)$$

Let us consider the operator H defined by

^(*) The holonomic case has been discussed in (1) and (5).

$$Hf \equiv -\frac{1}{\mu} \frac{\partial}{\partial q^{i}} (Q^{ij} \mu \frac{\partial f}{\partial q^{j}})$$
 (5.3)

with

$$\mu = \sqrt{g} \exp \psi$$
.

We will be looking for solutions of the diffusion equation in a volume Ω bound by a surface Σ . With this in mind, we define the inner product of two functions f_1 and f_2 as

$$(f_1, f_2) = \int_{\Omega} f_1^* f_2 \mu d^n q$$
 (5.4)

and we take for the space on which H operates the space of all normalizable function with norm given by the inner product defined above.

We further restrict the functions f to those that the derivative at the boundary satisfies the equation (*):

$$Q^{ij} \frac{\partial f}{\partial q^{j}} d\sigma_{i} = 0$$
 (5.5)

where $d\sigma_{i}$ is an element of surface at the boundary.

As the current is given by:

$$j^{i} = Q^{ij} \frac{\partial \rho}{\partial q^{j}} - b^{i} \rho = Q^{ij} \frac{\partial \rho}{\partial q^{j}} e^{\psi}$$
,

the boundary condition given by eq. (5.5) is equivalent to assume

The presence of Q^{ij} in eq. (5.5) playing the role of a singular metric could make irrelevant this boundary condition of f. This is impossible for non-holonomic constraints in the neighborhood of Σ unless Σ is an isolated integral of the constraint. In this case Σ is a natural boundary to the motion of the particles. Such an example is considered in section 8. In such singular case we may take $\partial_{ij}f \, d\sigma^{j} = 0$ to make the solution unique.

that no particle flows in or out of the volume Ω bound by Σ . This guarantees the conservation of the number of particles inside $\Sigma^{(\star)}$.

. Under these assumptions one can easily prove that H is hermitian. Besides, if \boldsymbol{f}_α is an eigenfunction of H:

$$Hf_{\alpha} = \alpha f_{\alpha}$$
,

we have:

$$\alpha(f_{\alpha}, f_{\alpha}) = \begin{cases} \partial_{i} f_{\alpha} Q^{ij} \partial_{j} f_{\alpha} \mu d^{n}q \geq 0 \end{cases}$$

what shows that the spectra of H is non-negative (we can always assume that f_{α} are real functions).

The equilibrium distribution is given by the eigenfunction \mathbf{f}_0 and we have:

$$\int \partial_{i} f_{0} Q^{ij} \partial_{j} f_{0} \mu d^{n}q = 0$$

what gives

$$Q^{ij} \partial_{j} f_{0} = 0$$
 (5.6)

As

for non-holonomic constraint the unique solution of eq. (3.6) is

$$f_0 = constant$$
.

This shows that the equilibrium state of the liouvillian systems is unique and we have

$$\rho = \text{const.} \exp(\psi(q))$$
.

We will consider now the time dependent diffusion equation obtained in (1), which can be put into the following form:

$$\frac{\partial \overline{\rho}}{\partial t} = - D H \overline{\rho}$$

^(*) This boundary condition is sufficient but not necessary to guarantee the conservation of the number of particles in the volume Ω . See the example in section 6 of this paper.

The equation

$$(\frac{\partial G}{\partial t} + DHG) = \delta(t-t_0) \delta^n(q-q_0)$$

has the solution

$$G = \sum_{\alpha} e^{-D\alpha(t-t_0)} f_{\alpha}(q) f_{\alpha}(q_0) \qquad \text{for } t \ge t_0$$

$$G = 0 \qquad \qquad \text{for } t < t_0$$

where \boldsymbol{f}_{α} are the orthonormalized eigenfunctions of H and obey

$$\sum_{\alpha} f_{\alpha}(q) f_{\alpha}(q_{0}) = \delta^{n}(q-q_{0}) .$$

The general solution for $\overline{\rho}(q;t)$ is

$$\overline{\rho}(q,t) = \frac{1}{\overline{V}} + \sum_{\alpha>0} e^{-D\alpha(t-t_0)} f_{\alpha}(q) \left(f_{\alpha}(q_0), \rho(t_0)\right) ,$$

with $\rho(t_0)$ the density distribution of the system at the instant t_0 and

$$V = \int_{\Omega} \mu \, d^n q .$$

One therefore observes that the modes included in the initial distribution $\rho(t_0)$ damps out each one with its characteristic relaxation time given by

$$t_{\alpha} = \frac{1}{D\alpha}$$
.

6 - AN EXAMPLE

We now consider the case of particles of unit masses moving in the three dimensional euclidean space subject to the constraint given by the following form:

$$xdy + x_0 dz = 0 (6.1)$$

where \mathbf{x}_0 is a constant length that fixes the scale of the system. This is a non-holonomic constraint for which

$$b_{i} \equiv a^{j} \frac{\partial a_{i}}{\partial q^{j}} = 0$$

and therefore liouvillian.

The diffusion equation takes the form.

$$\frac{1}{D} \frac{\partial \rho}{\partial t} = \frac{\partial^2 \rho}{\partial x^2} + \frac{1}{x_0^2 + x^2} \left\{ x_0^2 \frac{\partial^2 \rho}{\partial y^2} - 2x x_0 \frac{\partial^2 \rho}{\partial y \partial z} + x^2 \frac{\partial^2 \rho}{\partial z^2} \right\} . \quad (6.2)$$

One observes that the equation is invariant under translations in the y and z directions. We therefore set periodical boundary conditions in these directions in a retangular box of faces perpendicular to the coordinate axis.

We write

$$\psi_{\alpha} = \phi_{\alpha}(x) e^{ik_{2}(y-y_{1})} e^{ik_{3}(z-z_{1})}$$
(6.3)

and we set

$$k_2(y_2-y_1) = 2 n_2 \pi$$

$$k_3(z_2-z_1) = 2 n_3 \pi$$
(6.4)

where

$$x = x_1$$
; $x = x_2$
 $y = y_1$; $y = y_2$
 $z = z_1$; $z = z_2$

are the equations for the faces of the box. We impose ϕ_{α} to be an eigenfunction of

$$H = -\left[-\frac{\partial^2}{\partial x^2} + \frac{1}{x_0^2 + x^2} \left(x_0 \frac{\partial}{\partial y} - x \frac{\partial}{\partial z} \right)^2 \right]$$
 (6.5)

and we have

$$-\frac{\partial^2 \phi_{\alpha}}{\partial x^2} + V (k_2, k_3, x) \phi_{\alpha} = \alpha \phi_{\alpha}$$
 (6.6)

where

$$V(k_2, k_3, x) = \frac{(x_0 k_2 - x k_3)^2}{x_0^2 + x^2} .$$
 (6.7)

For $\phi_{\alpha}(x)$ we impose the boundary conditions

$$\frac{\partial \phi_{\alpha}}{\partial \mathbf{x}} \bigg|_{\mathbf{x} = \mathbf{x}_{1}} = \frac{\partial \phi_{\alpha}}{\partial \mathbf{x}} \bigg|_{\mathbf{x} = \mathbf{x}_{2}} = 0 \qquad (6.8)$$

With the above boundary conditions for each k_2 and k_3 , α takes discrete values which we enumerate from zero starting from the lowest eigenvalue. Thus we write $\psi_{n_1,n_2,n_3}(x,y,z)$ to the eigenfunctions of H given by eq. (6.8).

The Green's function for H can be written as

$$G(\vec{r},t;\vec{r}',t') = \sum_{n_1 n_2 n_3} \psi_{n_1 n_2 n_3}(x,y,z) \psi_{n_1 n_2 n_3}^{\star}(x',y',z') e^{-\alpha(n_1,n_2,n_3)(t-t')}$$

for
$$t \ge t'$$
 (6.9)

and

$$G(\vec{r},t;\vec{r}',t') = 0$$
 for $t < t'$.

From the fact that

$$\psi_{n_1,-n_2,-n_3}(x,y,z) = \psi_{n_1,n_2,n_3}^*(x,y,z)$$

and that the sum in eq. (6.9) runs over all integers n_2 and n_3 , we conclude that G given by eq. (6.9) is real.

The time dependent solution is

$$\rho(\vec{r};t) = \int G(\vec{r},t;\vec{r}',t') \rho(\vec{r}';t') d^{3}\vec{r}' .$$

Therefore, with the above equation we can calculate ρ from the knowledge of $\ \rho$ at an earlier time.

We will now compare the behaviour of the system when the box which contains the particles is situated in different regions of the space. Translations in the y and z-directions do not affect the system as the diffusion equation is invariant with respect to these dislocations. We will therefore compare only two systems, one positioned at the origin and another shifted in the x-direction.

We assume, for simplification that

$$|x_1-x_2| = |y_1-y_2| = |z_1-z_2| = 2x_0$$
.

Let us estimate the smallest relaxation time for the system. From eq. (6.6) we obtain:

$$\alpha = \left\{ \int_{x_1}^{x_2} \phi_{\alpha}^{2} dx + \int_{x_1}^{x_2} V \phi_{\alpha}^{2} dx \right\} ,$$

assuming that

$$\int_{x_1}^{x_2} \phi_{\alpha}^2 dx = 1 .$$

To estimate the lowest α we take $\phi_{\alpha}^{2} = \frac{1}{2x_{0}}$ then we

have:

$$\alpha \simeq \frac{1}{2x_0} \int_{x_1}^{x_1+2x_0} V(k_2, k_3, x) dx$$
.

From where we obtain:

$$\alpha = k_3^2 + \frac{(k_2^2 - k_3^2)}{2} \left\{ \tan^{-1}(\lambda_1 + 2) - \tan^{-1}\lambda_1 \right\} - \frac{k_2 k_3}{2} \log \left(\frac{1 + (\lambda_1 + 2)^2}{1 + \lambda_1^2} \right)$$

where

$$\lambda_1 = \frac{x_1}{x_0} .$$

For the box at the origin we have λ_1 = -1 and

$$\alpha = \frac{\pi}{4} k_2^2 + (1 - \frac{\pi}{4}) k_3^2$$
.

The lowest value is for $k_2=0$ and $k_3=\frac{\pi}{x_0}$ and we finally set

$$\tau_0 = \frac{4 x_0^2}{(4-\pi)}$$

for the lowest relaxation time for the box at the origin. In this box the system has a slightly faster tendency to be homogeneous in the y-direction than the z-direction as the constraint in this region of space predominantly inhibits motion in the z-direction.

For the box away from the plane x = 0, we have

$$\lambda_1 >> 1$$
 .

We immediatly observes that the lowest mode is associated with $k_3=0$ and we get, for $k_2=\frac{\pi}{x_0}$

$$\alpha \simeq \frac{\pi^2}{x_0^2} \frac{1}{1 + (\lambda_1 + 2)^2}$$

or

$$\tau_0 = \frac{x_0^2 - 1 + (\lambda_1 + 2)^2}{D_{\pi}^2}.$$

Here, the inhomogeneity in the y-direction has a tendency to persist for a long time as compared with the previous case. The reason is again the constraint, as, in this region of space, it predominantly inhibits the motion in the y-direction.

This strong dependence of the relaxation time of the system with respect to where we set the box signs to us that one should be careful with taking the thermodynamic limit in the case of non-holonomy. In general we have no uniformity of behaviour of the system in different regions of space and the relaxation of the system may come to be forbiddingly high to guarantee uniformity of the thermodynamic limit.

7 - THE NON-LIOUVILLIAN CASE

We will now discuss eq. (4.7) when the constraint is non-liouvillian. We set

$$b^{i} = Q^{ij} \frac{\partial X}{\partial q^{j}} + C^{i}$$
 (7.1)

and we assume that

$$C^{i}_{i} = 0$$
 . (7.2)

Thus, the equation for X takes the form

$$\frac{1}{\sqrt{g}} \frac{\partial}{\partial q^{i}} \left[\sqrt{g} \ Q^{ij} \frac{\partial \chi}{\partial q^{j}} \right] = S(q)$$
 (7.3)

where

$$S(q) = \frac{1}{\sqrt{q}} \frac{\partial}{\partial q^{i}} (\sqrt{g} b^{i}) . \qquad (7.4)$$

Let us define the Green's function by

$$\frac{1}{\sqrt{g}} \frac{\partial}{\partial q^{i}} \left(\sqrt{g} Q^{ij} G(q,q') \right) = \delta^{n}(q-q')$$
 (7.5)

with the following boundary condition over the surface Σ enclosing the fluid (*)

$$Q^{ij} \frac{\partial G(q,q')}{\partial q^{j}} d\sigma_{i} = 0$$
.

For the function χ we assume

$$Q^{ij} \frac{\partial \chi}{\partial q^{j}} d\sigma_{i} = b^{i} d\sigma_{i}$$
 (7.6)

as its boundary condition. In this way we are taking $C^{\mathbf{i}}(q)$ tangent to the surface Σ . Under these assumptions we obtain

$$\chi(q) = \int_{\Omega} G(q,q')S(q) \sqrt{g} d^{n}q' + \int_{\Sigma} G(q,q') \sqrt{g} b^{i}(q')d\sigma_{i} . (7.7)$$

Let us write

$$\rho = \exp \psi(q)$$

^(*) See footnote on page 15.

and

$$\overline{X} = \psi - X$$
.

Thus, eq. (4.7) takes the form

$$\frac{1}{\sqrt{g}} \frac{\partial}{\partial q^{i}} \left(\sqrt{g} \ Q^{ij} \ \overline{X} \right) = \frac{\partial X}{\partial q^{i}} C^{i} + \overline{S} \ \overline{X} \ \overline{X} \ (7.8)$$

where

$$\overline{S} = \frac{\partial \overline{X}}{\partial q^{i}} \left(C^{i} + Q^{ij} \frac{\partial \overline{X}}{\partial q^{j}} \right) - \frac{\partial X}{\partial q^{i}} Q^{ij} \frac{\partial \overline{X}}{\partial q^{j}} . \quad (7.9)$$

We take for $\overline{\chi}$ the same boundary condition as that taken for G(q,q'), i.e.,

$$Q^{ij} \frac{\partial \overline{X}}{\partial q^{j}} d\sigma_{i} = 0 .$$

Therefore we have for $\overline{\chi}(q)$:

$$\overline{\chi}(q) = \overline{\chi}_0(q) + \int G(q,q') \overline{S}[\chi(q')] \sqrt{g} d^n q'$$
 (7.10)

where

$$\overline{X}_{0}(q) = \int G(q,q') \frac{\partial X(q')}{\partial q'^{j}} C^{j}(q') \sqrt{g} d^{n}q' \qquad (7.11)$$

Eq. (7.10) can be solved by the usual iterative method.

The equilibrium solution is thus given by

$$\rho_0 = \text{const.exp}(\overline{X} + X) \qquad . \tag{7.12}$$

Let us observe that, from the discussion of section 5,

the Green function G(q,q') is uniquely defined apart from a constant. So it is also $\chi(q)$. The function $\overline{\chi}$ is also uniquely defined by the iterative method applied to the eq. (7.10) and thus ρ_0 , given by eq. (7.12), comes to be known apart from a multiplicative constant.

. We now turn our attention to the time dependent solutions of the diffusion equation in the case of non-liouvillian constraints:

$$\frac{\partial \rho}{\partial t} = \frac{D}{\sqrt{g}} \frac{\partial}{\partial q^{i}} \left(\sqrt{g} \left(Q^{ij} \frac{\partial \rho}{\partial q^{j}} - b^{i} \rho \right) \right) \qquad (7.13)$$

We write

$$\rho(q,t) = \overline{\rho}(q,t) \rho_0(q)$$

$$\mu(q) = \rho_0(q) \sqrt{g}$$

$$\rho_0 = e^{\psi}$$

$$\gamma^{i} = Q^{ij} \frac{\partial \psi}{\partial q^{j}} - b^{i}$$

and

With these definitions we may rewrite eq. (7.13) as

$$\frac{\partial \overline{\rho}}{\partial t} = D \left[\frac{1}{\mu} \frac{\partial}{\partial q^{j}} (\mu Q^{ij} \frac{\partial \overline{\rho}}{\partial q^{j}}) + \gamma^{i} \frac{\partial \overline{\rho}}{\partial q^{i}} \right] . \quad (7.14)$$

We observe that

$$\frac{\partial}{\partial q^{i}} (\nu \gamma^{i}) = 0$$

it is another form of saying that $\boldsymbol{\epsilon}_0$ is the equilibrium solution.

The boundary condition for $\rho(q,t)$ is obtained by imposing that no current flows through the surface Σ of the container and we must have

$$(Q^{ij} \frac{\partial \rho}{\partial q^{j}} - b^{i} \rho) d\sigma_{i} = 0$$

or, equivalently

$$Q^{ij} \frac{\partial \overline{\rho}}{\partial q^{j}} d\sigma_{i} = 0 . \qquad (7.15)$$

Let us now consider the vector space of the functions defined in the volume Ω with normal derivative at the boundary Σ satisfying eq. (7.15). In such a space we define the operator

$$H = H_0 + H_1$$

with

$$H_0 f \equiv -\frac{1}{\mu} \frac{\partial}{\partial q^{i}} (\mu Q^{ij} \frac{\partial f}{\partial q^{j}})$$
 (7.16)

and

$$H_1 f = -\gamma^{i} \frac{\partial f}{\partial q^{i}} \qquad (7.16a)$$

We observe that ${\rm H}_0$ and ${\rm H}_1$ are hermitean and antihermitean operators respectively.

To construct the Green's function for H we will consider the bi-orthogonal basis generated by H and its adjoint H⁺.

Let us call \boldsymbol{f}_{α} the eigenfunction of H corresponding to the eigenvalue $\alpha.$ We have

$$Hf_{\alpha} = af_{\alpha}$$
.

In general α will be a complex number. In this case $f_{\alpha}^{\star} \text{ is the eigenfunction corresponding to the eigenvalue } \alpha^{\star} \text{ and}$ we have

$$f_{\alpha}^* = f_{\alpha^*}$$
.

Because of that, the spectrum of H is the same as the spectrum of H and to every f_{α} there corresponds a f_{α}^{+} such that $^{(*)}$

$$H^+f^+_{\alpha} = \alpha f^+_{\alpha}$$
.

We further have

$$\int f_{\alpha}^{+} f_{\alpha}, \quad \mu \ d^{n} q = 0 \qquad \text{if} \quad \alpha \neq \alpha'$$

and we normalize these functions by the condition

$$\int f_{\alpha}^{+} f_{\alpha} \mu d^{n} q = 1 .$$

The Green's function satisfying the following equation

$$\left(\frac{\partial}{\partial t} + DH\right)G(q,q';t-t') = \delta^{n}(q-q')\delta(t-t')$$

is

$$G = \sum_{\alpha} e^{-D\alpha(t-t')} f_{\alpha}(q) f_{\alpha}^{+}(q') \quad \text{for} \quad t \ge t'$$

$$G = 0 \quad \text{for} \quad t < t' \quad .$$

It is a simple matter to show, from the fact that complex eigenvalues always occurs in conjugate pairs that G(q,q';t-t'), defined by eq. (7.17), is a real, non-symmetric function with res-

^(*) See, for example, P.M. Morse and H. Feshbach, Methods of Theoretical Physics, Vol. 1, MacGraw-Hill Book (N.York) 1953.

pect to exchange of q by q'.

The time dependent solution $\rho(q;t)$ is

$$\rho(q;t) = \rho_0(q) \int G(q,q';t) \rho(q';0) \rho_0(q') \sqrt{g} d^n q .$$

We should observe that the non-hermitian character of the diffusion operator H may lead to unexpected behaviour of the system. If the imaginary parts of some eigenvalues of H are larger than their corresponding real parts, the system, exciting these modes, comes to equilibrium through an oscillatory behaviour, unusual in the transient behaviour for diffusion.

8 - AN EXAMPLE

To illustrate the formalism we consider a simple example of non-liouvillian systems. Let us consider the three-dimensional euclidean space and let us introduce toroidal coordinate (r,ϕ,θ) by the following transformation

$$x = (a + r sin\phi) cos\theta$$

$$y = (a + r sin\phi) sin\theta$$

$$z = r cos\phi$$
(8.1)

We take for the surface of the container, two tori defined by $\mathbf{r}=\mathbf{r}_1$ and $\mathbf{r}=\mathbf{r}_0$ and we will assume

$$a > r_0 > r_1$$
.

We will set D, the diffusion coefficient, equal to unit.

For the constraint we take the form:

$$\omega = adr + \Delta \left[rd\phi + (a + rsin\phi) d\theta \right]$$
 (8.2)

where

$$\Delta = \frac{(r-r_1)(r-r_0)}{(r_0-r_1)^2} . \tag{8.3}$$

The choice of Δ given by the previous equation makes the constraint self-confining in the sense that the surfaces $r=r_0$ and $r=r_1$ are natural boundaries for particles moving between these two tori as the field a_i is everywhere normal to these two surfaces. To see this better let us first introduce the metric in the toroidal coordinates. We observe that

$$dx^{2} + dy^{2} + dz^{2} = dr^{2} + r^{2}d\phi^{2} + (a + r\sin\phi)^{2} d\theta^{2}$$
,

and we therefore set

$$(g_{ij}) = \begin{cases} 1 & 0 & 0 \\ 0 & r^2 & 0 \\ 0 & 0 & (a+r\sin\phi)^2 \end{cases}$$

where the indices (1,2,3) corresponds to the $(dr,d\phi,d\theta)$ directions respectively. We also have

$$(a_i) = \Lambda \left[a, \Delta r, \Delta (a + r \sin \phi)\right]$$

and

$$a^{i}a_{i} = 1 = \Lambda^{2} (a^{2} + 2\Delta^{2})$$

from where we obtain

$$L = \frac{1}{\sqrt{a^2 + 2^2}}$$
.

At the surface of the container, where $\Delta = 0$, we have

$$(a_i) = (1,0,0).$$

To calculate (b_i) we use the formula

$$b_{i} = a^{j} \left(\frac{\partial a_{i}}{\partial q^{j}} - \frac{\partial a_{j}}{\partial q^{i}} \right)$$

which avoids calculating the affine conexion. On the surface of the container, we obtained:

$$(b_{i}) = \begin{cases} \frac{1}{a(r_{0}-r_{1})} & (0,r_{0},a+r_{0}\sin\phi) & \text{for } r = r_{0} \\ \frac{1}{a(r_{0}-r_{1})} & (0,-r_{1},-(a+r_{1}\sin\phi)) & \text{for } r = r_{1} \end{cases}$$

As (b $_{\mbox{\scriptsize i}})$ is tangent to the surface of the container, ψ satisfies the boundary condition

$$\frac{\partial \psi}{\partial \rho} = 0$$
 for $r = r_0$ and $r = r_1$.

If one would calculate the divergence of (b_i) in the bulk of the fluid one would find it to be different from zero, what would say that ψ is not constant over the volume of the system. We cannot calculate the divergence of ψ in the d¢ and directions on the surface unless we solve its equation explicitly. To get an idea of the solenoidal currents on the surface

of the container, we observe that Q^{ij} is the identity operator in the tangent plane of these surfaces and we have

$$\gamma_{\phi} = -\frac{1}{r_0 - r_1} + \frac{\partial \psi}{\partial \phi}$$
 for $r = r_0$

and

$$\gamma_{\theta} = -\frac{(a+r_0\sin\phi)}{a(r_0-r_1)} + \frac{\partial\psi}{\partial\theta}$$
 for $r = r_0$.

Because (a_i) does not depend on θ we may assume that ψ is also independent of θ and

$$\gamma_{\theta} = -\frac{(a+r_0 \sin \phi)}{a(r_0-r_1)} \qquad \text{for} \quad r = r_0$$

what shows that there exists, in this example, a permanent sole-noidal current in the opposite directions of $d\theta$, everywhere on the outer surface of the container. On the inner surface, this current is in the positive direction of $d\theta$. We also have a current in the negative $d\varphi$ direction on the outer surface whose circulation is given by

$$\oint \gamma_{\phi} d\phi = -\frac{2\pi}{r_0 - r_1} .$$

Such an example should be easily simulated on computers and the solenoidal currents observed.

9 - CONCLUSIONS

We have stabilished by two different approaches the diffusion equation for non-holonomic systems. We have also

specified the procedures for solving it for both liouvillian and non-liouvillian systems and discussed the equilibrium and transient states of such systems. With these results we believe that, unless microscopic physical systems with non-holonomic constraints are found in nature, further development of the theory here developed is pointless. We have even suggested in the introduction, where we should look for such systems in nature. However, two aspects of the theory seen to us worth while pursuing its development. One is the probability of classifying the constraints, let us say in three dimensional space, by applying group theoretical considerations. We have in mind a development somewhat similar to the applications of homotopy theory to crystal defects (6). Though we believe that the situation here is complicated by the lack of translational invariance of the non--holonomic structures. The other direction is the large Λ^2 limit which cannot be reached by the method here presented.

10 - Acknowledgements

We would like to thank Dr. M. Abud for many stimulating discussions.

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