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ON SPINOR SPACE REPRESENTATION OF LORENTZ GROUP

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ABSTRACT

The spinor space representation of Homogeneous Lorentz group offered by Clifford numbers in Minkowski space is reviewed. Two spinor calculus naturally follows when spinor matrix representation for these numbers is used. Representations of the improper four group are also discussed.

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1. INTRODUCTION.

The purpose of the present article is to discuss the four component and two component spinor analysis, starting from the representation of Lorentz group in terms of Clifford numbers. The results are not new¹, however, a good deal of clarity in discussion is achieved. With the extensive use of spinors in Riemannian space² this is perhaps desirable.

In sections 2 and 3 we review the four spinor representation of the restricted homogeneous Lorentz group offered by Clifford algebra in Minkowski space. Section 4 is devoted to 2-spinor calculus which naturally follows when we express the matrices γ^μ in the spinor representation and the $SL(2, C)$ group structure is made transparent. In section 5 we discuss how a spin frame in two dimensional spinor space can be defined in terms two legs like the four-legs or tetrads of vectors frequently used in Minkowski space. A set of null tetrad of vectors $\sigma^{\mu(A)(\dot{B})}$ is also constructed. Finally, in sections 5 and 6 we discuss in detail the representations of the improper Four group in spinor space together with the transformations of bilinear invariants.

2. NOTATION. REPRESENTATION OF LORENTZ GROUP BY CLIFFORD NUMBERS. SPINOR SPACE.

Homogeneous Lorentz group (H. L. G.) may be defined as the group of 4x4 real matrices $\{\Lambda\}$ which satisfy

$$\Lambda^T G \Lambda = G \quad (1)$$

where³ $\Lambda = (\Lambda^\mu{}_\nu)$, $G = (g_{\mu\nu}) = (g_{\nu\mu})$, $(\Lambda^T)^\mu{}_\nu = \Lambda^\nu{}_\mu$ with $\mu, \nu = 0, 1, 2, 3$

and $g_{00} = 1$, $g_{kk} = -1$, $k = 1, 2, 3$, $g_{\mu\nu} = 0$ for $\mu \neq \nu$. We will be mostly concerned⁴ here with restricted H.L.G. - indicated simply as Lorentz group, for which

$$\Lambda^0_0 > 1 \quad \text{and} \quad \det \Lambda = +1 \quad (2)$$

The equation (2.1) written explicitly reads

$$(\Lambda^T)^\mu_\alpha g_{\alpha\beta} \Lambda^\beta_\nu = g_{\alpha\beta} \Lambda^\alpha_\mu \Lambda^\beta_\nu = g_{\mu\nu} \quad (3)$$

Here the summation on repeated indices is understood.

The matrix group can be represented by the group of linear transformations on a four dimensional real linear vector space, called Minkowski space, with basis vectors \underline{e}_μ which transform as:

$$\underline{e}'_\mu \equiv L(\Lambda) \underline{e}_\mu = \Lambda^\nu_\mu \underline{e}_\nu \quad (4)$$

The contravariant components of a (real) vector \underline{A} w.r.t. the basis $\{\underline{e}_\mu\}$, indicated by real components A^μ , e.g., $\underline{A} = A^\mu \underline{e}_\mu$, transform as

$$A'^\mu = \Lambda^\mu_\nu A^\nu \quad (5)$$

since

$$\underline{A}' \equiv L(\Lambda) A^\nu \underline{e}_\nu = A^\nu \Lambda^\mu_\nu \underline{e}_\mu \equiv A'^\mu \underline{e}_\mu \quad (6)$$

The group of contragradient matrices $\{\Lambda^{-1T}\}$ is isomorphic to the matrix group $\{\Lambda\}$. Indicating the basis vectors in the corresponding representation space by \underline{e}^μ it can be realized as a group of linear transformations defined by

$$\underline{e}'^\mu = (\Lambda^{-1})^\mu_\nu \underline{e}^\nu \quad (7)$$

The covariant components A_μ of vector \underline{A} w.r.t. this basis ($\underline{A} \equiv A_\mu \underline{e}^\mu$) transform as

$$A'_\mu = (\Lambda^{-1})^\nu{}_\mu A_\nu = (\Lambda^{-1T})^\mu{}_\nu A_\nu \quad (8)$$

Equation (2.1) implies

$$\Lambda T^{-1} = G \Lambda G^{-1} \quad (9)$$

so that the contragradient representation is equivalent to the representation $\{\Lambda\}$. We note also from equations (2.5) and (2.8) that the Kronecker delta δ^μ_ν is an invariant tensor. From the fact that Λ^{-1} is also a Lorentz transformation equation (2.3) implies $g_{\mu\nu} = (\Lambda^{-1})^\alpha{}_\mu (\Lambda^{-1})^\beta{}_\nu g_{\alpha\beta}$ which states that the indices μ and ν are covariant tensor indices and that $g_{\mu\nu}$ is an invariant tensor.

It is clear that $(g_{\mu\nu} \underline{e}^\nu)$ transforms like \underline{e}_μ for

$$\begin{aligned} (g_{\mu\nu} \underline{e}^\nu)' &= g_{\mu\nu} \underline{e}'^\nu = g_{\alpha\beta} \Lambda^\alpha{}_\mu \Lambda^\beta{}_\nu (\Lambda^{-1})^\nu{}_\rho \underline{e}^\rho \\ &= \Lambda^\alpha{}_\mu (g_{\alpha\rho} \underline{e}^\rho) \end{aligned}$$

Thus we may define

$$\underline{e}_\mu = g_{\mu\nu} \underline{e}^\nu \quad (10)$$

which is an alternative statement of the equivalence expressed by equation (2.9). This leads to

$$A_\mu = g_{\nu\mu} A^\nu \quad (11)$$

In other words while the components (A^0, A^1, A^2, A^3) transform by matrix Λ , the components $(A^0, -A^1, -A^2, -A^3)$ transform according to the matrix (Λ^{-1T}) . The two representations are equivalent since the former can be obtained from the latter by a change of basis in the representation space according to equation (2.10).

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tion of the Lorentz group. The Clifford algebra in Minkowski space is defined by a set of four hypercomplex numbers $\gamma^0, \gamma^1, \gamma^2, \gamma^3$ which satisfy the anti-commutation relation ⁷

$$\gamma^\mu \gamma^\nu + \gamma^\nu \gamma^\mu = 2 g^{\mu\nu} I \quad (18)$$

Any product of γ 's can be reduced to, using equation (2.18), to one of the 16 elements $I, \gamma^\mu, (\gamma^\mu \gamma^\nu - \gamma^\nu \gamma^\mu), \gamma_5 \gamma^\mu, \gamma_5$ where $\gamma_5 = \gamma^0 \gamma^1 \gamma^2 \gamma^3$. Representing the γ 's by $(r \times r)$ matrices we can show that the 16 elements are linearly independent so that r must be ≥ 4 . It also follows that the representation of the algebra by 4×4 matrices is irreducible. In the following γ 's will be regarded as (4×4) (irreducible) matrices.

It may be easily shown that the 6 elements $\Sigma^{\mu\nu} = \frac{i}{4} (\gamma^\mu \gamma^\nu - \gamma^\nu \gamma^\mu)$ satisfy the commutation relations of the Lie algebra of the generators $M^{\mu\nu}$ of the homogeneous Lorentz group, viz,

$$[\Sigma^{\mu\nu}, \Sigma^{\rho\sigma}] = i(g^{\mu\sigma} \Sigma^{\nu\rho} - g^{\mu\rho} \Sigma^{\nu\sigma} - g^{\nu\sigma} \Sigma^{\mu\rho} + g^{\nu\rho} \Sigma^{\mu\sigma}) \quad (19)$$

Thus we can obtain a representation by (4×4) complex matrices ⁹ $\{S(\Lambda)\}$ of Lorentz group in terms of Clifford numbers with

$$S(\Lambda) = e^{-i/2 \omega_{\mu\nu} \Sigma^{\mu\nu}} \quad (20)$$

where ¹⁰ $\omega_{\mu\nu} = \Lambda_{\mu\nu} - g_{\mu\nu}$. The corresponding representation space is 4-dimensional complex vector space called Spinor Space. Equations (2.18) to (2.20) lead to

$$S^{-1}(\Lambda) \gamma^\mu S(\Lambda) = \Lambda^\mu_{\nu} \gamma^\nu \quad (21)$$

Denoting the basis vectors of the Spinor space by \underline{Z}_a ($a = 1, 2, 3, 4$), and the components of a vector $\underline{\xi}$ w.r.t. this basis by ξ^a e.g., $\underline{\xi} = \xi^a \underline{Z}_a$, cor-

responding to a Lorentz transformation Λ in Minkowski space the transformation in spinor space is defined to be the linear transformation given by

$$\underline{Z}'_a \equiv U(\Lambda)\underline{Z}_a = S(\Lambda)^b{}_a \underline{Z}_b \quad (22)$$

Here $S^a{}_b$ are the matrix elements of the matrix S . Group property of the transformations (or the operators $U(\Lambda)$ defined on spinor space) may be easily verified. The components ξ^a are seen to transform as

$$\xi'^a \equiv (U(\Lambda)\underline{\xi})^a = S(\Lambda)^a{}_b \xi^b \quad (23)$$

The contragradient representation constituted by the group of matrices $\{S^{-1T}(\Lambda)\}$ is realized on a representation space, whose basis vectors will be indicated by \underline{Z}^a . The group of linear operators acts according to

$$\underline{Z}'^a = (S^{-1}(\Lambda))^a{}_b \underline{Z}^b \quad (24)$$

and the components ξ_a of a vector $\underline{\xi} = \xi_a \underline{Z}^a$ transform as

$$\xi'_a = (S^{-1}(\Lambda))^b{}_a \xi_b = (S^{-1T}(\Lambda))^a{}_b \xi_b \quad (25)$$

We observe that $\xi^a \eta_a$ is an invariant under homogeneous Lorentz transformations.

The conjugate representation by the group of matrices $\{S^*(\Lambda)\}$ is realized on a space with basis vectors indicated by \underline{Z}_a with

$$\underline{Z}'_a = S(\Lambda)^b{}_a \underline{Z}_b ; \quad S^b{}_a = (S^b{}_a)^* \quad (26)$$

and

$$\xi'^{\dot{a}} = S(\Lambda)^{\dot{a}}{}_b \xi^b \quad (27)$$

where $\xi^{\dot{a}}$ are components of $\underline{\xi}$ w.r.t. the basis \underline{Z}_a .

The representation contragradient to the conjugate one is realized on a vector space with basis vectors denoted by $\underline{z}^{\dot{a}}$ with

$$\underline{z}^{\dot{a}} = (S^{-1}(\Lambda))^{\dot{a}}_{\dot{b}} \underline{z}^{\dot{b}} \quad (28)$$

and

$$\xi^{\dot{a}} = (S^{-1}(\Lambda))^{\dot{b}}_{\dot{a}} \xi_{\dot{b}} \quad (29)$$

3. INVARIANT TENSORS

It will be shown below that all these representation, in the present case are equivalent to each other and there is essentially one irreducible representation. However, it is convenient to work with upper, lower, dotted and undotted indices (just as in the case of Minkowski space).

The equation (2.20) can be written explicitly as $((\gamma^{\mu})^a_b \equiv \gamma^{\mu a}_b)$:

$$\gamma^{\mu a}_b = \Lambda^{\mu}_{\nu} S(\Lambda)^a_c (S^{-1}(\Lambda))^d_b \gamma^{\nu c}_d \quad (1)$$

The "mixed quantities" $\gamma^{\mu a}_b$ thus are invariant or held fixed under the Lorentz transformation of the indices defined above and the tacit assumption made that the index ' μ ' in γ^{μ} is a space time contravariant index is consistently assigned. Since Λ^{-1} is a Lorentz transformation we also have:

$$\gamma^{\mu a}_b = (\Lambda^{-1})^{\mu}_{\nu} (S^{-1}(\Lambda))^a_c (S(\Lambda))^b_d \gamma^{\nu c}_d \quad (2)$$

Taking the complex conjugate of equation (3.1)

$$\gamma^{\mu \dot{a}}_{\dot{b}} = \Lambda^{\mu}_{\nu} S(\Lambda)^{\dot{a}}_{\dot{c}} (S^{-1}(\Lambda))^{\dot{d}}_{\dot{b}} \gamma^{\nu \dot{c}}_{\dot{d}} \quad (3)$$

It may be remarked that the Kronecker deltas δ^a_b , $\delta^{\dot{a}}_{\dot{b}}$ are also invariant tensors.

The equivalence of the representations indicated above follow from

$$\{\gamma^{\mu T}, \gamma^{\nu T}\}_+ = \{\gamma^{\mu*}, \gamma^{\nu*}\}_+ = \{\gamma^{\mu\dagger}, \gamma^{\nu\dagger}\}_+ = 2 g^{\mu\nu} I \quad (4)$$

which from the fundamental lemma⁸ assures the existence of non-singular matrices A, B, C such that¹²

$$\begin{aligned} A \gamma^{\mu} A^{-1} &= \gamma^{\mu\dagger} \\ B \gamma^{\mu} B^{-1} &= \gamma^{\mu T} \\ C \gamma^{\mu} C^{-1} &= \gamma^{\mu*} \end{aligned} \quad (5)$$

One can show then

$$B S(\Lambda) B^{-1} = S^{-1T}(\Lambda) \quad \text{or} \quad B^{-1} = S(\Lambda) B^{-1} S^T(\Lambda) \quad (6)$$

$$A S(\Lambda) A^{-1} = S^{\dagger-1}(\Lambda) \quad (7)$$

$$C S(\Lambda) C^{-1} = S^*(\Lambda) \quad (8)$$

We can write equation (3.6) explicitly as:

$$(S^{-1T})^a_c B_{cd} (S^{-1})^d_b = (S^{-1})^c_a B_{cd} (S^{-1})^d_b = B_{ab}$$

or

$$\begin{aligned} B_{ab} &= (S^{-1}(\Lambda))^c_a (S^{-1}(\Lambda))^d_b B_{cd} \\ &= S(\Lambda)^c_a S(\Lambda)^d_b B_{cd} \end{aligned} \quad (9)$$

where the matrix $B \equiv (B_{ab})$. This relation shows that B_{ab} is an invariant tensor with a and b transforming as covariant indices. B matrix plays the

role of metric tensor in spinor space. Since $B_{ab} \underline{z}^b$ transforms as \underline{z}_a we may define

$$\underline{z}_a = B_{ab} z^b \quad (10)$$

which implies

$$\xi_a = B_{ba} \xi^b \quad (11)$$

It may be shown that B may be chosen unitary and antisymmetric.¹³ Metric tensor B^{ab} can be introduced by

$$B_{ab} = B_{ca} B_{db} B^{cd} \quad (12)$$

so that ($B_{ab} = -B_{ba}$)

$$\begin{aligned} B_{db} B^{cd} &= -\delta^c_b \\ B_{ca} B^{cd} &= \delta^d_a \end{aligned} \quad (13)$$

and $B^{ab} = -B^{ba}$ as expected. Also if $B \equiv (B_{ab})$ then $(B^{ab}) = -B^{-1}$. We may also choose a representation of γ matrices such that B is a real matrix, then, $B^* = B = -B^T = -B^{-1}$ and $(B^{ab}) = B$. Using equation (3.13) we have

$$\xi^a = B^{ab} \xi_b \quad \text{and} \quad \underline{z}^a = -B^{ab} \underline{z}_b$$

against $\xi_a = -B_{ab} \xi^b$ and $\underline{z}_a = B_{ab} \underline{z}^b$.

We may define the inner product between two vectors $\underline{\xi}$ and $\underline{\eta}$ by

$$\underline{\xi} \cdot \underline{\eta} = \xi_a \eta^a = B_{ab} \xi^a \eta^b = B^{ab} \xi_a \eta_b \quad (15)$$

From $\underline{z}_a = \delta^b_a \underline{z}_b$ etc. it follows¹⁴

$$\begin{aligned} \underline{z}_a \cdot \underline{z}_b &= B_{ab} & \underline{z}^a \cdot \underline{z}^b &= B^{ab} \\ \underline{z}^a \cdot \underline{z}_b &= \delta^a_b = -\underline{z}_a \cdot \underline{z}^b \end{aligned} \quad (16)$$

Other properties of inner product are

$$\underline{\xi} \cdot \underline{\eta} = - \underline{\eta} \cdot \underline{\xi}$$

$$(\alpha \underline{\xi}) \cdot \underline{\eta} = \underline{\xi} \cdot (\alpha \underline{\eta}) = \alpha \underline{\xi} \cdot \underline{\eta}$$

(17)

$$(\underline{\xi}_1 + \underline{\xi}_2) \cdot \underline{\eta} = \underline{\xi}_1 \cdot \underline{\eta} + \underline{\xi}_2 \cdot \underline{\eta}, \quad \underline{\xi} \cdot (\underline{\eta}_1 + \underline{\eta}_2) = \underline{\xi} \cdot \underline{\eta}_1 + \underline{\xi} \cdot \underline{\eta}_2$$

$$(\underline{\xi} \cdot \underline{\xi} \equiv \xi^a \xi_a = 0 \quad \text{for all } \underline{\xi})$$

and $\underline{\xi} \cdot \underline{\eta} = 0$ for all $\underline{\eta}$ implies $\underline{\xi} \equiv 0$. The representation space is called Symplectic space and the transformations $S(\Lambda)$ leave invariant the non-degenerate skew symmetric bilinear form given by equation (3.15).

An exactly similar discussion can be carried out for conjugate and its contragradient representations. Since $(S^{-1}T)^* = B^* S^* B^{*-1}$ the invariant metric tensors are $B_{\dot{a}\dot{b}}$ and $B^{\dot{a}\dot{b}}$ where $(B_{\dot{a}\dot{b}}) = B^*$ and $(B^{\dot{a}\dot{b}}) = -B^{*-1}$ which for real matrix B are the same as B_{ab} and B^{ab} . We observe that $\xi^{\dot{a}} \eta_{\dot{a}}$ is an invariant but $\xi^{\dot{a}} \eta_a$ is not so and that $\xi^{\dot{a}}$ transforms like ξ^{a*} while $\xi_{\dot{a}} = B_{\dot{a}\dot{b}} \xi^{\dot{b}}$ transforms like ξ_a^* .

We consider now the equivalence relation of equation (3.7). It can be written explicitly as:

$$(S^{-1}T)^{\dot{a}}_{\dot{c}} A_{\dot{c}\dot{d}} (S^{-1})^d_b = (S^{-1})^{\dot{c}}_{\dot{a}} A_{\dot{c}\dot{d}} (S^{-1})^d_b = A_{\dot{a}\dot{b}}$$

or

$$A_{\dot{a}\dot{b}} = (S^{-1}(\Lambda))^{\dot{c}}_{\dot{a}} (S^{-1}(\Lambda))^d_b A_{\dot{c}\dot{d}} \quad (18)$$

where we write $A \equiv (A_{\dot{a}\dot{b}})$. This relation shows that $A_{\dot{a}\dot{b}}$ is an invariant tensor with one dotted and another undotted covariant index. Taking the

complex conjugate we obtain invariant tensor $A_{\dot{a}\dot{b}}$. Raising the indices by metric tensors we obtain invariant tensors ¹⁵ $A^{\dot{a}\dot{b}}, A^{\dot{a}\dot{b}}, A^{\dot{a}}_{\dot{b}}, A^{\dot{a}}_{\dot{b}}$. etc. It is clear that they are useful in constructing invariants of type $\xi^{\dot{a}} A_{\dot{a}\dot{b}} \eta^{\dot{b}}$ and of type $\xi^{\dot{a}*} A_{\dot{a}\dot{b}} \xi^{\dot{b}}$ which may not vanish in contrast to $\xi^{\dot{a}} \xi_{\dot{a}} = 0$. We may choose ⁸ A to be hermitian e.g. $A_{\dot{a}\dot{b}} = A_{\dot{b}\dot{a}} = (A_{\dot{b}\dot{a}})^*$ and $A^2 = I$.

Other invariant hermitian tensors are ¹⁶ $\Gamma^{\mu} = (\Gamma^{\mu}_{\dot{a}\dot{b}}) = (A_{\dot{a}\dot{c}} \gamma^{\mu\dot{c}}_{\dot{b}})$, $A \Sigma^{\mu\nu} \equiv (\Gamma^{\mu\nu}_{\dot{a}\dot{b}})$, $A \gamma_5 \equiv (\Gamma_{\dot{a}\dot{b}})$, $(iA \gamma_5 \gamma^{\mu}) = (\Gamma^{\mu}_{\dot{a}\dot{b}})$. For example, $\Gamma^{\mu}_{\dot{b}\dot{a}} = (\Gamma^{\mu}_{\dot{a}\dot{b}})^* = (A_{\dot{b}\dot{c}} \gamma^{\mu\dot{c}}_{\dot{a}})^* = A_{\dot{b}\dot{c}} \gamma^{\mu\dot{c}}_{\dot{a}} = \gamma^{\mu\dot{c}}_{\dot{a}} A_{\dot{c}\dot{b}} = (\gamma^{\mu\dot{c}}_{\dot{a}} A)_{\dot{c}\dot{b}} = (A \gamma^{\mu})_{\dot{a}\dot{b}} = \Gamma^{\mu}_{\dot{a}\dot{b}}$ since from equation (3.5) $A \gamma^{\mu} = \gamma^{\mu\dot{c}} A$. Tensor quantities may be constructed from a quantity like $\eta^{\dot{a}\dot{b}}$ e.g. scalar $A_{\dot{a}\dot{b}} \eta^{\dot{a}\dot{b}}$, pseudoscalar $\Gamma_{\dot{a}\dot{b}} \eta^{\dot{a}\dot{b}}$, four-vector $\Gamma^{\mu}_{\dot{a}\dot{b}} \eta^{\dot{a}\dot{b}}$, pseudo four-vector $\Gamma^{\mu}_{\dot{a}\dot{b}} \eta^{\dot{a}\dot{b}}$, antisymmetric tensor $\Gamma^{\mu\nu}_{\dot{a}\dot{b}} \eta^{\dot{a}\dot{b}}$. ¹⁷

In particular, reminding that $\xi^{\dot{a}}$ transforms as $\xi^{\dot{a}*}$ we have the well known bilinear covariants $\xi^{\dot{a}*} A_{\dot{a}\dot{b}} \xi^{\dot{b}} \equiv \xi^{\dagger} A \xi$, $\xi^{\dagger} A \gamma^{\mu} \xi = \xi^{\dot{a}*} \Gamma^{\mu}_{\dot{a}\dot{b}} \xi^{\dot{b}}$, $\xi^{\dagger} A \gamma_5 \gamma^{\mu} \xi$, $\xi^{\dagger} A \Sigma^{\mu\nu} \xi$ and $\xi^{\dagger} A \gamma_5 \xi$ transforming as scalar, vector, pseudo-vector, antisymmetric tensor, and pseudo-scalar in Minkowski space.

4. SPINOR REPRESENTATION OF γ MATRICES. TWO SPINORS

To bring out clearly the relationship of the 2-spinor calculus with the 4-spinor calculus discussed above we use a convenient matrix representation for traceless γ matrices.

We take:

$$\gamma^{0\dagger} = \gamma^0 \quad \gamma^{k\dagger} = -\gamma^k, \quad k = 1, 2, 3 \quad (1)$$

so that $\gamma_5 \equiv \gamma^0 \gamma^1 \gamma^2 \gamma^3 = -\gamma_5^\dagger$; $\gamma_5^2 = -I$. Clearly $\gamma^0 \gamma^\mu \gamma^0 = \gamma^{\mu\dagger}$ so that we may identify $A \equiv (A_{ab}) = \gamma^0 = A^\dagger = A^{-1}$. Further we will take ¹⁸ γ^μ to be odd matrices so that $\Sigma^{\mu\nu}$, hence, $S(\Lambda)$ are even. A suitable representation is spinor representation defined by

$$\gamma^0 = \begin{pmatrix} 0 & \sigma^0 \\ \sigma^0 & 0 \end{pmatrix} \quad \gamma^k = \begin{pmatrix} 0 & \sigma^k \\ -\sigma^k & 0 \end{pmatrix} \quad \gamma_5 = i \begin{pmatrix} \sigma^0 & 0 \\ 0 & -\sigma^0 \end{pmatrix} \quad (2)$$

where σ^k are the Pauli 2x2 matrices,

$$\sigma^1 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \quad \sigma^2 = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}, \quad \sigma^3 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \quad \text{and} \quad \sigma^0 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}.$$

We note also for this representation $\gamma^{0T} = \gamma^0$, $\gamma^{2T} = \gamma^2$, $\gamma^{1T} = -\gamma^1$, $\gamma^{3T} = -\gamma^3$ and $\gamma_5^T = \gamma_5$. A real matrix B satisfying equation (3.5) can be taken to be ($B = B^* = -B^T = -B^{-1}$):

$$B = -\gamma_5 \gamma^0 \gamma^2 = \begin{pmatrix} i\sigma^2 & 0 \\ 0 & i\sigma^2 \end{pmatrix} \quad (3)$$

so that

$$(B_{ab}) = (B^{ab}) = (B_{\dot{a}\dot{b}}) = (B^{\dot{a}\dot{b}}) = \begin{pmatrix} 0 & 1 & 0 & 0 \\ -1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & -1 & 0 \end{pmatrix} \quad (4)$$

Also

$$\omega_{\rho\sigma} \Sigma^{\rho\sigma} = \begin{pmatrix} \vec{\sigma} \cdot (\vec{a} - i\vec{b}) & 0 \\ 0 & \vec{\sigma} \cdot (\vec{a} + i\vec{b}) \end{pmatrix} \quad (5)$$

where $b^k = \frac{1}{2} (\omega_{0k} - \omega_{k0})$; $a^k = \frac{1}{2} (\omega_{\ell m} - \omega_{m\ell})$ k, ℓ, m cyclic and $\vec{\sigma} \cdot \vec{a} \equiv \sigma^1 a^1 + \sigma^2 a^2 + \sigma^3 a^3$. For $S(\Lambda)$ we find

$$S(\Lambda) = \begin{pmatrix} S_1(\Lambda) & 0 \\ 0 & S_1^{\dagger-1}(\Lambda) \end{pmatrix} \quad (6)$$

where

$$S_1(\Lambda) = e^{-\frac{i}{2} \vec{\sigma} \cdot (\vec{a} - i\vec{b})} \quad (7)$$

The representation is unitary for space rotations but is in general non-unitary. In so far as only restricted Lorentz group is concerned $S(\Lambda)$ appears as direct sum of two-dimensional representations.

The (2x2) matrix groups $\{S_1(\Lambda)\}$ and $\{S_1^{\dagger-1}(\Lambda)\}$ themselves constitute ¹⁹ two inequivalent representations of the Lorentz group. Under parity transformation, we will see below, the two get interchanged so that representation is irreducible under full Lorentz group. We note $\det(S_1(\Lambda)) = +1$ so that $\{S_1(\Lambda)\}$ and $\{S_1^{\dagger-1}(\Lambda)\}$ constitute the two inequivalent representations of $SL(2, C)$ group. ²⁰

It is clear the two upper components (ξ^1, ξ^2) of ξ^a transform, under a Lorentz transformation, among themselves according

to (2x2) matrix $S_1(\Lambda)$ while the lower components (ξ^3, ξ^4) according to $S_1^{\dagger-1}(\Lambda)$. A change of notation is thus suggested:

$$u^1 \equiv \xi^1 \quad u^2 \equiv \xi^2 \quad v_1 \equiv \xi^3 \quad v_2 \equiv \xi^4 \quad (8)$$

$$u'^A = S_1(\Lambda)^A_B u^B \quad (9)$$

$$v'_{\dot{A}} = (S_1^{-1}(\Lambda))^{\dot{B}}_{\dot{A}} v_{\dot{B}}$$

where $A, B = 1, 2$ and $\dot{A}, \dot{B} = \dot{1}, \dot{2}$. Also $\xi_1 = -\xi^2 = -u^2$, $\xi_2 = \xi^1 = u^1$, $\xi_3 = -\xi^4 = -v_2$, $\xi_4 = \xi^3 = v_1$ and (ξ_1, ξ_2) transform according to matrix $S_1^{-1T}(\Lambda)$ while (ξ_3, ξ_4) according to the matrix $S_1^*(\Lambda)$. We may thus introduce the notation ²¹.

$$u_1 \equiv \xi_1 \quad u_2 \equiv \xi_2 \quad -v^{\dot{1}} \equiv \xi_3 \quad -v^{\dot{2}} \equiv \xi_4 \quad (10)$$

so that

$$u_A = -\epsilon_{AB} u^B, \quad v_{\dot{A}} = -\epsilon_{\dot{A}\dot{B}} v^{\dot{B}} \quad (11)$$

where $\epsilon_{AB}, \epsilon_{\dot{A}\dot{B}}$ are Levi-civita symbols ²² and $u'_A = (S_1^{-1}(\Lambda))^B_A u_B$, $u'_{\dot{A}} = (S_1(\Lambda))^{\dot{B}}_{\dot{A}} u_{\dot{B}}$. We remark that the invariant tensor B is an even matrix in our representation

$$B = (B_{ab}) = \left(\begin{array}{c|c} (\epsilon_{AB}) & 0 \\ \hline 0 & (\epsilon_{\dot{A}\dot{B}}) \end{array} \right); \quad (B^{ab}) = \left(\begin{array}{c|c} (\epsilon^{AB}) & 0 \\ \hline 0 & (\epsilon^{\dot{A}\dot{B}}) \end{array} \right) \quad (12)$$

where $(\epsilon_{AB}) = (\epsilon^{AB}) = (\epsilon_{\dot{A}\dot{B}}) = (\epsilon^{\dot{A}\dot{B}}) = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$. From the identities

like ²³

$$\epsilon^{CD} S_1^A C S_1^B D = (\det S_1) \epsilon^{AB} = \epsilon^{AB} \quad (13)$$

if $\det S_1 = 1$ we see that ϵ^{AB} , ϵ_{AB} , $\epsilon^{\dot{A}\dot{B}}$, $\epsilon_{\dot{A}\dot{B}}$ are invariant tensors. Hence equation (4.11) expresses the equivalence of representation S_1 with (S_1^{T-1}) and S_1^* with $S_1^{-1\dagger}$. Since $\xi^{\dot{a}}$ transforms like $\xi^{\dot{a}}$ we see that $u^{\dot{A}}$ transforms like $u^{\dot{A}}$ while $v_{\dot{A}}$ transforms like $v_{\dot{A}}$. We will adopt the customary practice of identifying $u^{\dot{A}} = u^{*A}$ and $u_{\dot{A}} = u_A^*$. There is no invariant quantity (like $A_{\dot{a}b}$) which related the dotted and undotted components since the conjugate representation $(u^{\dot{A}})$ is not equivalent to the representation $(u^{\dot{A}})$. Likewise we define the basis vectors \underline{h} by

$$\underline{h}_1 \equiv Z_1, \quad \underline{h}_2 \equiv Z_2, \quad \underline{h}^1 \equiv Z_3, \quad \underline{h}^2 \equiv Z_4 \quad (14)$$

and

$$\begin{aligned} -\underline{h}^1 &\equiv \underline{Z}^1 = -\underline{Z}_2 = -\underline{h}_2, & -\underline{h}^2 &\equiv \underline{Z}^2 = \underline{Z}_1 = \underline{h}_1, \\ \underline{h}_{\dot{1}} &= \underline{Z}^3 = -\underline{Z}_4 = -\underline{h}^2, & \underline{h}_{\dot{2}} &= \underline{Z}^4 = \underline{Z}_3 = \underline{h}^1 \end{aligned} \quad (15)$$

so that

$$\underline{\xi} = u^A \underline{h}_A + v_{\dot{A}} \underline{h}^{\dot{A}} = -u_A \underline{h}^A - v^{\dot{A}} \underline{h}_{\dot{A}} \quad (16)$$

and

$$\underline{h}_A = -\epsilon_{AB} \underline{h}^B, \quad \underline{h}_{\dot{A}} = -\epsilon_{\dot{A}\dot{B}} \underline{h}^{\dot{B}} \quad (17)$$

Under a Lorentz transformation the basis vectors \underline{h} transform as

$$\begin{aligned} \underline{h}'_A &= S_1(\Lambda)^B_A \underline{h}_B \\ \underline{h}'_A &= (S_1^{-1}(\Lambda))^A_B \underline{h}^B \\ \underline{h}'_{\dot{A}} &= (S_1(\Lambda))^{\dot{B}}_{\dot{A}} \underline{h}_{\dot{B}} \\ \underline{h}'_{\dot{A}} &= (S_1^{-1}(\Lambda))^{\dot{A}}_{\dot{B}} \underline{h}^{\dot{B}} \end{aligned} \quad (18)$$

From

$$\epsilon_{AB} \epsilon^{BC} = -\delta^C_A, \quad \epsilon_{\dot{A}\dot{B}} \epsilon^{\dot{B}\dot{C}} = -\delta^{\dot{C}}_{\dot{A}} \quad (19)$$

it follows

$$\underline{u}^A = \epsilon^{AB} u_B, \quad \underline{h}^A = \epsilon^{AB} \underline{h}_B \quad (20)$$

and similar expression for dotted indices.

From equation (3.16) we find the following inner products

$$\begin{aligned} \underline{h}_A \cdot \underline{h}^B &= -\underline{h}^A \cdot \underline{h}_B = \delta^A_B = \underline{h}_{\dot{A}} \cdot \underline{h}^{\dot{B}} = -\underline{h}^{\dot{A}} \cdot \underline{h}_{\dot{B}} \\ \underline{h}_A \cdot \underline{h}^{\dot{B}} &= \underline{h}_{\dot{A}} \cdot \underline{h}^B = \underline{h}^A \cdot \underline{h}_{\dot{B}} = \underline{h}^{\dot{A}} \cdot \underline{h}_B = 0 \end{aligned} \quad (21)$$

and

$$\begin{aligned} \underline{h}_A \cdot \underline{h}_B &= \epsilon_{AB} = \epsilon^{AB} = \underline{h}^A \cdot \underline{h}^B \\ \underline{h}_{\dot{A}} \cdot \underline{h}_{\dot{B}} &= \epsilon_{\dot{A}\dot{B}} = \epsilon^{\dot{A}\dot{B}} = \underline{h}^{\dot{A}} \cdot \underline{h}^{\dot{B}} \end{aligned} \quad (22)$$

The vector spaces generated by undotted and dotted basis vectors are orthogonal. The inner product of two vectors \underline{u} and $\underline{\phi}$ in undotted space is

$$\underline{u} \cdot \underline{\phi} = u^A \underline{h}_A \cdot \phi^B \underline{h}_B = \epsilon_{AB} u^A \phi^B = \epsilon^{AB} u_A \phi_B = -u^A \phi_A = u_A \phi^A \quad (23)$$

and satisfies properties given in equation (3.17). The representation space is a symplectic space $Sp(2)$ in two dimensions. The same goes for the dotted vector space and the linear independence of basis vectors follows from equation (4.22). We remark that $u^A \phi_A = -u_A \phi^A$ and $u^A u_A = 0$.

In the spinor representation the equation (2.21) leads to ²⁴

$$\sigma^\mu = \Lambda^\mu{}_\nu S_1(\Lambda) \sigma^\nu S_1^\dagger(\Lambda) \quad (24)$$

from which it follows that

$$\sigma^\mu \equiv (\sigma^\mu \dot{A}\dot{B}) \quad (25)$$

and

$$\sigma^{\mu\dot{A}\dot{B}} = \Lambda^\mu{}_\nu S_1(\Lambda)^A{}_C S_1(\Lambda)^{\dot{B}}{}_{\dot{D}} \sigma^{\nu\dot{C}\dot{D}} \quad (26)$$

showing that $\sigma^{\mu\dot{A}\dot{B}}$ defined by equation (4.25) is an invariant mixed quantity like $(\gamma^{\mu a}{}_b)$. On lowering the indices by invariant metric tensor ϵ_{AB} and using

$$\epsilon_{AC} S_1(\Lambda)^C{}_D \epsilon^{DB} = - (S_1^{-1}(\Lambda))^B{}_A = -S_1(\Lambda^{-1})^B{}_A \quad (27)$$

we show

$$\sigma_{AB}^\mu = \Lambda^\mu{}_\nu (S_1^{-1}(\Lambda))^C{}_A (S_1^{-1}(\Lambda))^{\dot{D}}{}_{\dot{B}} \sigma^{\nu\dot{C}\dot{D}} \quad (28)$$

Both $(\sigma^{\mu\dot{A}\dot{B}})$ and (σ_{AB}^μ) are hermitian matrices, that is $\sigma^{\mu\dot{A}\dot{B}} = \sigma^{\mu\dot{B}\dot{A}}$, $\sigma_{AB}^\mu = \sigma_{BA}^\mu \equiv (\sigma^{\mu\dot{B}\dot{A}})^*$. From $(\sigma_{AB}^\mu) = (\epsilon_{AC} \epsilon_{BD} \sigma^{\mu\dot{C}\dot{D}}) = -(\epsilon \sigma^\mu \epsilon)$ we see $(\sigma_{AB}^0) = \sigma^0$, $(\sigma_{AB}^1) = -\sigma^1$, $(\sigma_{AB}^2) = \sigma^2$, $(\sigma_{AB}^3) = -\sigma^3$ so that

$$(\sigma_{AB}^0) = \sigma^0; \quad (\sigma_{AB}^k) = (\sigma^k_{AB})^* = -\sigma^k, \quad k = 1, 2, 3 \quad (29)$$

The matrices $(\sigma^{\mu\dot{A}\dot{B}})$ are not all hermitian contrary to $(\sigma^{\mu\dot{A}\dot{B}})$, (σ_{AB}^μ) and (σ_{AB}^μ) . It can be shown easily

$$\sigma^{\mu\dot{A}\dot{B}} \sigma_{BC}^\nu + \sigma^{\nu\dot{A}\dot{B}} \sigma_{BC}^\mu = 2 g^{\mu\nu} \delta_C^A \quad (30)$$

from which follows

$$\sigma^{\mu\dot{A}\dot{B}} \sigma_{AB}^\nu = 2 g^{\mu\nu} \quad (31)$$

Then

$$\sigma_{\mu\dot{C}\dot{D}} \sigma^{\mu\dot{A}\dot{B}} \sigma_{AB}^\nu = 2 g^{\mu\nu} \sigma_{\mu\dot{C}\dot{D}} = 2 \sigma_{\nu\dot{C}\dot{D}}$$

which implies ²⁵

$$\sigma_{\mu\dot{C}\dot{D}} \sigma^{\mu\dot{A}\dot{B}} = 2 \delta_C^A \delta_{\dot{D}}^{\dot{B}} \quad (32)$$

Other similar relations follow by raising a lowering the indices and taking complex conjugation. From equations (4.26) and (4.31) we have

$$2g^{\mu\nu} = \Lambda^\mu_\rho (S_1(\Lambda))^A_C (S_1(\Lambda))^{\dot{B}}_{\dot{D}} \sigma^{\rho\dot{C}\dot{D}} \sigma^\nu_{\dot{A}\dot{B}} \quad (33)$$

or

$$\Lambda^{\nu\alpha} \equiv g^{\mu\nu} (\Lambda^{-1})^\alpha_\mu = \frac{1}{2} S_1(\Lambda)^A_C S_1(\Lambda)^{\dot{B}}_{\dot{D}} \sigma^{\alpha\dot{C}\dot{D}} \sigma^\nu_{\dot{A}\dot{B}}$$

so that

$$\begin{aligned} \Lambda^\mu_\nu &= \frac{1}{2} S_1(\Lambda)^A_C S_1(\Lambda)^{\dot{B}}_{\dot{D}} \sigma_\nu^{\dot{C}\dot{D}} \sigma^\mu_{\dot{A}\dot{B}} \\ &= \frac{1}{2} g_{\alpha\nu} \text{Tr} \{ (\sigma^\mu_{\dot{B}\dot{A}}) S_1(\Lambda) \sigma^\alpha S_1^\dagger(\Lambda) \} \end{aligned} \quad (34)$$

The following explicit form of γ^μ will be useful latter.

$$(\gamma^{\mu a}{}_b) = \begin{pmatrix} 0 & (\sigma^{\mu\dot{A}\dot{B}}) \\ (\sigma^\mu_{\dot{A}\dot{B}}) & 0 \end{pmatrix} \quad (35)$$

$$(A_{\dot{a}\dot{b}} \gamma^{\mu b}{}_c) = \begin{pmatrix} (\sigma^\mu_{\dot{A}\dot{B}}) & 0 \\ 0 & (\sigma^{\mu\dot{A}\dot{B}}) \end{pmatrix} \quad (36)$$

The results obtained here are the main tools of 2-spinor calculus discussed in references 1 and 2.

Eqn. (4.26) shows that $\sigma^{\mu AB} u_{AB}$ transforms as a 4-vector in Minkowski space while, for a vector U^μ , $(U_\mu \sigma^{\mu AB})$ transforms as u_{AB} . Thus we may establish a correspondence between u_{AB} and a 4-vector U^μ by the relation ²⁶

$$U^\mu = \frac{1}{2} \sigma^{\mu AB} u_{AB} \quad (37)$$

$$u_{AB} = \sigma_{\mu AB} U^\mu$$

U^μ is real if u_{AB} is hermitian, it is a null vector if $u_{AB} = \xi_A \eta_B$ and a real null vector if $u_{AB} = \pm \xi_A \xi_B$ (e.g. a 2-spinor ξ_A determines a real null vector). Since u_{AB} are component of a vector in the direct product spinor space spanned by $\{\underline{h}_A \otimes \underline{h}_B\}$

$$\underline{u} \equiv u^{AB} (\underline{h}_A \otimes \underline{h}_B) = U_\mu \sigma^{\mu AB} (\underline{h}_A \otimes \underline{h}_B) \equiv U_\mu \underline{E}^\mu \quad (38)$$

where

$$\underline{E}^\mu = \sigma^{\mu AB} (\underline{h}_A \otimes \underline{h}_B) \quad (39)$$

constitute a basis for the representation of the Lorentz group. In fact

$$\begin{aligned} \underline{E}^{\mu} &= (\Lambda^{-1\mu}{}_\nu \sigma^{\nu CD} S_1^{-1}(\Lambda)^A{}_C S_1^{-1}(\Lambda)^B{}_D) S_1(\Lambda)^E{}_A S_1(\Lambda)^F{}_B (\underline{h}_E \otimes \underline{h}_F) \\ &= \Lambda^{-1\mu}{}_\nu \sigma^{\nu CD} \underline{h}_C \otimes \underline{h}_D = (\Lambda^{-1})^\mu{}_\nu \underline{E}^\nu \end{aligned} \quad (40)$$

thus establishing the correspondence $\underline{e}^\mu \longleftrightarrow \underline{E}^\mu$. Explicitly,

$$\underline{E}^0 = (\underline{h}_1 \otimes \underline{h}_1 + \underline{h}_2 \otimes \underline{h}_2), \quad \underline{E}^1 = (\underline{h}_2 \otimes \underline{h}_1 + \underline{h}_1 \otimes \underline{h}_2) \quad (41)$$

$$\underline{E}^2 = -i(\underline{h}_1 \otimes \underline{h}_2 - \underline{h}_2 \otimes \underline{h}_1), \quad \underline{E}^3 = (\underline{h}_1 \otimes \underline{h}_1 - \underline{h}_2 \otimes \underline{h}_2)$$

The inner product is found to be

$$\begin{aligned} \underline{E}^\mu \cdot \underline{E}^\nu &= \sigma^{\mu AB} \sigma^{\nu CD} (\underline{h}_A \cdot \underline{h}_C) (\underline{h}_B \cdot \underline{h}_D) \\ &= \sigma^{\mu AB} \sigma^{\nu CD} \epsilon_{AC} \epsilon_{BD} = \sigma^{\mu AB} \sigma^{\nu}_{AB} = 2g^{\mu\nu} \end{aligned} \quad (42)$$

5. SPIN FRAME

The expression in equation 4.37 reminds us of tetrad formalism frequently used in general relativity. The formalism is useful for discussion in Riemannian space where the metric tensor $g^{\mu\nu}$ becomes function of space time coordinates while at the same time we introduce local cartesian frame of reference at each point in space-time. The tetrads or four legs then connect the world component A^μ with local components $A^{(\mu)}$. We will limit ourselves to the discussion in which the metric tensors remains constant independent of the coordinates. The discussion in 2-dimensional spinor space goes in close analogy to the case of 4-dimensional Minkowski space which we first review briefly.

Consider four vectors $\underline{n}_{(\alpha)}$, $(\alpha) = (0), (1), (2), (3)$ such that

$$\underline{n}_{(\alpha)} \cdot \underline{n}_{(\beta)} = g_{(\alpha)(\beta)} \quad (1)$$

where $g_{(\alpha)(\alpha)} = (1, -1, -1, -1)$, $g_{(\alpha)(\beta)} = 0$ for $(\alpha) \neq (\beta)$ e.g. \underline{n}_0 is time-like and $\underline{n}_{(1)}, \underline{n}_{(2)}, \underline{n}_{(3)}$ are space-like. They are clearly linearly independent and we may write

$$\underline{A} = A^{(\alpha)} \underline{n}_{(\alpha)} = A_{(\alpha)} \underline{n}^{(\alpha)} \quad (2)$$

where we define $g^{(\alpha)(\beta)} \equiv g_{(\alpha)(\beta)}$ and $A^{(\alpha)} = g^{(\alpha)(\beta)} A_{(\beta)}$. We expand

$\underline{n}_{(\alpha)}$ w.r.t. the basis $\{\underline{e}_{\mu}\}$

$$\begin{aligned}\underline{n}_{(\alpha)} &= h_{(\alpha)}^{\mu} \underline{e}_{\mu} = h_{(\alpha)\mu} \underline{e}^{\mu} \\ \underline{n}_{(\alpha)} &= g^{(\alpha)(\beta)} \underline{n}_{(\beta)} = h_{\mu}^{(\alpha)} \underline{e}^{\mu} = h^{(\alpha)\mu} \underline{e}_{\mu}\end{aligned}\quad (3)$$

whence it follows

$$\underline{A} = A^{\mu} \underline{e}_{\mu} = A^{(\alpha)} h_{(\alpha)}^{\mu} \underline{e}_{\mu} \quad (4)$$

or

$$A^{\mu} = A^{(\alpha)} h_{(\alpha)}^{\mu} \quad (5)$$

and similar relations obtained by raising and lowering the indices. The normalization conditions of \underline{e}_{μ} and $\underline{n}_{(\alpha)}$ gives ²⁷

$$\begin{aligned}g_{(\alpha)(\beta)} h_{\mu}^{(\alpha)} h_{\nu}^{(\beta)} &= g_{\mu\nu} \\ g_{\mu\nu} h_{(\alpha)}^{\mu} h_{(\beta)}^{\nu} &= g_{(\alpha)(\beta)}\end{aligned}\quad (6)$$

From the discussion in section 2 we find that under a Lorentz transformation

$$\underline{n}'_{(\alpha)} \equiv L(\Lambda) \underline{n}_{(\alpha)} = h_{(\alpha)}^{\mu} \Lambda^{\nu}_{\mu} \underline{e}_{\nu} \equiv h'^{\mu}_{(\alpha)} \underline{e}_{\mu} \quad (7)$$

e.g. $h'^{\mu}_{(\alpha)} = \Lambda^{\mu}_{\nu} h^{\nu}_{(\alpha)}$ so that index (α) is unaffected. From $A^{(\alpha)} = h^{(\alpha)}_{\mu} A^{\mu}$, shown easily, we see that $A^{(\alpha)}$ components are unchanged too.

Thus tetrads of vectors $h^{\mu}_{(\alpha)}$ (or $\underline{n}_{(\alpha)}$) define a (fixed) frame of reference w.r.t. which any vector A^{μ} can be decomposed. The linear independence of $h^{\mu}_{(\alpha)}$ is easily demonstrated. We also note $\underline{A} \cdot \underline{B} = A^{\mu} B_{\mu} = A^{(\alpha)} B_{(\alpha)}$ and that the inner product remains invariant under a Lorentz transformation as well as under a rotation of the frame of reference, that is, when

$$\begin{aligned} \underline{n}_{(\alpha)} &\rightarrow \underline{N}_{(\alpha)} \text{ with } \underline{N}_{(\alpha)} \cdot \underline{N}_{(\beta)} = g_{(\alpha)(\beta)} \text{ or equivalently }^{28} \\ h_{(\alpha)}^{\mu} &\rightarrow R_{(\alpha)}^{(\beta)} h_{(\beta)}^{\mu} \text{ with } g_{(\sigma)(\rho)} R_{(\alpha)}^{(\sigma)} R_{(\beta)}^{(\rho)} = g_{(\alpha)(\beta)} \end{aligned}$$

For 2-spinor space a spin frame may be defined in terms of two vectors $\underline{n}_{(1)}$ and $\underline{n}_{(2)}$, in complex two dimensional space with basis vectors \underline{h}_1 , and \underline{h}_2 which satisfy, like \underline{h}_A , the normalization condition

$$\underline{n}_{(A)} \cdot \underline{n}_{(B)} = \epsilon_{(A)(B)} \quad (8)$$

where $\epsilon_{(1)(2)} = -\epsilon_{(2)(1)} = 1$, $\epsilon_{(A)(B)} = 0$ for $(A) \neq (B)$.²⁹ The spin frame is completely specified in terms of the components $h_{(A)}^B$ of the vectors $\underline{n}_{(A)} = h_{(A)}^B \underline{h}_B = -h_{(A)B} \underline{h}^B$ just as $h_{(\alpha)}^{\mu}$ did so in earlier case. From equation (4.23) it follows

$$\epsilon_{(A)(B)} = \epsilon_{CD} h_{(A)}^C h_{(B)}^D = h_{D(A)} h_{(B)}^D = -h_{(A)}^D h_{(B)D} \quad (9)$$

This leads to³⁰

$$\epsilon^{AB} = \epsilon^{(C)(D)} h_{(C)}^A h_{(D)}^B = h_{(C)}^A h^{(C)B} = -h^{(D)A} h_{(D)}^B \quad (10)$$

where $\epsilon^{(A)(B)} = \epsilon_{(A)(B)}$ and they are used to raise or lower the indices inside brackets in the fashion identical to that of ϵ_{AB} and ϵ^{AB} , for example, $\underline{n}^{(A)} = \epsilon^{(A)(B)} \underline{n}_{(B)}$ and $u_{(A)} = -\epsilon_{(A)(B)} u^{(B)}$ etc. From

$$\underline{u} = u^{(A)} \underline{n}_{(A)} = -u_{(A)} \underline{n}^{(A)} = u^B \underline{h}_B = -u_B \underline{h}^B \quad (11)$$

we have the expansion

$$u^A = h_{(B)}^A u^{(B)} = -h^{(B)A} u_{(B)} \quad (12)$$

The inverse relations³¹ are

$$\begin{aligned}
 u^{(A)} &= -h_B^{(A)} u^B = h^{(A)B} u_B \\
 \underline{h}_A &= -h_A^{(C)} \underline{n}_{(C)} = h_{(C)A} \underline{n}^{(C)}
 \end{aligned}
 \tag{13}$$

and others obtained by raising and lowering the indices. A Lorentz transformation Λ induces, according to the discussion in section 4, the transformation:

$$\underline{n}'_{(A)} = h_{(A)}^B \underline{h}_B = S_1(\Lambda)^C_B h_{(A)}^B \underline{h}_C \equiv h'_{(A)}^B \underline{h}_B
 \tag{14}$$

or

$$h'_{(A)}^B = S_1(\Lambda)^B_C h_{(A)}^C
 \tag{15}$$

Similarly, we have $h'_{(A)B} = (S_1^{-1}(\Lambda))^C_B h_{(A)C}$. Thus the components $u^{(A)}$ are unaltered. For the inner product we note $\underline{u} \cdot \underline{\phi} = u_A \phi^A = -u^A \phi_A = u_{(A)} \phi^{(A)} = -u^{(A)} \phi_{(A)}$. It thus remains invariant under Lorentz transformations as well as under the spin frame rotations. The latter constitute the transformations defined by

$$\underline{N}_{(A)} = S^{(B)}_{(A)} \underline{n}_{(B)} \equiv H^B_{(A)} \underline{h}_B
 \tag{16}$$

such that $\underline{N}_{(A)} \cdot \underline{N}_{(B)} = \epsilon_{(A)(B)}$. It follows that $\epsilon_{(A)(B)} S^{(A)}_{(C)} S^{(B)}_{(D)} = \epsilon_{(C)(D)}$ so that the complex matrix $(S^{(A)}_{(B)})$ is unimodular and belongs to $SL(2, C)$ group. Also $H^B_{(A)} = S^{(C)}_{(A)} h^B_{(C)}$ and $\underline{u} = u^{(A)} \underline{n}_{(A)} = U^{(A)} \underline{N}_{(A)}$ implies $U^{(A)} = (S^{-1})^{(A)}_{(B)} u^{(B)}$. We observe that while $u^{(A)}$ is unaltered under Lorentz transformations, u^A is unaltered under spin frame rotations. An exactly analogous discussion goes for the complex 2-spinor space with dotted indices spanned by $\{\underline{h}_1^{\dot{}}, \underline{h}_2^{\dot{}}\}$.

An arbitrary spinor $u^{A\dot{B}}$, likewise, may be expanded w.r.t. the spin frame, $u^{A\dot{B}} = h_{(C)}^A h_{(\dot{D})}^{\dot{B}} u^{(C)(\dot{D})}$. For the case of $\sigma^{\mu A\dot{B}}$ we have

$$\sigma^{\mu A\dot{B}} = h_{(C)}^A h_{(\dot{D})}^{\dot{B}} \sigma^{\mu(C)(\dot{D})} \quad (17)$$

or

$$\sigma^{\mu(A)(\dot{B})} = h_C^{(A)} h_{\dot{D}}^{(\dot{B})} \sigma^{\mu C\dot{D}} \quad (18)$$

Under a Lorentz transformation the quantities $\sigma^{\mu(A)(\dot{B})}$ transform like a four vector, viz,

$$\sigma^{\mu(A)(\dot{B})} = \Lambda^\mu{}_\nu \sigma^{\nu(A)(\dot{B})} \quad (19)$$

Moreover, we may easily show $\sigma^{\mu(A)(\dot{B})} \sigma_{\mu(C)(\dot{D})} = 2 \delta_{(C)}^{(A)} \delta_{(\dot{D})}^{(\dot{B})}$ and $\sigma^{\mu(A)(\dot{B})} \sigma_{\nu(A)(\dot{B})} = 2 g^{\mu\nu}$ so that $\sigma^{\mu(1)(\dot{1})}$, $\sigma^{\mu(1)(\dot{2})}$, $\sigma^{\mu(2)(\dot{1})}$ and $\sigma^{\mu(2)(\dot{2})}$ are linearly independent set. We may thus expand ³² any four-vector U^μ in terms of them

$$U^\mu = u_{(A)(\dot{B})} \sigma^{\mu(A)(\dot{B})} = u_{A\dot{B}} \sigma^{\mu A\dot{B}} \quad (20)$$

where

$$u_{(A)(\dot{B})} = \frac{1}{2} \sigma_{\mu(A)(\dot{B})} U^\mu \quad (21)$$

The explicit expressions for $\sigma^{\mu(A)(\dot{B})}$ are

$$\begin{aligned} \sigma^0(A)(\dot{B}) &= h_1^{(A)} h_1^{(\dot{B})} + h_2^{(A)} h_2^{(\dot{B})}, & \sigma^1(A)(\dot{B}) &= h_1^{(A)} h_2^{(\dot{B})} + h_2^{(A)} h_1^{(\dot{B})} \\ \sigma^2(A)(\dot{B}) &= i(-h_1^{(A)} h_2^{(\dot{B})} + h_2^{(A)} h_1^{(\dot{B})}), & \sigma^3(A)(\dot{B}) &= h_1^{(A)} h_1^{(\dot{B})} - h_2^{(A)} h_2^{(\dot{B})} \end{aligned} \quad (22)$$

We also note that

$$\sigma^{\mu(A)(\dot{B})} \sigma_{\mu(A)(\dot{B})} = 0, \quad (A), (\dot{B}) \text{ fixed.} \quad (23)$$

Thus $\sigma^{\mu(A)(\dot{B})}$ constitute a basis in Minkowski space of four null

tetrad of vectors, two of which are real e.g. $\sigma^{\mu(1)(\dot{1})}$ and $\sigma^{\mu(2)(\dot{2})}$ and $\sigma^{\mu(1)(\dot{2})}$ and $\sigma^{\mu(2)(\dot{1})}$ are complex conjugate of each other. 33

6. REPRESENTATION OF FOUR GROUP IN SPINOR SPACE

The following 4x4 matrices Λ_s , Λ_t , Λ_{st} together with identity matrix I constitute an Abelian group called the Four-group:

$$\Lambda_s = \begin{pmatrix} -1 & & & 0 \\ & -1 & & \\ & & -1 & \\ 0 & & & 1 \end{pmatrix} \quad \Lambda_t = \begin{pmatrix} 1 & & & 0 \\ & 1 & & \\ & & 1 & \\ 0 & & & -1 \end{pmatrix} \quad \Lambda_{st} \equiv \Lambda_s \Lambda_t = \begin{pmatrix} -1 & & & 0 \\ & -1 & & \\ & & -1 & \\ 0 & & & -1 \end{pmatrix} \quad (1)$$

They correspond to space reflection, time inversion and space-time inversion in Minkowski space. Combined with the restricted Lorentz group we obtain the Full or Extended Lorentz group. We can show that, if we stick to linear transformations in representation space, it is impossible to represent the four group by 2x2 matrices while maintaining the mixed quantities $\sigma^{\mu\dot{A}\dot{B}}$ fixed according to equation (4.26). For Λ_s we have,

$$\begin{aligned} (\sigma^{k\dot{A}\dot{B}}) &= -S_1(\Lambda_s) (\sigma^{k\dot{A}\dot{B}}) S_1^\dagger(\Lambda_s); \quad k = 1, 2, 3 \\ (\sigma^{0\dot{A}\dot{B}}) &= S_1(\Lambda_s) (\sigma^{0\dot{A}\dot{B}}) S_1^\dagger(\Lambda_s) \end{aligned} \quad (2)$$

while for Λ_t ,

$$\begin{aligned} (\sigma^{k\dot{A}\dot{B}}) &= +S_1(\Lambda_t) (\sigma^{k\dot{A}\dot{B}}) S_1^\dagger(\Lambda_t); \quad k = 1, 2, 3 \\ (\sigma^{0\dot{A}\dot{B}}) &= -S_1(\Lambda_t) (\sigma^{0\dot{A}\dot{B}}) S_1^\dagger(\Lambda_t) \end{aligned} \quad (3)$$

In either case we require $S_1 \sigma^k S_1^{-1} = -\sigma^k$ (or $S_1 \sigma^k = -\sigma^k S_1$) for $k=1,2,3$. It is easily verified that this is not possible to attain this in terms of 2x2 matrices for which $(\sigma^0, \sigma^1, \sigma^2, \sigma^3)$ is a complete set. The situation is different in 4-dimensional spinor space and the improper transformation can be represented by linear transformations through 4x4 matrices.

The restricted Lorentz group is invariant sub-group of the full group and one verifies the following relations:

$$\begin{aligned}
 \Lambda_S^{-1} \Lambda_R \Lambda_S &= \Lambda_R & \Lambda_t^{-1} \Lambda_R \Lambda_t &= \Lambda_R \\
 \Lambda_S^{-1} \Lambda_L \Lambda_S &= \Lambda_L^{-1} & \Lambda_t^{-1} \Lambda_L \Lambda_t &= \Lambda_L^{-1} \\
 \Lambda_{st}^{-1} \Lambda_R \Lambda_{st} &= \Lambda_R & \Lambda_{st}^{-1} \Lambda_L \Lambda_{st} &= \Lambda_L
 \end{aligned} \tag{4}$$

where Λ_R is a space rotation and Λ_L pure Lorentz transformation, say, in (01) plane. Hence we require the corresponding representation matrices in spinor space to satisfy:

$$\begin{aligned}
 S^{-1}(\Lambda_S) \gamma^k \gamma^l S(\Lambda_S) &= \gamma^k \gamma^l = S^{-1}(\Lambda_t) \gamma^k \gamma^l S(\Lambda_t) \\
 S^{-1}(\Lambda_S) \gamma^0 \gamma^k S(\Lambda_S) &= -\gamma^0 \gamma^k = S^{-1}(\Lambda_t) \gamma^0 \gamma^k S(\Lambda_t)
 \end{aligned} \tag{5}$$

At the same time we require that the $\gamma^{\mu a}{}_b$ behave as invariant "mixed quantity" under the full group, according to equation (3.1). This leads to

$$\begin{aligned}
 S(\Lambda_S) \gamma^k S^{-1}(\Lambda_S) &= -\gamma^k \\
 S(\Lambda_S) \gamma^0 S^{-1}(\Lambda_S) &= \gamma^0
 \end{aligned} \tag{6}$$

and

$$S(\Lambda_t) \gamma^k S^{-1}(\Lambda_t) = \gamma^k \quad (7)$$

$$S(\Lambda_t) \gamma^0 S^{-1}(\Lambda_t) = -\gamma^0$$

It is easily shown that these imply ³⁴

$$\gamma_s^i \equiv S(\Lambda) \gamma_s S^{-1}(\Lambda) = (\det \Lambda) \gamma_s \quad (8)$$

or, written explicitly,

$$\gamma_s^i{}^a{}_b \equiv S(\Lambda)^a{}_c S^{-1}(\Lambda)^d{}_b \gamma_s^c{}_d = (\det \Lambda) \gamma_s^a{}_b \quad (9)$$

From equation (2.18), it follows that we may choose

$$S(\Lambda_s) = a \gamma^0 \quad (10)$$

$$S(\Lambda_t) = b \gamma_s \gamma^0$$

then

$$\begin{aligned} S(\Lambda_{st}) &\equiv S(\Lambda_s) S(\Lambda_t) = -ab \gamma_s \\ &= -S(\Lambda_t) S(\Lambda_s) \equiv -S(\Lambda_{ts}) \end{aligned} \quad (11)$$

We note that, though $\Lambda_{st} = \Lambda_{ts}$ but $S(\Lambda_{st}) = -S(\Lambda_{ts})$. Hence, we have double valued representation of the four group in spinor space ³⁵. The constants 'a' and 'b' may be fixed by requiring that the parity and time inversion operations applied twice lead the identity transformation upto a + sign due to double-valuedness of the representation. Thus

$$[S(\Lambda_s)]^2 = a^2 I = \pm I \quad \text{or} \quad a^2 = \pm 1 \quad (12)$$

$$[S(\Lambda_t)]^2 = b^2 I = \pm I \quad \text{or} \quad b^2 = \pm 1$$

so that ³⁶ $a = \pm 1, \pm i; b = \pm 1, \pm i; |a|^2 = 1, |b|^2 = 1, a^4 = 1$ and $b^4 = 1$.

We find then the following relations. ³⁷

$$A S(\Lambda_s) A^{-1} = a \gamma^{0\dagger} = a a^* (a \gamma^0)^{\dagger-1} = S(\Lambda_s)^{-1\dagger}$$

$$A S(\Lambda_t) A^{-1} = b \gamma_5^\dagger \gamma^{0\dagger} = b b^* (b \gamma_5^{-1} \gamma^{0-1})^{\dagger-1} = -(b \gamma_5 \gamma^0)^{\dagger-1} = -S(\Lambda_t)^{\dagger-1} \quad (13)$$

which may be combined with equation (3.7) as

$$\begin{aligned} A S(\Lambda) A^{-1} &= S(\Lambda)^{\dagger-1} & \Lambda^0_0 &\geq 1 \\ &= -S(\Lambda)^{\dagger-1} & \Lambda^0_0 &\leq -1 \end{aligned} \quad (14)$$

for the full group. This may be interpreted as the transformation of matrix A,

$$A' \equiv S(\Lambda)^{\dagger-1} A S^{-1}(\Lambda) = \text{Sgn}(\Lambda^0_0) A \quad (15)$$

or

$$A'_{ab} \equiv (S^{-1}(\Lambda))^c_a (S^{-1}(\Lambda))^d_b A_{cd} = \text{Sgn}(\Lambda^0_0) A_{ab} \quad (16)$$

where $\text{Sgn}(\Lambda^0_0) = \pm 1$ according as $\Lambda^0_0 \geq 1$ or $\Lambda^0_0 \leq -1$.

The metric matrix B in the spinor representation of γ matrices of section 4 is given by $B = -\gamma_5 \gamma^0 \gamma^2$. We find

$$B' \equiv S^{-1T}(\Lambda_s) B S^{-1}(\Lambda_s) = a^2 B \quad (17)$$

$$B' \equiv S^{-1T}(\Lambda_t) B S^{-1}(\Lambda_t) = -b^2 B$$

or $B'_{ab} = S^{-1}(\Lambda_s)^c_a S^{-1}(\Lambda_s)^d_b B_{cd} = a^2 B_{ab}$ etc. Taking inverse of

equation (6.17) we find similar relations for B^{ab} . We note that $B'^{ac} B'_{cb} = B^{ac} B_{cb} = -\delta^a_b$ since the Kronecker delta is an invariant tensor under the full group. The tensors $A_{\dot{a}b}$, B_{ab} and B^{ab} are invariant only upto a sign under the four group.

7. TRANSFORMATION OF SPINOR AND BILINEAR INVARIANTS

The transformation of spinors given by equations (2.23), (2.25), (2.27) and (2.29) reads in terms of 2-spinors of section 4 as follows:

$$\text{Parity: } u'^A = a v_{\dot{A}}, \quad v'^A = -a^{*-1} u_{\dot{A}}, \quad u'_A = -a^{-1} v^{\dot{A}}, \quad v'_A = a^* u^{\dot{A}} \quad (1)$$

$$\text{Time-inversion: } u'^A = i b v_{\dot{A}}, \quad v'^A = i b^{-1*} u_{\dot{A}}, \quad u'_A = i b^{-1} v^{\dot{A}}, \quad v'_A = i b^* u^{\dot{A}} \quad (2)$$

and the relations obtained by taking their complex conjugate. From equations (4.12) and (6.17) it follows

$$(\epsilon_{AB})' = a^2 (\epsilon^{\dot{A}\dot{B}}) \quad (\epsilon^{AB})' = a^2 (\epsilon_{\dot{A}\dot{B}}) \quad (3)$$

for parity and

$$(\epsilon_{AB})' = -b^2 (\epsilon^{\dot{A}\dot{B}}) \quad (\epsilon^{AB})' = -b^2 (\epsilon_{\dot{A}\dot{B}}) \quad (4)$$

for time inversion. 39

The bilinear invariants of section 3 take the following form in spinor

representation

$$S \text{ (Scalar)} = \xi^{\dot{a}} A_{\dot{a}b} \eta^b = u^{\dot{A}} \chi_{\dot{A}} + v_A \phi^A \quad (5)$$

$$\text{where } \xi^{\dot{a}} = \begin{pmatrix} u^{\dot{A}} \\ v_A \end{pmatrix} \text{ and } \eta^{\dot{a}} = \begin{pmatrix} \phi^A \\ \chi_{\dot{A}} \end{pmatrix} \quad (6)$$

$$P \text{ (Pseudoscalar)} = \xi^{\dot{a}} A_{\dot{a}b} \gamma_s^b \eta^c = -i(u^{\dot{A}} \chi_{\dot{A}} - v_A \phi^A) \quad (7)$$

V (4-Vector):

$$\begin{aligned} V^\mu &= \frac{1}{2} \xi^{\dot{a}} A_{\dot{a}c} \gamma^{\mu c} \eta^b \\ &= \frac{1}{2} \sigma_{BA}^{\mu \dot{a}} (\phi^B u^{\dot{A}} + v^B \chi^{\dot{A}}) \end{aligned} \quad (8)$$

A (Pseudo vector):

$$A^\mu = \frac{1}{2} \xi^{\dot{a}} A_{\dot{a}c} (i \gamma_s \gamma^\mu)^c \eta^b = \frac{1}{2} \sigma_{BA}^{\mu \dot{a}} (\phi^B u^{\dot{A}} - v^B \chi^{\dot{A}}) \quad (9)$$

T (Antisymmetric tensor): $F^{\mu\nu} = \xi^{\dot{a}} A_{\dot{a}c} (\Sigma^{\mu\nu})^c \eta^b$ is apart from a factor $\approx \left[u^{\dot{A}} \sigma_{AB}^{\mu \dot{a}} \sigma^{\nu BC} \chi_{\dot{C}} + v_A \sigma^{\mu AB} \sigma_{BC}^{\nu \dot{a}} \phi^C \right] - (\mu \leftrightarrow \nu)$.

For

$$\begin{aligned} \xi^{\dot{a}} &= \eta^{\dot{a}} \\ S &= u^{\dot{A}} v_{\dot{A}} + u^A v_A = S^* \\ P &= -i(u^{\dot{A}} v_{\dot{A}} - u^A v_A) = P^* \\ V^\mu &= \frac{1}{2} \sigma_{BA}^{\mu \dot{a}} (u^B u^{\dot{A}} + v^B v_{\dot{A}}) = V^{\mu*} \end{aligned} \quad (10)$$

$$A^\mu = \frac{1}{2} \sigma_{BA}^{\mu \dot{a}} (u^B u^{\dot{A}} - v^B v_{\dot{A}}) = A^{\mu*}$$

We observe that the invariants S and P vanish for 4-spinors of type $(\begin{smallmatrix} u^A \\ \lambda u^{\dot{A}} \end{smallmatrix}) = \xi = \eta$. It is easily shown that $V^\mu V_\mu = A^\mu A_\mu = 4(u^{\dot{A}} \chi_{\dot{A}})(\phi^B v_B)$ which for $\xi = \eta$ reduces to $4(u^{\dot{A}} v_{\dot{A}})(u^B v_B)$ and is real. Hence $\xi = \eta = (\begin{smallmatrix} u^A \\ \lambda u^{\dot{A}} \end{smallmatrix})$ defines a real null vector, or that a 2-spinor defines a real null vector². The two scalars S and P and the two vectors V and A behave differently under improper transformations. For example,

$$\begin{aligned} (\xi^\dagger A \gamma^\mu \xi)' &\equiv \xi'^\dagger A' \gamma'^\mu \xi' = \xi^\dagger S^\dagger S^{-1\dagger} A S^{-1} \Lambda^\mu_\nu S \gamma^\nu S^{-1} S \xi \\ &= \Lambda^\mu_\nu (\xi^\dagger A \gamma^\nu \xi) = \xi'^\dagger A' \gamma'^\mu \xi' \end{aligned} \quad (11)$$

the last equality following from the invariance of $\gamma^{\mu a}_b$ under full group.

From equation (6.15) it follows:

$$\begin{aligned} \xi'^\dagger A \gamma^\mu \xi' &= \Lambda^\mu_\nu (\xi^\dagger A \gamma^\nu \xi) && \Lambda \in \mathcal{L}_+^\dagger \\ &= -\xi^\dagger A \gamma^k \xi; && k = 1, 2, 3 \\ &= +\xi^\dagger A \gamma^0 \xi && \mu = 0 \\ &= +\xi^\dagger A \gamma^\mu \xi && \Lambda = \Lambda_{st} \end{aligned} \quad \left. \vphantom{\begin{aligned} \xi'^\dagger A \gamma^\mu \xi' \\ = -\xi^\dagger A \gamma^k \xi \\ = +\xi^\dagger A \gamma^0 \xi \\ = +\xi^\dagger A \gamma^\mu \xi \end{aligned}} \right\} \Lambda = \Lambda_s \text{ or } \Lambda_t \quad (12)$$

For pseudo-vector $\xi'^\dagger A \gamma_5 \gamma^\mu \xi'$ we have opposite sign for $\Lambda = \Lambda_s$ or Λ_t .

For scalar and pseudo scalar we obtain

$$\begin{aligned} \xi'^\dagger A \xi' &= \xi^\dagger A \xi && \text{for } \Lambda = \Lambda_s \\ &= -\xi^\dagger A \xi && \text{for } \Lambda = \Lambda_t, \Lambda_{st} \\ \xi'^\dagger A \gamma_5 \xi' &= -\xi^\dagger A \gamma_5 \xi && \text{for } \Lambda = \Lambda_s, \Lambda_{st} \\ &= +\xi^\dagger A \gamma_5 \xi && \text{for } \Lambda = \Lambda_t \end{aligned} \quad (13)$$

and for tensor case

$$\xi'^{\dagger} A \gamma^k \gamma^l \xi' = \pm \xi^{\dagger} A \gamma^k \gamma^l \xi$$

$$\xi' A \gamma^0 \gamma^k \xi' = \mp \xi^{\dagger} A \gamma^0 \gamma^k \xi$$

the upper sign holding for Λ_s and lower for Λ_t .

The choice of the phases factors 'a' and 'b' may be narrowed by appealing to antilinear operation of charge conjugation associated with Dirac equation:

$$(i \gamma^{\mu a}{}_b \partial_{\mu} - m \delta^a{}_b) \xi^b = e A_{\mu} \gamma^{\mu a}{}_b \xi^b \quad (14)$$

On taking the complex conjugate, multiplying by A_{ac}° and using $A_{ac}^{\circ} \gamma^{\mu c}{}_b = A_{cb}^{\circ} \gamma^{\mu c}{}_a$ we obtain

$$i A_{bd}^{\circ} \gamma^{\mu d}{}_c \partial_{\mu} \xi^{*b} + m A_{cb}^{\circ} \xi^{*b} = -e A_{\mu} A_{bd}^{\circ} \gamma^{\mu d}{}_c \xi^{*b}$$

From $\left\{ -\gamma^{\mu T}, -\gamma^{\nu T} \right\} = 2 g^{\mu\nu}$ it follows that there exists a nonsingular matrix C such that $C \gamma^{\mu} C^{-1} = -\gamma^{\mu T}$ or $\gamma^{\mu a}{}_c C^{cb} = -C^{ac} \gamma^{\mu b}{}_c$ where $C^{-1} \equiv (C^{ab})$ and whose invariance under restricted group may easily be verified. Hence

$$(i \gamma^{\mu a}{}_b \partial_{\mu} - m \delta^a{}_b) \eta^b = -e A_{\mu} \gamma^{\mu a}{}_b \eta^b \quad (15)$$

where the charge conjugate spinor η is given by

$$\eta^a \equiv C^{ca} A_{bc}^{\circ} \xi^{*b} \quad (16)$$

It corresponds to a Dirac particle with charge (-e). A candidate for C is

$$C = \lambda \gamma_5 B^{-1} \quad (17)$$

Requiring that charge conjugation applied twice leads back to original spinor leads to $|\lambda|^2 = 1$.

We verify ⁴² that under a restricted transformation

$$\eta'^a = \mathbb{C}^{ca} A_{bc} \xi^{*b} = \mathbb{C}^{ca} A_{bc} S(\Lambda)^b_d \xi^d = S(\Lambda)^a_b \eta^b \quad (18)$$

and now impose ⁸ that $\eta'^a \equiv \mathbb{C}^{ca} A_{bc} \xi^{*b}$ satisfies the same relation under the improper transformations as well which leads to

$$\begin{aligned} \mathbb{C}'^{-1} &\equiv S(\Lambda) \mathbb{C}^{-1} S^T(\Lambda) = \mathbb{C}^{-1} && \text{for } \Lambda^0_0 \geq 1 \\ &= -\mathbb{C}^{-1} && \text{for } \Lambda^0_0 \leq -1 \end{aligned} \quad (19)$$

This in turn requires $a^2 = -1$, $b^2 = -1$ e.g., $a = \pm i$, $b = \pm i$.

* * *

REFERENCES AND FOOTNOTES[†]

- * 1. Exhaustive list of references on spinor analysis may be found in W. L. Bade and H. Jehle, Rev. Mod. Phys. 25, 714 (1953) and W. C. Parke and H. Jehle, Lectures in Theoretical Physics Vol. VII a, Univ. of Boulder Press (1964) p. 297. See also E. M. Corson; Tensors, Spinors and Relativistic Wave Equations (Blackie and Sons Ltd. London, 1953) and J. Aharoni, The Special Theory of Relativity, (Oxford University Press 1965).
- * 2. See for example, F. A. E. Pirani, Lectures in General Relativity, (Prentice Hall, N. J., 1965); C. J. Isham, A. Salam and J. Strathee, IC/72/123 (1972).
3. The first or upper index labels row and the second or lower index labels columns when Λ^μ_ν or $g_{\mu\nu}$ are written as matrices. We will avoid using matrices corresponding to Λ_μ^ν .
4. See section 7 where representations of Four group are considered.
5. It follows that $g^{\mu\nu}$ is a contravariant tensor in indices μ and ν .
6. $g^{\mu\nu} g_{\mu\nu} = g_{\alpha\beta} \Lambda^\alpha_\mu \Lambda^\beta_\nu g^{\mu\nu} \equiv g_{\alpha\beta} g^{\alpha\beta}$ or $g^{\alpha\beta} = g^{\mu\nu} \Lambda^\alpha_\mu \Lambda^\beta_\nu$.
7. $(\gamma^0)^2 = I$ (identity), $(\gamma^k)^2 = -I$, $k = 1, 2, 3$. The tacit assumption that ' μ ' appearing in γ^μ is Minkowski space index will be shown below.

[†] The references are marked by an asterisk.

- *8. See for example, S. S. Schweber: Relativistic Quantum Field Theory (Row Peterson and Co., 1961), Chapters 1 and 4.
9. Due to the appearance of half-angles the representation is double-valued for space rotations, e.g. both the matrices $\pm S(\Lambda)$ represent the rotation. There is no ambiguity in sign due to half-angles for pure Lorentz transformations. We will adopt the normalization $\det S(\Lambda) = 1$.
10. Note that except the identity matrix all other elements of Clifford algebra are traceless. Note also $\omega_{\mu\nu} + \omega_{\nu\mu} + \epsilon_{\alpha\beta} \omega^{\alpha}_{\mu} \omega^{\beta}_{\nu} = 0$. The relations $S(\Lambda) S(\Lambda') = S(\Lambda\Lambda')$ and $S(\Lambda^{-1}) = S^{-1}(\Lambda)$ may easily be verified.
11. T indicates transpose and $(A^T)^a_b = A^b_a$. The greek letters label space-time indices while roman letters the spinor indices. It is clear that $\{S^{-1T}(\Lambda)\}$, $\{S^*(\Lambda)\}$ and $\{S^{-1\dagger}(\Lambda)\}$ constitute representations isomorphic to the group $\{S(\Lambda)\}$.
12. We also have matrices corresponding to a negative sign on the right hand side. Note that $A\gamma^{\mu}A^{-1} = \gamma^{\mu T*} = (B\gamma^{\mu}B^{-1})^* = B^*C\gamma^{\mu}C^{-1}B^{-1*}$. Hence $(A^{-1}B^*C)$ is a multiple of identity. If we impose $\det(A) = \det(B) = \det(C) = 1$, these matrices are defined only upto a factor $\pm 1, \pm i$.
13. It cannot be chosen to be symmetric as it will lead to ten antisymmetric linearly independent 4×4 matrices $(B\gamma_5\gamma^{\mu}), (B\Sigma^{\mu\nu})$.

14. Thus $\underline{Z}_a \cdot \underline{Z}_b = 0$ when $a = b$ and $\underline{Z}_a \cdot \underline{Z}_b = -\underline{Z}_b \cdot \underline{Z}_a$. Also equations (3.16) ensure that \underline{Z}_a are linearly independent vectors (when $B_{ab} = -B_{ba}$ is non-singular matrix).
15. These tensors are like metric tensor and may be used to relate the dotted basis with undotted basis vectors.
16. We have $\gamma_5 = \gamma^0 \gamma^1 \gamma^2 \gamma^3$, $\gamma_5^\dagger = A \gamma_5 A^{-1}$, $\Sigma^{\mu\nu\dagger} = A \Sigma^{\mu\nu} A^{-1}$, $\{\gamma_5, \gamma^\mu\}_+ = 0$.
17. In fact η_{ab}^* regarded as (4x4) matrix can be decomposed in terms of the 16 linearly independent matrices A , $A \gamma^\mu$, $A \Sigma^{\mu\nu}$, $i A \gamma_5 \gamma^\mu$, $A \gamma_5$ which form a basis for all 4-dim. matrices of the form (η_{ab}^*) . Similar situation holds for (η_{ab}) , $(\eta_{ab}^{\cdot\cdot})$ etc.
18. Since γ 's constitute an irreducible representation they can not be all chosen to be even matrices.
19. They become identical for space rotation sub-group. The representation $\{S_1(\Lambda)\}$ is the so called $D(\frac{1}{2}, 0)$ representation while $\{S_1^{\dagger-1}(\Lambda)\}$ is $D(0, \frac{1}{2})$ of the $SL(2, C)$ group. $\{S(\Lambda)\}$ corresponds to $D(\frac{1}{2}, 0) \oplus D(0, \frac{1}{2})$. See for example Corson¹ or Schweber⁸.
- * 20. M. A. Naimark, Linear Representations of Lorentz Group, (Pergamon Press N.Y. 1964); I. M. Gel'fand, M. I. Graev and N. Ya. Vilenkin, Integral Geometry and Representation Theory (Academic Press, N. Y., 1966); M. Carmeli: J. Math. Phys. 11, 1917 (1970).

$$= \det S(\Lambda_t) = \det S(\Lambda_{st}) = 1.$$

37. These relations (as well as the expressions for $S(\Lambda_s)$ and $S(\Lambda_t)$) are derived using equation (2.18), $A \gamma^\mu A^{-1} = \gamma^{\mu\dagger}$ and the definition $\gamma_5 = \gamma^0 \gamma^1 \gamma^2 \gamma^3$.

21. The minus sign for ξ_3 and ξ_4 is for convenience.
22. $\epsilon_{12} = \epsilon^{12} = 1$, $\epsilon_{AB} = -\epsilon_{BA}$, $\epsilon_{AB} = \epsilon^{AB}$ and same definition for dotted indices.
23. In matrix notation $\epsilon^{-1} S_1 \epsilon = S_1^{T-1}$ where $\epsilon = (\epsilon^{AB}) = (\epsilon_{AB})$.
24. Use $\gamma^\mu S(\Lambda) = \Lambda^\mu{}_\nu S(\Lambda) \gamma^\nu$ and $(\Lambda^k{}_\ell \sigma^\ell + \Lambda^k{}_0 \sigma^0)$.
 $(\Lambda^k{}_m \sigma^m - \Lambda^k{}_0 \sigma^0) = (\Lambda^k{}_1)^2 + (\Lambda^k{}_2)^2 + (\Lambda^k{}_3)^2 - (\Lambda^k{}_0)^2 = 1$ etc.
25. In fact $\sigma_{\mu CD} \sigma^{\mu AB} = 2 \delta_C^A \delta_D^B + F_{CD}^{AB}$ such that $F_{CD}^{AB} \sigma_{AB}^{\nu} = 0$. It is easily shown $F_{CD}^{AB} \equiv 0$.
26. $U_\mu U^\mu = \det(u^{AB})$. Note $g^{\mu\nu} = \frac{1}{4} \sigma_{AB}^\mu \sigma_{CD}^\nu (2\epsilon^{AC} \epsilon^{BD})$ implies $g^{AB, CD} = 2 \epsilon^{AC} \epsilon^{BD}$.
27. The first relation leads to the second by noting $g^{\mu\nu} g_{(\alpha)(\beta)} h_\mu^{(\alpha)} h_\nu^{(\beta)} = g^{\mu\nu} g_{\mu\nu} = g_{(\alpha)(\beta)} g^{(\alpha)(\beta)}$.
28. $\underline{N}_{(\alpha)} = R_{(\alpha)}^{(\beta)} \underline{n}_{(\beta)}$ then $h_{(\alpha)}^\mu \rightarrow H_{(\alpha)}^\mu = R_{(\alpha)}^{(\beta)} h_{(\beta)}^\mu$ and $A^{(\alpha)} \rightarrow (R^{-1})^{(\alpha)}_{(\beta)} A^{(\beta)} \equiv \underline{A}^{(\alpha)}$. Note $\underline{A} = A^{(\alpha)} \underline{n}_{(\alpha)} = \underline{A}^{(\alpha)} \underline{N}_{(\alpha)}$.
29. The label (A) = (1) or (2) is convenient. We could, of course, use any other labelling, say (A) = (0) or (1) etc.

These are exactly the results obtained in the non-degenerate case ¹.

ii) Identical sub-bands

We now considers two identical sub-bands, one gets the following results:

$$\begin{aligned} \chi_{(0)}^{(\alpha)}(k,q) &= \chi_{(0)}^{(\beta)}(k,q) = \chi_{(0)}^{(d)}(k,q) \\ \chi_{(1)}^{\alpha\beta}(k,q) &= \chi_{(1)}^{\beta\alpha}(k,q) = \chi_{(1)}(k,q) \end{aligned} \quad (56)$$

$$U_{\alpha} = U_{\beta} = U \quad \text{and} \quad v_{sd}^{(\alpha)}(k) = v_{sd}^{(\beta)}(k)$$

The results (55) imply that: $\bar{J}_{(\alpha)}^{(d)}(k+q,k) = J_{(\beta)}^{(d)}(k+q,k)$ and consequently $v_{(\alpha)}^{(d)}(k,q) = 1$.

The susceptibility $\chi_{(J)}^{(\alpha)} = \chi_{(J)}^{(\beta)}$ assume a particularly interesting form, namely:

$$\chi_{(J)}(k,q) = \frac{\chi_{(0)}^{(d)}(k,q)}{1 + (U_{\text{eff}}^{(d)}(q) + \bar{J}_{\alpha\beta}(q))\chi_{(0)}^{(d)}(q)} \quad (57-a)$$

where the effective interactions are defined by:

$$\begin{aligned} U_{\text{eff}}^{(d)}(q) &= U \left\{ 1 + \frac{J_{\alpha\beta}}{U} \frac{\chi_{\text{mix}}(q)}{\chi_{(0)}^{(d)}(q)} \right\} \\ \bar{J}_{\alpha\beta}(q) &= J_{\alpha\beta} \left\{ 1 + \frac{U}{J_{\alpha\beta}} \frac{\chi_{\text{mix}}(q)}{\chi_{(0)}^{(d)}(q)} \right\} \end{aligned} \quad (57-b)$$

As for the s-electrons are concerned, since $\bar{J}_{(\alpha)}^{(d)} = \bar{J}_{(\beta)}^{(d)}$ the effective ex-

38. Thus we need two kinds of 2-spinors to represent parity and time inversion corresponding to inequivalent representations $D(\frac{1}{2}, 0)$ and $D(0, \frac{1}{2})$. Under space-time inversion $u'^A = i(ab)u^A$, $v'_A = -i(ab)v_A$.

39. $(\epsilon^{\dot{A}\dot{B}})' = (\epsilon^{AB})'^* = a^2(\epsilon_{AB})$ etc. and $u'_A = -(\epsilon_{AB})' u'^B$ etc.

40. $\gamma'_5 = (\det \Lambda)\gamma_5$.

41. C must be antisymmetric just like B matrix.

42. $C^{-1} = S(\Lambda) C^{-1} S(\Lambda)^T$; $S^\dagger(\Lambda) A S(\Lambda) = A$.