

Statistical characterization of the standard map

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Abstract. The standard map, paradigmatic conservative system in the (x, p) phase space, has been recently shown (Tirnakli and Borges (2016 *Sci. Rep.* **6** 23644)) to exhibit interesting statistical behaviors directly related to the value of the standard map external parameter K . A comprehensive statistical numerical description is achieved in the present paper. More precisely, for large values of K (e.g. $K = 10$) where the Lyapunov exponents are neatly positive over virtually the entire phase space consistently with Boltzmann–Gibbs (BG) statistics, we verify that the q -generalized indices related to the entropy production q_{ent} , the sensitivity to initial conditions q_{sen} , the distribution of a time-averaged (over successive iterations) phase-space coordinate q_{stat} , and the relaxation to the equilibrium final state q_{rel} , collapse onto a fixed point, i.e. $q_{\text{ent}} = q_{\text{sen}} = q_{\text{stat}} = q_{\text{rel}} = 1$. In remarkable contrast, for small values of K (e.g. $K = 0.2$) where the Lyapunov exponents are virtually zero over the entire phase space, we verify $q_{\text{ent}} = q_{\text{sen}} = 0$, $q_{\text{stat}} \simeq 1.935$, and $q_{\text{rel}} \simeq 1.4$. The situation

corresponding to intermediate values of K , where both stable orbits and a chaotic sea are present, is discussed as well. The present results transparently illustrate when BG behavior and/or q -statistical behavior are observed.

Keywords: nonlinear dynamics

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1. Introduction

Statistical characterization of dynamical systems, particularly weakly chaotic low-dimensional dissipative maps, have been made according to its sensitivity to the initial conditions, the rate of increase of the entropy, the rate of relaxation to the attractor, and the distribution of a statistical variable [1]. For strongly chaotic systems, these behaviors present an exponential nature and are described by the Boltzmann–Gibbs (BG) statistical mechanical framework [2]. On the other hand, weakly chaotic systems, that present zero *largest Lyapunov exponent* (LLE) λ , need a more general formalism to be conveniently handled. It has been observed that the nonextensive statistical mechanical framework is able to describe different features of various classes of complex systems [3–18]. If the LLE approaches zero, the sensitivity to the initial conditions and the rate of relaxation to the attractor follow q -exponential behaviors, the distributions exhibit a q -Gaussian form, and the rate of increase of entropy demands S_q entropy. All these behaviors are parameterized by the indices q_{sen} , q_{ent} , q_{rel} , q_{stat} , for *sensitivity*, *entropy production*, *relaxation*, and *stationary distribution*, respectively. It has been observed (and in some instances proved) that, for low-dimensional systems, $q_{\text{sen}} = q_{\text{ent}}$, through the q -generalized Pesin identity [1]. Consequently, three (possibly related) quantities remain to be addressed, that are currently referred to as the q -triplet [1]. The q -triplet has been experimentally observed in a variety of complex systems like in the ozone layer [19] and in the Voyager I data for the solar wind [20], among many others. The possible relations between the q -triplet indices should in principle exhibit the

fixed point $q = 1$ in BG statistical regimes. This happens whenever the LLE is positive. In fact, the LLE plays a central role in the determination of which statistical framework is to be used in the description of nonlinear dynamical systems.

In the present work we address a low-dimensional conservative system, namely the standard map [21, 22]:

$$p_{i+1} = p_i - K \sin x_i \quad ; \quad x_{i+1} = x_i + p_{i+1} \quad (1)$$

where p and x are taken as modulo 2π . Its phase space can exhibit strongly (weakly) chaotic regions characterized by positive (zero) local LLE. The LLE has been numerically evaluated through the Benettin *et al* algorithm [23] for each initial condition separately [24, 25]. For sufficiently small values of K , for instance $K = 0.2$, virtually the entire phase space exhibits stable orbits (zero LLE), and if K takes high values ($K = 10$), the points of the phase space have finite positive values of LLE. In the present work, we numerically evaluate the values of q_{sen} , q_{ent} , and q_{rel} for both strongly and weakly chaotic cases. We also revisit the stationary distributions that have been recently found in [24], and particularly the mixed case, where both strongly and weakly chaotic regions exist. Finally, we exhibit the interplay, within the stationary distributions, between strongly and weakly chaotic q_{stat} indices for arbitrary values of K .

2. Sensitivity to initial conditions

The sensitivity to initial conditions is given by

$$\xi(t) = \lim_{\|\Delta x(0)\| \rightarrow 0} \frac{\|\Delta x(t)\|}{\|\Delta x(0)\|}, \quad (2)$$

where $\Delta x(t)$ is the temporal dependence of the discrepancy of two very close initial conditions at time t . When ergodic behavior dominates, equation (2) is expressed by the exponential dependence,

$$\xi(t) = e^{\lambda t} \quad (3)$$

and λ is the standard LLE. Strongly chaotic systems are those which present $\lambda > 0$. Strong insensitivity to initial conditions corresponds to $\lambda < 0$. The marginal case $\lambda = 0$ is governed by a rule which is more subtle than equation (3) [26], namely:

$$\xi(t) = \exp_{q_{\text{sen}}}(\lambda_{q_{\text{sen}}} t), \quad (4)$$

where $\exp_q x \equiv [1 + (1 - q)x]_+^{1/(1-q)}$ is the so called q -exponential function [27] with $[u]_+ = \max\{u, 0\}$ (with $\exp_1 x = e^x$), and $\lambda_{q_{\text{sen}}}$ is a generalized Lyapunov coefficient. If $\lambda_{q_{\text{sen}}} > 0$ the system is weakly chaotic, in the sense that $\xi(t)$ diverges slower than the exponential case, —asymptotically, a power law—. If the system is strongly chaotic, $q_{\text{sen}} \rightarrow 1$, and equation (4) recovers the standard exponential dependence, with $\lambda_{q_{\text{sen}}} \rightarrow \lambda_1 \equiv \lambda$.

The correctness of this description can be checked, for both regimes of standard map, in figure 1 (strongly chaotic regime) and figure 3 (weakly chaotic regime). They show, for different values of q , the averages of $\ln_q \xi(t)$ (where $\ln_q x \equiv (x^{1-q} - 1)/(1 - q)$)

is the inverse function of the q -exponential, and $\ln_1 x = \ln x$) over N_r realizations. Each realization starts with a randomly chosen pair of very close initial conditions, that are localized inside a particular cell of the W equally partitioned phase space. The case $W = 1$ represents averaging over N_r realizations, starting with randomly chosen pairs of initial conditions that are localized all over the whole phase space. We consider decreasing initial discrepancies in equation (2), so as to obtain a well defined behavior for increasingly long times (see figure 1(a)).

For the strongly chaotic case, exponential sensitivity to the initial conditions is verified with $q_{\text{sen}}^{\text{av}} = 1$, and the same generalized Lyapunov exponent characterizes the whole phase space, no matter the value of W (e.g. $W = 1$) or the particular cell inside of which the average is performed. In fact, the slope of all intermediate regimes in figure 1(b) exhibits $\lambda = \lambda_{q_{\text{sen}}^{\text{av}}=1} = 1.62$, in accordance with [29] (see also [30]).

For the weakly chaotic case, stability islands dominate the phase space. In this case, statistical characterization of the map was already tentatively done [31, 32]. But the characterization of cells evolution is much more intricate, and a common transient time can not be defined. This fact tends to preclude a neat linear dependence of $\langle \ln_{q_{\text{sen}}} \xi \rangle$ with time. Consequently, in weakly chaotic regimes, the N_r random pairs of initial conditions are not to be chosen all over the entire phase space but instead inside particular cells, so that their trajectories will go through cells with a similar spreading rate, and a transient time is susceptible to be simply defined (see figure 2). In this way, we verify that the map exhibits $q_{\text{sen}}^{\text{av}} = 0$, whose value of $\lambda_{q_{\text{sen}}^{\text{av}}}$ characterizes the local sensitivity to initial conditions, as it is shown in figure 3.

Summarizing, in both chaotic regimes we verify, after a transient, a nontrivial property [28] namely that there exists a special value of q , noted $q_{\text{sen}}^{\text{av}}$ (where av stands for *average* over the whole phase space for strongly chaotic regime), which yields a linear dependence of $\langle \ln_{q_{\text{sen}}^{\text{av}}} \xi \rangle$ with time. In other words, we verify $\langle \ln_{q_{\text{sen}}^{\text{av}}} \xi(t) \rangle \approx \lambda_{q_{\text{sen}}^{\text{av}}} t$.

3. The rate of entropy production

With respect to the entropy production per unit time, we may conveniently use the q -entropy ($k = 1$, henceforth) [1, 33]

$$S_q(t) \equiv k \frac{1 - \sum_{i=1}^W p_i^q}{q - 1} = k \sum_{i=1}^W p_i \ln_q(1/p_i) \quad [S_1 = S_{\text{BG}} \equiv k \sum_{i=1}^W p_i \ln(1/p_i)]. \quad (5)$$

The q -entropy production is estimated dividing the phase space in W equal cells, and randomly choosing $N_{\text{ic}} \gg W$ initial conditions inside one of the W cells (typically $N_{\text{ic}} = 10W$, so as to obtain statistically well defined results). We follow the spreading of points within the phase space, and calculate equation (5) from the set of occupancy probabilities $\{p_i(t)\}$ ($i = 1, 2, \dots, W$). Fluctuations are of course present, but they can be reduced when we choose $N_c \gg 1$ initial cells within which the N_{ic} initial conditions are chosen, and average $S_q(t)$ over the N_c realizations. The proper value of the entropic parameter $q_{\text{ent}}^{\text{av}}$ is the special value of q which makes the averaged q -entropy production per unit time to be finite, which is ultimately related with the extensivity of the entropy. The q -entropy production per unit time is consequently obtained as

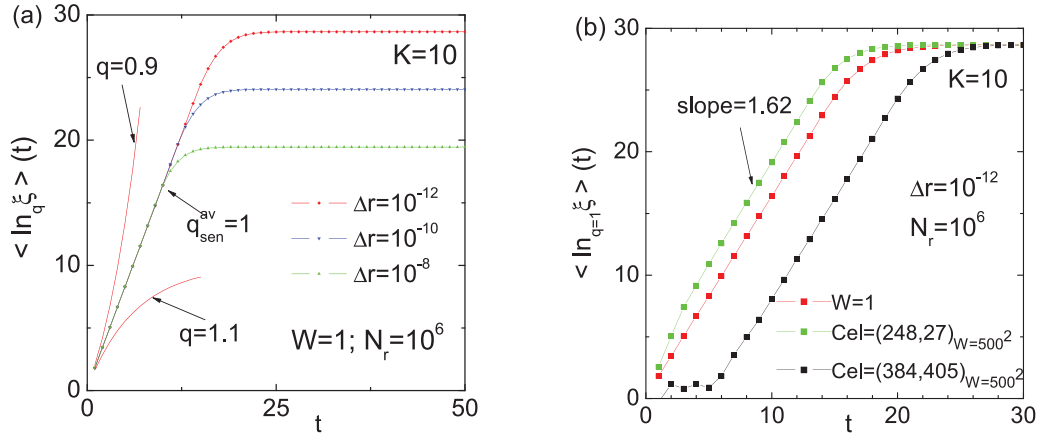


Figure 1. (a) Averages of $\ln \xi_q(t)$ over $N_r = 10^6$ realizations localized all over the whole phase space, i.e. $W = 1$ (see text), for $K = 10$. Decreasing Euclidean discrepancy of initial conditions $\Delta r \equiv \|\Delta x(0)\|$ are considered, and $\langle \ln_{q_{\text{sen}}^{\text{av}}=1} \xi \rangle$ linear dependence with time is yielded in the $\Delta r \rightarrow 0$ limit. (b) Averages of $\ln \xi_q(t)$ over $N_r = 10^6$ realizations, for $K = 10$, and $\Delta r \equiv \|\Delta x(0)\| = 10^{-12}$. The $N_r = 10^6$ pairs of initial conditions are randomly chosen over the whole phase space (red squares) and, amongst the $W = 500 \times 500$ cells of the equally partitioned phase, over one of the quickest spreading cells (green squares) and over one of the slowest spreading cells (black squares). In all cases, the slope is preserved in intermediate regimes.

$$K_{q_{\text{ent}}^{\text{av}}} = \lim_{t \rightarrow \infty} \lim_{W \rightarrow \infty} \lim_{N_{\text{ic}} \rightarrow \infty} \frac{\langle S_{q_{\text{ent}}^{\text{av}}} \rangle_{N_c}(t)}{t} < \infty, \quad (6)$$

and must be calculated taking into account that the partitions of phase space, N_c and N_{ic} are such as to obtain robust results.

When the LLE is large enough and the phase space is dominated by a chaotic sea, the BG entropy ($S_1 = S_{\text{BG}} \equiv -\sum_{i=1}^W p_i \ln p_i$) is expected to be the appropriate one (i.e. $q_{\text{ent}} = 1$). Fluctuations are reduced averaging over a set of $N_c = 0.01 W$ randomly chosen initial cells localized all over the phase space. Our numerical results show, as expected, that the proper value of the entropic index is $q_{\text{ent}}^{\text{av}} = q_{\text{sen}}^{\text{av}} = 1$ for $K = 10$ (see figure 4). Both indices have been obtained comparing the nonlinearity measure of the polynomial fitting curves over the intermediate regime (after a transient and before saturation) where the correlation coefficient is constant and equals 1. Another interesting result that emerged is the coincidence of the slopes of the sensitivity and entropy functions of time (see figures 1 and 4), i.e. the q -entropy production per unit time satisfies $K_{q_{\text{sen}}^{\text{av}}=1} = \lambda_{q_{\text{sen}}^{\text{av}}=1}$. These results are numerically compatible with a q -generalized Pesin-like identity for ensemble averages in strongly chaotic conservative maps, and reinforce those in [28].

Entropic characterization of weakly chaotic regime in conservative maps is much more subtle [34, 35]. The phase space of weakly chaotic conservative maps exhibits stability islands and contains regions with a huge diversity of transient times. This framework makes a hard task to reduce fluctuations of $S_q(t)$ by averaging over N_c cells, and a convenient averaging criterion must be adopted.

The first practical difficulty that we find to discriminate N_c proper cells, in order to estimate $K_{q_{\text{ent}}^{\text{av}}}$ through equation (6), is the slow convergence of the finite time LLE to its

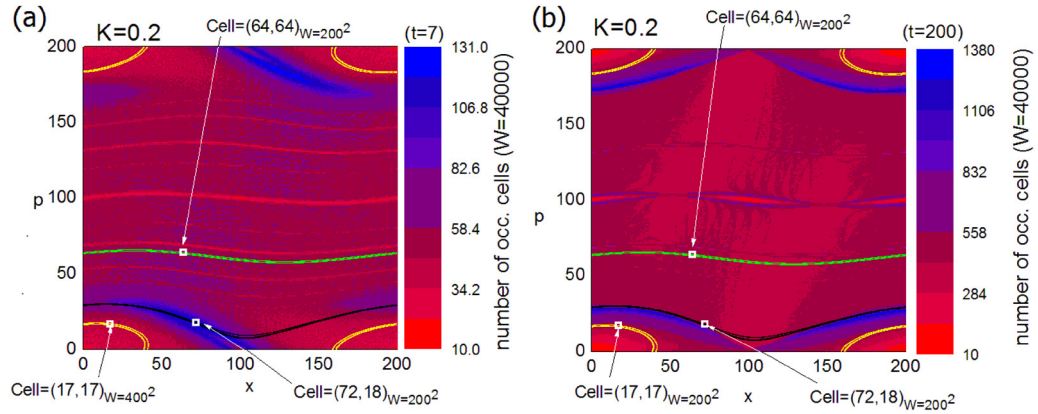


Figure 2. Color maps of the integrated number of occupied cells by the iteration 1 to the iteration t ($t = 7$ (a), $t = 200$ (b)) of 4×10^5 random initial conditions localized in the $(x\text{th}, p\text{th})$ cell of a $W = 200 \times 200$ equally partitioned phase space ($K = 0.2$). To warn about the different local transient times, we superimposed three particular cells and the trajectories of their respective interior initial conditions (yellow, black and green lines).

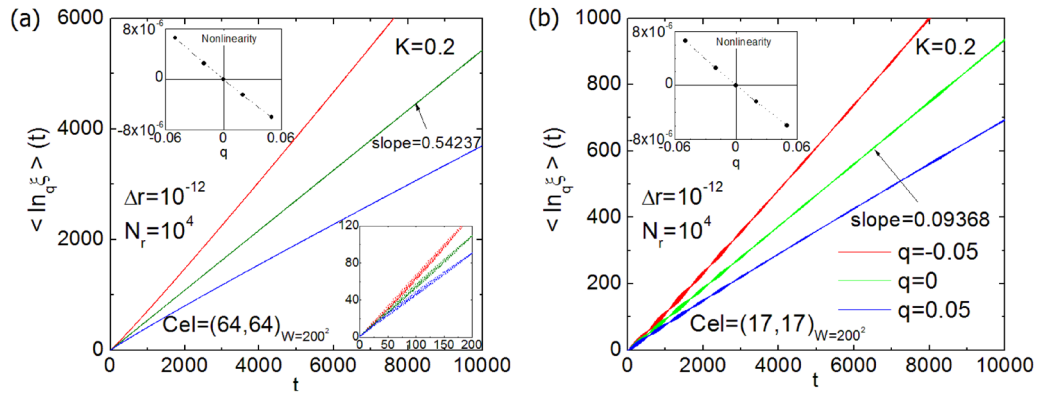


Figure 3. Averages of $\ln \xi_q(t)$ over $N_r = 10^4$ realizations whose initial conditions have been randomly chosen in $(64\text{th}, 64\text{th})$ (a), and $(17\text{th}, 17\text{th})$ (b) cells of the $W = 200 \times 200$ equally partitioned phase space of $K = 0.2$ standard map. A slightly oscillating evolution around q -exponential is observed for short times. Insets represent the nonlinearity measure $R \equiv C/B$ in the fitting curve of $\langle \ln \xi_q(t) \rangle$, $A + Bt + Ct^2$, and demonstrate that $q_{\text{sen}}^{\text{av}} = 0$ is the optimum value of q (a straight line fitting curve is obtained).

$t \rightarrow \infty$ limit value. Extremely long computer times are required, and it is for this reason that we tested the adequacy of the *smaller alignment index* (SALI) [36], instead of the LLE, to characterize weak chaos. First of all, we conclude that the SALI temporal evolution is a computationally cheap tool to characterize chaotic behavior of trajectories. In fact, the SALI tends to zero in both stable and chaotic orbits, but with completely different time rates: it decreases abruptly in strongly chaotic orbits and reaches the limit of accuracy of the computer after about 200 iterations. In contrast, it decreases with time as a power law in stable orbits. We have consequently verified, for the first time to the best of our knowledge, that the SALI decreases with time as a power law even in the case of weakly chaotic orbits. Besides, the power index of the *local* SALI

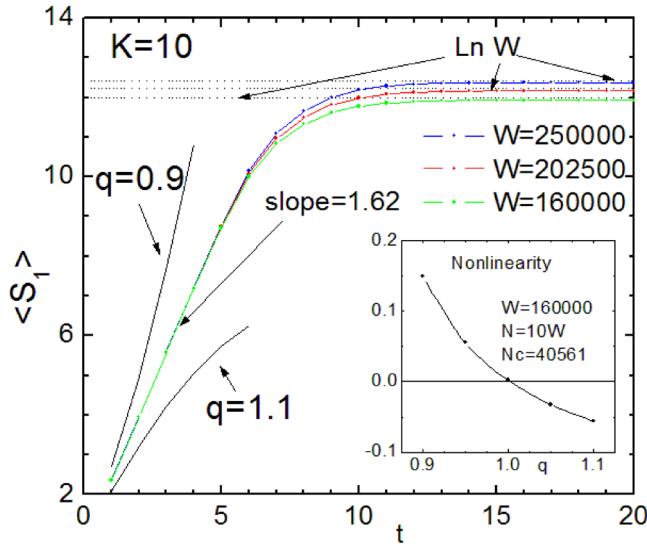


Figure 4. Temporal dependence of $(q_{\text{ent}}^{\text{av}} = 1)$ -entropy in the standard map with $K = 10$, averaging over $N_c = 0.01W$ initial cells, for different values of the number of cells in the equally partitioned phase space, W . The case of $q < q_{\text{ent}}^{\text{av}} = 1$ ($q > q_{\text{ent}}^{\text{av}} = 1$) corresponds to positive (negative) concavity. The $t \rightarrow \infty$ limiting value is $\langle S_1 \rangle = \ln W$.

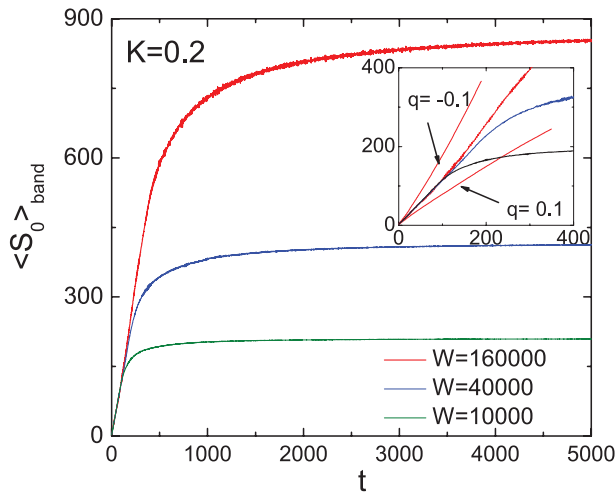


Figure 5. Increase of $(q_{\text{ent}}^{\text{av}} = 0)$ -entropy in the standard map with $K = 0.2$, for different values of W , in a longitudinal band of phase space that covers $p = 2$, $x \in [0, 2\pi]$ (see text). The inset shows that $q < q_{\text{ent}} = 0$ ($q > q_{\text{ent}} = 0$) corresponds to positive (negative) concavity.

temporal evolution is also a computationally cheap resource to discriminate the initial cells that present similar transient entropy behavior. Identifying N_c cells that present a similar SALI temporal evolution, and obtaining the q -entropy production averaged over those N_c initial cells inside of which we randomly choose the N_{ic} initial conditions, $\langle S_q \rangle_{N_c}$ does not present the oscillations of entropy production typically observed in conservative maps [35]. Figure 5 exemplifies this fact, as $\langle S_q \rangle$ has been obtained averaging over a band of the phase space where the criterion of similar SALI evolution is

fulfilled. Consequently, we confirm that a conservative system such as the standard map verifies the same statistical behavior than dissipative ones, i.e. there is a specific value of $q < 1$ in weak chaotic regime (for the logistic map, $q_{\text{ent}} = 0.2445$ [30]) which yields finite entropy production per unit time, and hence $S_{q_{\text{ent}}}$ is the proper entropy to thermodynamically characterize the system.

Summarizing, our numerical results show in both strongly and weakly chaotic regimes, as expected, $q_{\text{ent}}^{\text{av}} = q_{\text{sen}}^{\text{av}}$, which points towards the conjecture of the generalized Pesin equality [26]. In particular, $q_{\text{ent}}^{\text{av}} = q_{\text{sen}}^{\text{av}} = 1$ and $K_{q_{\text{ent}}^{\text{av}}} = \lambda_{q_{\text{sen}}^{\text{av}}} = 1.62$ for $K = 10$ (strong chaotic regime, since $\text{LLE} > 0$), and $q_{\text{ent}}^{\text{av}} = q_{\text{sen}}^{\text{av}} = 0$ for $K = 0.2$ (weakly chaotic regime, since $\lambda \simeq 0$, $\lambda_{q_{\text{sen}}^{\text{av}}} > 0$).

We have also verified, for intermediate values of the parameter of the map that make the chaotic sea and the quasiperiodic trajectories coexist, that the regions of the phase space portrait where $\text{LLE} \neq 0$ verify $q_{\text{ent}}^{\text{av}} = q_{\text{sen}}^{\text{av}} = 1$ and $K_{q_{\text{ent}}^{\text{av}}} = \lambda_{q_{\text{sen}}^{\text{av}}}$, and the regions of the phase space portrait where $\text{LLE} = 0$ verify $q_{\text{ent}}^{\text{av}} = q_{\text{sen}}^{\text{av}} = 0$ but quite frequently $K_{q_{\text{ent}}^{\text{av}}} \neq \lambda_{q_{\text{sen}}^{\text{av}}}$. In particular, we found $\lambda_{q_{\text{sen}}^{\text{av}}=1} = 0.47$ and $\lambda_{q_{\text{sen}}^{\text{av}}=1} = 0.88$, for the chaotic sea associated to the parameter values $K = 2$ and $K = 4$, respectively.

4. The rate of relaxation of the entropy

For the methods described in sections 2 and 3, we chose an ensemble of initial conditions inside one of the W cells of the phase space, and thus $S_q(0) = 0$, $\forall q$. Alternatively, an ensemble of initial conditions can be spread over the entire phase space of a *dissipative* system [37] and, therefore, the maximum possible value for the entropy is $S_{q_{\text{ent}}}(0) = \ln_{q_{\text{ent}}} W$. In that case, the time evolution brings the system to its attractor, and it has been observed that the number of occupied cells falls, and the entropy exponentially relaxes, in the case of a strongly chaotic system, or q -exponentially relaxes, in the case of a weakly chaotic system [38].

The method adopted in [37] cannot be identically applied to a conservative map, since there is no attractor, but the method introduced in [38] can be adapted to area-preserving models. We consider the variable $\Delta S_q(t) = S_q(\infty) - S_q(t)$ and evaluate its average over an ensemble of initial conditions for $t \rightarrow \infty$. The average must be computed with a different criterion in strongly and weakly chaotic regimes, according to their respective dynamical behavior in phase space.

The strongly chaotic map is dominated all over the partitioned phase space by a chaotic sea, and we can analytically calculate $S_{q=1}(\infty) = \ln W$. In that case, the average $\langle \Delta S_q(t) \rangle_{N_{\text{ic}}}$ has been estimated over the most quickly spreading cells N_{ic} , to minimize the computation time. On the contrary, the stability islands dominate the phase space in the weakly chaotic regime, and their respective value of $S_{q_{\text{ent}}}(\infty) = \ln_{q_{\text{ent}}} W_{\text{islands}}$ (where W_{islands} is the number of occupied cells when the system achieves its stationary state) is unknown, as it numerically depends on the cells where the initial conditions are randomly chosen. Consequently, in weakly chaotic regimes, $S_{q_{\text{ent}}}(\infty)$ must be first numerically estimated.

We verify, as expected, that $\lim_{W \rightarrow \infty} \Delta S_{q_{\text{ent}}}^{\text{av}} \sim \exp_{q_{\text{rel}}}(-t/\tau_q)$, where τ_q is a relaxation time. Figures 6(a) and (b) show the time dependence of $\ln_{q_{\text{rel}}} \langle \Delta S_{q_{\text{ent}}}(t) \rangle / \langle S_{q_{\text{ent}}}(\infty) \rangle$ for

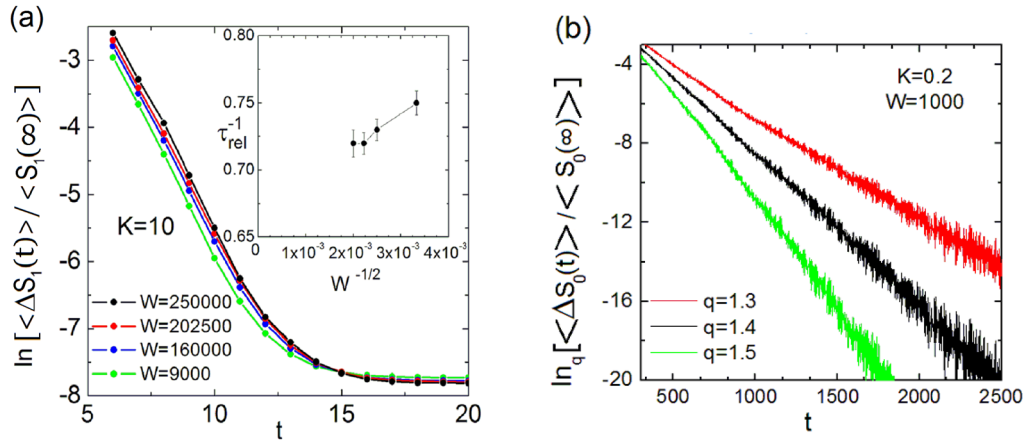


Figure 6. (a) Time evolution of $\ln_{q_{\text{rel}}} \langle \Delta S_{q=1}(t) \rangle / \langle S_{q=1}(\infty) \rangle$ in the $K = 10$ (strongly chaotic) standard map. The averages have been calculated over the more quickly spreading cells, to optimize the computational cost. Inset represents the numerical estimations of the inverse of relaxation time $\tau_{\text{rel}}^{-1}(W^{-1/2})$. (b) Time evolution of $\ln_{q_{\text{rel}}} \langle \Delta S_{q=0}(t) \rangle / \langle S_{q=0}(\infty) \rangle$ in the $K = 0.2$ (weakly chaotic) standard map. The averages are calculated over the cells that belong to the same longitudinal band analyzed in figure 5. According to a procedure similar to what was done in figure 3, the nonlinearity measure identifies $q_{\text{rel}} = 1.4$.

the strongly chaotic case ($K = 10$), and for the weakly chaotic case ($K = 0.2$), respectively. The former case displays an exponential relaxation, i.e. $q_{\text{rel}} = 1$, consistently with BG framework. Observe that the numerical estimations of the inverse time of relaxation to the $S_{q_{\text{ent}}=1}(\infty)$ entropy limit, are compatible with a finite relaxation time $\tau_{q=1} \equiv \tau_{\text{rel}}(W \rightarrow \infty)$. The weakly chaotic case presents a q -exponential relaxation regime, with $q_{\text{rel}} \simeq 1.4$ for $K = 0.2$. The numerical estimation of q_{rel} , for intermediate values of the map parameter K , is much more subtle because of the uncertainty related to the numerical estimation of $\ln_{q_{\text{ent}}} W_{\text{islands}}$.

5. Stationary distributions

Probability density distributions are among the most relevant items regarding the statistical description of nonlinear dynamical systems. Gaussian distributions are typical for ergodic and mixing systems, for which LLE is positive [24, 39], and q -Gaussian distributions are typical for weakly chaotic systems for which LLE = 0 [24, 39–41].

We define the q -Gaussian distribution as

$$P_q(x; \mu_q, \sigma_q) = A_q \sqrt{B_q} \left[1 - (1 - q) B_q (x - \mu_q)^2 \right]^{\frac{1}{1-q}}, \quad (7)$$

where μ_q is the q -mean value, σ_q is the q -variance, A_q is the normalization factor and B_q is a parameter which characterizes the width of the distribution [42]:

$$A_q = \begin{cases} \frac{\Gamma[\frac{5-3q}{2(1-q)}]}{\Gamma[\frac{2-q}{1-q}]} \sqrt{\frac{1-q}{\pi}}, & q < 1 \\ \frac{1}{\sqrt{\pi}}, & q = 1 \\ \frac{\Gamma[\frac{1}{q-1}]}{\Gamma[\frac{3-q}{2(q-1)}]} \sqrt{\frac{q-1}{\pi}}, & 1 < q < 3 \end{cases} \quad (8)$$

$$B_q = [(3-q)\sigma_q^2]^{-1} \quad (9)$$

where $q \rightarrow 1$ recovers the Gaussian distribution $P_1(x; \mu_1, \sigma_1) = \frac{1}{\sigma_1 \sqrt{2\pi}} e^{-\frac{1}{2}(\frac{x-\mu_1}{\sigma_1})^2}$.

Both Gaussian and q -Gaussian distributions have recently been observed for the standard map. In [24], the authors analyzed, for representative K values, the distribution of sums of iterates of the map

$$y = \sum_{i=1}^T (x_i - \langle x \rangle), \quad (10)$$

where $\langle \dots \rangle$ represents both time average over T iterations and ensemble average over M initial conditions, i. e.

$$\langle x \rangle = \frac{1}{M} \frac{1}{T} \sum_{j=1}^M \sum_{i=1}^T x_i^{(j)}. \quad (11)$$

The probability distributions of y , namely $P(y)$, that emerge from the standard map with weakly chaotic phase space are q -Gaussians (say $q \equiv q_{\text{stat}} \neq 1$), while Gaussian distributions are associated with the strongly chaotic regime (say $q \equiv q_{\text{stat}} = 1$). The scenario for intermediate values of K is also quite rich. For these cases, the phase space displays regions with points that have positive LLE, —the chaotic sea—, and regions with $\lambda = 0$, —the stability islands. The probability distributions for initial conditions within the strongly chaotic regions are Gaussians ($q_{\text{stat}} = 1$), and the probability distributions for initial conditions that belong to the weakly chaotic regions are q -Gaussians ($q_{\text{stat}} \neq 1$). One remarkable feature is that, for initial conditions within weakly chaotic regions, $q_{\text{stat}} \simeq 1.935$ in all cases, regardless the value of K .

Observe that if the initial conditions are spread over the entire phase space, the initial conditions are from both the chaotic sea and the stability islands. In that case, the distribution that emerges is a linear combination of a Gaussian and a q -Gaussian. Consequently, the probability distribution of the standard map, for any arbitrary value of K , can be modeled as

$$P(y) = \alpha P_q(y; \mu_q, \sigma_q) + (1 - \alpha) P_1(y; \mu_1, \sigma_1). \quad (12)$$

where $P_q(y)$ and $P_1(y)$ are the probability densities for the initial conditions taken inside the weak and strong regions, respectively. In [24] it was taken the linear combination of the probability distributions normalized to the maximum value $P(0)$, and the physical meaning of the interpolating parameter was not clear.

Let us now take the linear combination of the usual probability densities in equation (12). First, we find out the ratio of the areas for the strongly and weakly chaotic regions. In order to achieve this, we randomly generate $N_{\text{ic}} = 4 \times 10^6$ initial

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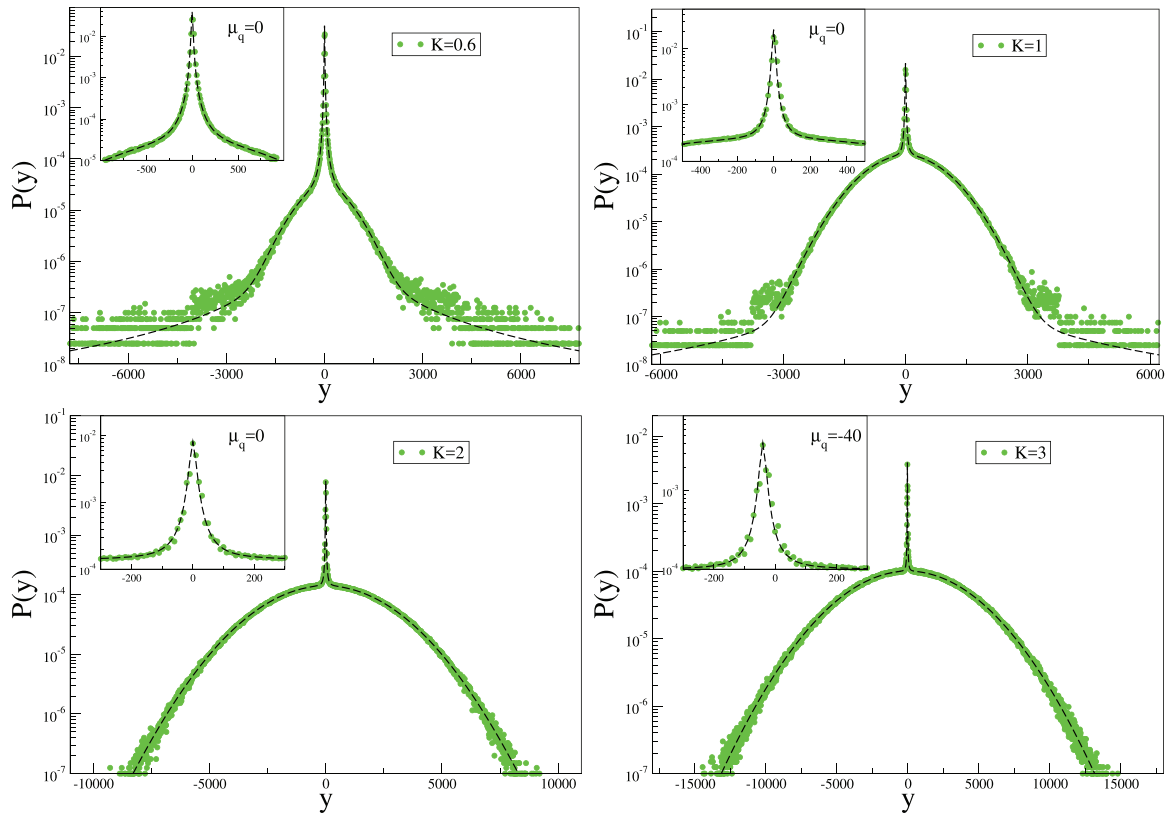


Figure 7. Probability distribution functions of the standard map for 4 representative K values. In all cases, $T = 2^{22}$ and $M = 4 \times 10^7$.

Table 1. The values of the parameters for representative K values.

$A_1 = 0.5642\dots$, $A_{q=1.935} = 0.3364\dots$				
K	B_1	B_q	α_1	α_q
0.2	—	0.015	0	1
0.6	10.7×10^{-7}	0.015	0.0380	0.9416
1	8.00×10^{-7}	0.015	0.4826	0.5078
2	1.06×10^{-7}	0.010	0.7622	0.2367
3	0.40×10^{-7}	0.010	0.8825	0.1170
10	0.52×10^{-7}	—	1	0

conditions all over the phase space and count how many of those having non-zero LLE and those having nearly zero LLE. Dividing these numbers by the total number of initial conditions, we mimic the ratio of the areas. We classify an initial condition belonging to a weakly chaotic region if its LLE is smaller than a given threshold $\lambda < \lambda_- = 5 \times 10^{-5}$. Correspondingly, an initial condition is considered to belong to a strongly chaotic region whenever $\lambda > \lambda_+ = 10^{-2}$. These limiting values λ_- and λ_+ are chosen according to what is explained in [24]: the phase-space ratio, i.e. (number of points with $\lambda < \lambda_{\text{threshold}}$)/(number of points with $\lambda > \lambda_{\text{threshold}}$) remains almost constant for $\lambda_- < \lambda_{\text{threshold}} < \lambda_+$. We call $\alpha_1 = N_{\text{ic}}(\lambda > \lambda_+)/N_{\text{ic}}$, and $\alpha_q = N_{\text{ic}}(\lambda < \lambda_-)/N_{\text{ic}}$. There remains a small amount of initial conditions with intermediate finite time LLE values ($\lambda_- \leq \lambda \leq \lambda_+$) that are not taken into account in equation (12), and that are

expected to be neglectable in the macroscopic limit. We have thus considered the approximated form of equation (12) as

$$P(y) \approx \alpha_q P_q(y; \mu_q, \sigma_q) + \alpha_1 P_1(y; \mu_1, \sigma_1). \quad (13)$$

The values of α_1 and α_q for some representative K values are shown in table 1. The respective values of B_1 and B_q are computed using the pdf of the system that arises from the initial conditions with positive and (nearly) zero LLE, respectively. Once B_1 and B_q values are known, we have no fitting parameter and α values are entirely determined by the intrinsic dynamics of the map. Figure 7 shows our results for some representative values of K .

6. Concluding remarks

The q -triplet (q_{ent} , q_{rel} , q_{stat}) is an important feature in the statistical description of dynamical systems that might be nonergodic and/or nonmixing, as a consequence of zero largest Lyapunov exponent (LLE). These indices define the rate of entropy production, the rate of relaxation, and the distribution of the nearly stationary states. Positive LLE leads to mixing and ergodic systems, and the strongly chaotic regime makes these three indices to collapse into $q = 1$, within the BG framework. Zero LLE characterize weak chaos and may lead to breakdown of ergodicity and nonmixing dynamics. The statistical description in many such circumstances appears to be associated with the q -entropy, where the usual exponential and Gaussian functions turn into more general forms, namely the q -exponential and the q -Gaussian ones. This scenario has been previously observed and evaluated for dissipative low-dimensional systems.

We have now considered a paradigmatic low-dimensional conservative system, namely the standard map. We have evaluated the q -triplet, and have numerically verified that the sensitivity to initial conditions index satisfies $q_{\text{sen}} = q_{\text{ent}}$, in both strongly and weakly chaotic regimes. Our results corroborate the expected situation, i.e. that if the entire phase space is strongly chaotic (LLE > 0), $q_{\text{ent}} = q_{\text{rel}} = q_{\text{stat}} = 1$ and $K_{q_{\text{ent}}}^{\text{av}} = \lambda_{q_{\text{sen}}}^{\text{av}} \simeq 1.62 > 0$. The present results are numerically compatible with a q -generalization of a Pesin-like identity for ensemble averages, extending the results in [28] to the case of conservative maps. If the entire phase space is in a nearly weakly chaotic regime (nearly vanishing LLE), which happens for low values of K , we show that the standard map is characterized by $q_{\text{ent}} = 0$, $q_{\text{rel}} \simeq 1.4$, and $q_{\text{stat}} \simeq 1.935$. We have also shown that $\lambda_{q_{\text{sen}}}^{\text{av}}$ is a property that can be characterized by the smaller alignment index (SALI), a computationally cheap tool to identify different chaotic regimes and to discriminate a variety of transient times and dynamical behaviors. The phase space for intermediate values of K exhibits regions of positive LLE and regions of zero LLE. Ensemble averages of initial conditions taken within the strongly chaotic regions behave, independently of the value of K , according to $q_{\text{ent}} = q_{\text{sen}} = q_{\text{stat}} = 1$, and $K_{q_{\text{ent}}}^{\text{av}} = \lambda_{q_{\text{sen}}}^{\text{av}}$. In contrast, ensemble averages of initial conditions taken within the weakly chaotic regions behave according to the non degenerate q -triplet, with precisely the same values of q_{ent} , q_{sen} and q_{stat} obtained for say $K = 0.2$. This work improves what has been done in [24], as we have numerically found the proper superposition of

distributions for the mixed case (coexistence of strongly and weakly chaotic regimes) without any additional fitting parameter.

The q -triplet structure plays a central role on the statistical description of many nonlinear dynamical systems, and additional effort addressing other conservative and dissipative maps shall bring further tests for the robustness of this framework, and they are very welcome.

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