Flow: Waves and instabilities in stationary plasmas

Overview

- Introduction: theoretical themes for a complete MHD description of laboratory and astrophysical plasmas, static versus stationary plasmas;
- **Spectral theory of stationary plasmas:** Frieman–Rotenberg formalism for waves and instabilities, non-selfadjointness and complex eigenvalues, implications of the Doppler shift for the continuous spectra;
- Kelvin–Helmholtz instability of streaming plasmas: gravitating plasma with an interface where the velocity changes discontinuously, influence of the magnetic field;
- Magneto-rotational instability of rotating plasmas: derivation of the dispersion equation, growth rates of instabilities, application to accretion disks.

Theoretical themes

- We have encountered:
 - Central concept of magnetic flux tubes \Rightarrow Cylindrical plasmas, 1D: f(r)[book: Chap. 9]
 - Astrophysical flows (winds, disks, jets) \Rightarrow **Plasmas with background flow**

[this lecture, future Volume 2]

- Magnetic confinement for fusion (tokamak) \Rightarrow Toroidal plasmas, 2D: $f(r, \vartheta)$ [next lecture, future Volume 2]
- Explosive phenomena due to reconnection \Rightarrow **Dissipative MHD**

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[future Volume 2]
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- All plasma dynamics (e.g. space weather) ⇒ Computational MHD
 [future Volume 2]
- Dynamos, transonic flows, shocks, turbulence \Rightarrow Nonlinear MHD

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[future Volume 2]
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• MHD with background flow is the most urgent topic (also for fusion since divertors and neutral beam injection cause significant flows in tokamaks).

 \Rightarrow From static (v = 0) to stationary (v \neq 0) plasmas!

Static versus stationary plasmas

• Starting point is the set of nonlinear ideal MHD equations:

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{v}) = 0, \qquad (1)$$

$$\rho(\frac{\partial \mathbf{v}}{\partial t} + \mathbf{v} \cdot \nabla \mathbf{v}) + \nabla p - \mathbf{j} \times \mathbf{B} - \rho \mathbf{g} = 0, \qquad \mathbf{j} = \nabla \times \mathbf{B}, \qquad (2)$$

$$\frac{\partial p}{\partial t} + \mathbf{v} \cdot \nabla p + \gamma p \nabla \cdot \mathbf{v} = 0, \qquad (3)$$

$$\frac{\partial \mathbf{B}}{\partial t} - \nabla \times (\mathbf{v} \times \mathbf{B}) = 0, \qquad \nabla \cdot \mathbf{B} = 0, \tag{4}$$

with gravitational acceleration $\mathbf{g}=-\nabla\Phi_{gr}$ due to external gravity field $\Phi_{gr}.$

• Recall the simplicity of static equilibria ($\partial/\partial t = 0$, $\mathbf{v} = 0$),

$$\nabla p = \mathbf{j} \times \mathbf{B} + \rho \mathbf{g}, \qquad \mathbf{j} = \nabla \times \mathbf{B}, \qquad \nabla \cdot \mathbf{B} = 0,$$
 (5)

with perturbations described by self-adjoint operator \mathbf{F} with real eigenvalues ω^2 :

$$\mathbf{F}(\boldsymbol{\xi}) = \rho \frac{\partial^2 \boldsymbol{\xi}}{\partial t^2} \quad \Rightarrow \quad \mathbf{F}(\hat{\boldsymbol{\xi}}) = -\rho \omega^2 \hat{\boldsymbol{\xi}} \,. \tag{6}$$

• Can one construct a similar powerful scheme for stationary plasmas ($\mathbf{v} \neq 0$)?

Stationary equilibria

• Basic nonlinear ideal MHD equations for stationary equilibria ($\partial/\partial t = 0$):

$$\nabla \cdot (\rho \mathbf{v}) = 0, \tag{7}$$

$$\rho \mathbf{v} \cdot \nabla \mathbf{v} + \nabla p = \mathbf{j} \times \mathbf{B} + \rho \mathbf{g}, \qquad \mathbf{j} = \nabla \times \mathbf{B},$$
(8)

$$\mathbf{v} \cdot \nabla p + \gamma p \nabla \cdot \mathbf{v} = 0, \qquad (9)$$

$$\nabla \times (\mathbf{v} \times \mathbf{B}) = 0, \qquad \nabla \cdot \mathbf{B} = 0.$$
 (10)

 \Rightarrow None of them trivially satisfied now (except for simple geometries)!

• For plane gravitating plasma slab, equilibrium unchanged w.r.t. static case:

$$(p + \frac{1}{2}B^2)' = -\rho g \qquad (' \equiv d/dx).$$
 (11)

• For cylindrical plasma, the equilibrium is changed significantly by the centrifugal acceleration, $-\mathbf{v} \cdot \nabla \mathbf{v} = (v_{\theta}^2/r)\mathbf{e}_r$:

$$(p + \frac{1}{2}B^2)' = \frac{1}{r}(\rho v_\theta^2 - B_\theta^2) - \rho \Phi_{\rm gr}' \qquad (' \equiv d/dr).$$
(12)

⇒ Modifications for plane and cylindrical stationary flows quite different: translations and rotations are physically different phenomena. Frieman–Rotenberg formalism

[Rev. Mod. Phys. 32, 898 (1960)]

Spectral theory for general stationary equilibria (no further simplifying assumptions):



 First, construct displacement vector ξ connecting perturbed flow at position r with unperturbed flow at position r⁰:

$$\mathbf{r}(\mathbf{r}^0, t) = \mathbf{r}^0 + \boldsymbol{\xi}(\mathbf{r}^0, t)$$
. (13)

• In terms of the coordinates (\mathbf{r}^0, t) , the equilibrium ρ^0 , \mathbf{v}^0 , p^0 , \mathbf{B}^0 (\mathbf{r}^0) is time-independent, satisfies Eqs. (7)–(10).

• Gradient
$$\nabla = (\nabla \mathbf{r}^0) \cdot \nabla^0 = \nabla (\mathbf{r} - \boldsymbol{\xi}) \cdot \nabla^0 \approx \nabla^0 - (\nabla^0 \boldsymbol{\xi}) \cdot \nabla^0$$
, (14)

and Lagrangian time derivative

$$\frac{\mathrm{D}}{\mathrm{D}t} \equiv \frac{\partial}{\partial t} \Big|_{\mathbf{r}^0} + \mathbf{v}^0 \cdot \nabla^0 \,, \tag{15}$$

yield expression for the velocity:

$$\mathbf{v}(\mathbf{r}^{0} + \boldsymbol{\xi}) \equiv \frac{\mathrm{D}\mathbf{r}}{\mathrm{D}t} = \frac{\mathrm{D}\mathbf{r}^{0}}{\mathrm{D}t} + \frac{\mathrm{D}\boldsymbol{\xi}}{\mathrm{D}t} = \mathbf{v}^{0} + \mathbf{v}^{0} \cdot \nabla^{0}\boldsymbol{\xi} + \frac{\partial\boldsymbol{\xi}}{\partial t}.$$
 (16)

Frieman–Rotenberg formalism (cont'd)

• Linearization of Eqs. (1), (3), (4) gives perturbed quantities in terms of ξ alone:

$$\rho \approx \rho^0 - \rho^0 \nabla^0 \cdot \boldsymbol{\xi} \,, \tag{17}$$

$$p \approx p^0 - \gamma p^0 \nabla^0 \cdot \boldsymbol{\xi} ,$$
 (18)

$$\mathbf{B} \approx \mathbf{B}^0 + \mathbf{B}^0 \cdot \nabla^0 \boldsymbol{\xi} - \mathbf{B}^0 \nabla^0 \cdot \boldsymbol{\xi} , \qquad (19)$$

where we will now drop the superscripts 0 (since they are tagged on everything).

• Inserting these into Eq. (2) yields the **spectral equation for stationary equilibria:**

$$\rho \frac{\partial^2 \boldsymbol{\xi}}{\partial t^2} + 2\rho \mathbf{v} \cdot \nabla \frac{\partial \boldsymbol{\xi}}{\partial t} - \mathbf{F}(\boldsymbol{\xi}) = 0, \qquad (20)$$

$$\mathbf{F} \equiv \mathbf{F}_{\text{static}} + \nabla \cdot \left[\rho (\mathbf{v} \cdot \nabla \mathbf{v}) \boldsymbol{\xi} - \rho \mathbf{v} \mathbf{v} \cdot \nabla \boldsymbol{\xi} \right],$$
(21)

$$\mathbf{F}_{\text{static}} \equiv -\nabla \pi - \mathbf{B} \times (\nabla \times \mathbf{Q}) + (\nabla \times \mathbf{B}) \times \mathbf{Q} + (\nabla \Phi) \nabla \cdot (\rho \boldsymbol{\xi}).$$

• For normal modes, $\boldsymbol{\xi} \sim \exp(-i\omega t)$, a quadratic eigenvalue problem is obtained:

$$\mathbf{F}(\boldsymbol{\xi}) + 2\mathrm{i}\rho\omega\mathbf{v}\cdot\nabla\boldsymbol{\xi} + \rho\omega^{2}\boldsymbol{\xi} = 0, \qquad (22)$$

where the operator \mathbf{F} is non-selfadjoint and the eigenvalues ω are complex!

Spectral equation for plane slab

• For the plane slab model of Chapter 7, extended with a plane shear flow field,

$$\mathbf{B} = B_y(x)\mathbf{e}_y + B_z(x)\mathbf{e}_z, \quad \rho = \rho(x), \quad p = p(x),$$

$$\mathbf{v} = v_y(x)\mathbf{e}_y + v_z(x)\mathbf{e}_z, \quad (23)$$

the equilibrium is unchanged and the two new terms in \mathbf{F} yield: $\mathbf{v} \cdot \nabla \mathbf{v} = 0$ and $-\nabla \cdot (\rho \mathbf{v} \mathbf{v} \cdot \nabla \boldsymbol{\xi}) = -\rho (\mathbf{v} \cdot \nabla)^2 \boldsymbol{\xi}$, so that the eigenvalue problem (22) becomes:

$$\mathbf{F}_{\text{static}}(\boldsymbol{\xi}) = -\rho(\omega + \mathrm{i}\mathbf{v}\cdot\nabla)^2\,\boldsymbol{\xi} \equiv -\rho\widetilde{\omega}^2\,\boldsymbol{\xi}\,. \tag{24}$$

• Hence, the equations for the static slab remain valid with the following replacement:

$$\omega \quad \to \quad \widetilde{\omega}(x) \equiv \omega - \mathbf{k}_0 \cdot \mathbf{v}(x) \,, \tag{25}$$

where $\widetilde{\omega}(x)$ is the *local Doppler shifted frequency* observed in a local frame comoving with the plasma layer at the vertical position x.

• Since $\tilde{\omega}$ depends on x, eigenvalues of discrete modes will be shifted by some average of the local Doppler shifts across the layer. If a static equilibrium is unstable (eigenvalue ω on positive imaginary axis), for the corresponding equilibrium with flow that eigenvalue moves into the complex plane and becomes an *overstable mode*.

HD continua for plane shear flow

• How are the MHD waves affected by background flow of the plasma?

First, consider **continuous spectrum in the HD case** for plane slab geometry, inhomogeneous fluid with horizontal flow:

$$\mathbf{v} = v_y(x)\mathbf{e}_y + v_z(x)\mathbf{e}_z\,.$$

• Lagrangian time derivative:

$$(\mathrm{D}f/\mathrm{d}t)_1 \equiv (\partial f/\partial t + \mathbf{v} \cdot \nabla f)_1 = -\mathrm{i}\,\widetilde{\omega}f_1 + f_0' v_{1x}\,, \qquad \widetilde{\omega} \equiv \omega - \mathbf{k_0} \cdot \mathbf{v}\,,$$

 $\widetilde{\omega}(x)$: frequency observed in local frame co-moving with fluid layer at position x.

• Singularities when $\tilde{\omega} = 0$ somewhere in the fluid \Rightarrow HD flow continuum { $\Omega_0(x)$ }, consisting of the zeros of the local Doppler shifted frequency

$$\widetilde{\omega} \equiv \omega - \Omega_0, \qquad \Omega_0 \equiv -i \mathbf{v} \cdot \nabla = \mathbf{k_0} \cdot \mathbf{v},$$

on the interval $x_1 \le x \le x_2$. These singularities have been the subject of extensive investigations in the hydrodynamics literature.

[Lin 1955, Case 1960, Drazin and Reid, Hydrodynamic Stability (Cambridge, 2004)]

MHD continua for plane shear flow

• Forward (+) / backward (-) Alfvén and slow continua, and fast cluster points:

$$\Omega_A^{\pm} \equiv \Omega_0 \pm \omega_A, \qquad \omega_A \equiv F/\sqrt{\rho}, \qquad F \equiv -i \mathbf{B} \cdot \nabla = \mathbf{k}_0 \cdot \mathbf{B},$$

$$\Omega_S^{\pm} \equiv \Omega_0 \pm \omega_S, \qquad \omega_S \equiv \sqrt{\frac{\gamma p}{\gamma p + B^2}} F/\sqrt{\rho}, \quad \Omega_0 \equiv -i \mathbf{v} \cdot \nabla = \mathbf{k}_0 \cdot \mathbf{v},$$

$$\Omega_F^{\pm} \equiv \pm \infty.$$

 The flow contribution to the MHD continua creates the following ordering of the local frequencies (which are all real) in the co-moving frame:

$$\Omega_F^- \le \Omega_{f0}^- \le \Omega_A^- \le \Omega_{s0}^- \le \Omega_S^- \le \Omega_0 \le \Omega_S^+ \le \Omega_{s0}^+ \le \Omega_A^+ \le \Omega_{f0}^+ \le \Omega_F^+$$

- The discrete spectra are monotonic along the real ω -axis outside these frequencies.
- In the limit $\mathbf{B} \to 0$, the Alfvén and slow continua collapse into the flow continuum,

$$\Omega_A^{\pm} \to \Omega_0, \qquad \Omega_S^{\pm} \to \Omega_0 \qquad \text{(whereas } \Omega_F^{\pm} \text{ remains at } \pm \infty\text{)}.$$

Vice versa, the flow continuum is absorbed by the four MHD continua when $B \neq 0$: Contrary to statements in the literature, *there is no separate flow continuum in MHD*. [Goedbloed, Beliën, van der Holst, Keppens, *Phys. Plasmas* **11**, 4332 (2004)]

HD & MHD spectra along the real axis

• **HD spectrum** of stationary plane fluid flow:



• MHD spectrum of stationary plane plasma flow:



Kelvin–Helmholtz instability: equilibrium

- Extend Rayleigh–Taylor instability of plasma–vacuum interface (sheets 6-36 6-42) to plasma–plasma interface with two different velocities (see figure on 6-36): Rayleigh–Taylor + Kelvin–Helmholtz!
- Upper layer ($0 < x \le a$):

$$\rho = \text{const}, \quad \mathbf{v} = (0, v_y, v_z) = \text{const}, \quad \mathbf{B} = (0, B_y, B_z) = \text{const},$$
$$p' = -\rho g \quad \Rightarrow \quad p = p_0 - \rho g x \quad (p_0 \ge \rho g a). \tag{26}$$

Lower layer ($-b \le x < 0$):

$$\hat{\rho} = \text{const}, \quad \hat{\mathbf{v}} = (0, \hat{v}_y, \hat{v}_z) = \text{const}, \quad \hat{\mathbf{B}} = (0, \hat{B}_y, \hat{B}_z) = \text{const},$$
$$\hat{p}' = -\hat{\rho}g \qquad \Rightarrow \quad \hat{p} = \hat{p}_0 - \hat{\rho}gx. \quad (27)$$

• Jumps at the interface (x = 0):

$$p_{0} + \frac{1}{2}B_{0}^{2} = \hat{p}_{0} + \frac{1}{2}\hat{B}_{0}^{2} \qquad \text{(pressure balance)}, \qquad (28)$$
$$\mathbf{j}^{\star} = \mathbf{n} \times \llbracket \mathbf{B} \rrbracket = \mathbf{e}_{x} \times (\mathbf{B} - \hat{\mathbf{B}}) \qquad \text{(surface current)}, \qquad (29)$$
$$\boldsymbol{\omega}^{\star} = \mathbf{n} \times \llbracket \mathbf{v} \rrbracket = \mathbf{e}_{x} \times (\mathbf{v} - \hat{\mathbf{v}}) \qquad \text{(surface vorticity)}.$$

Kelvin–Helmholtz instability: normal modes

• Now (in contrast to energy principle analysis of 6-36 – 6-42), normal mode analysis:

$$\boldsymbol{\xi} \sim \exp\left[\mathrm{i}(k_y y + k_z z - \omega t)\right].$$

• For *incompressible plasma*, taking limit $c^2 \equiv \gamma p / \rho \rightarrow \infty$ of Eq. (50) on sheet 7-20, *with plane flow,* replacing $\omega \rightarrow \tilde{\omega}$ (Eq. (25) of sheet F-7), basic ODE becomes:

$$\frac{d}{dx}\left[\rho(\widetilde{\omega}^2 - \omega_A^2)\frac{d\xi}{dx}\right] - k_0^2\left[\rho(\widetilde{\omega}^2 - \omega_A^2) + \rho'g\right]\,\xi = 0\,.$$
(30)

Doppler shifted freq. $\widetilde{\omega} \equiv \omega - \Omega_0$, $\Omega_0 \equiv \mathbf{k}_0 \cdot \mathbf{v}$; Alfvén freq. $\omega_A \equiv \mathbf{k}_0 \cdot \mathbf{B}/\sqrt{\rho_0}$.

 In this case, all equilibrium quantities constant so that ODEs simplify to equations with constant coefficients:

$$\xi'' - k_0^2 \xi = 0$$
, BC $\xi(a) = 0 \implies \xi = C \sinh[k_0(a - x)]$, (31)

$$\hat{\xi}'' - k_0^2 \hat{\xi} = 0$$
, BC $\hat{\xi}(-b) = 0 \implies \hat{\xi} = \hat{C} \sinh[k_0(x+b)]$. (32)

 \Rightarrow Surface modes (cusp-shaped eigenfunctions). This part is trivial: all physical intricacies reside in the BCs at x = 0 determining the eigenvalues.

Kelvin–Helmholtz instability: interface conditions

- Now (in contrast to energy principle analysis of 6-36–6-42), need both interface conditions (model II* BCs), to determine relative amplitude \hat{C}/C and eigenvalue ω :
 - First interface condition (continuity of normal velocity):

$$[\mathbf{n} \cdot \boldsymbol{\xi}] = 0 \quad \Rightarrow \quad \boldsymbol{\xi}(0) = \hat{\boldsymbol{\xi}}(0) = 0 \quad \Rightarrow \quad \boldsymbol{C} = \hat{\boldsymbol{C}}.$$
(33)

- Second interface condition (pressure balance):

$$\left[\!\left[\Pi + \mathbf{n} \cdot \boldsymbol{\xi} \,\mathbf{n} \cdot \nabla (p + \frac{1}{2}B^2)\right]\!\right] = 0, \quad \Pi \equiv -\gamma p \nabla \cdot \boldsymbol{\xi} - \boldsymbol{\xi} \cdot \nabla p + \mathbf{B} \cdot \mathbf{Q}, \quad (34)$$

where $\gamma p \nabla \cdot \boldsymbol{\xi}$ is undetermined. Determine Π from expression for compressible plasmas, Book, Eq. (7.99), with ω replaced by $\widetilde{\omega}$ and taking limit $\gamma \to \infty$:

$$\Pi \equiv -\frac{\widetilde{N}}{\widetilde{D}}\xi' + \rho g \,\frac{\widetilde{\omega}^2(\widetilde{\omega}^2 - \omega_A^2)}{\widetilde{D}}\xi \ \to \ \frac{\rho}{k_0^2}(\widetilde{\omega}^2 - \omega_A^2)\xi'\,. \tag{35}$$

• Dividing the second by the first interface condition then gives

$$\left[\frac{\rho}{k_0^2} (\widetilde{\omega}^2 - \omega_A^2) \frac{\xi'}{\xi} - \rho g \right] = 0 \quad \Rightarrow \quad \text{eigenvalue } \omega \,. \tag{36}$$

Kelvin–Helmholtz instability: dispersion equation

• Inserting solutions (31) and (32) for ξ and $\hat{\xi}$ yields the **dispersion equation**:

$$-\rho\left[(\omega-\Omega_0)^2-\omega_A^2\right]\coth(k_0a)-k_0\rho g=\hat{\rho}\left[(\omega-\hat{\Omega}_0)^2-\hat{\omega}_A^2\right]\coth(k_0b)-k_0\hat{\rho}g.$$
(37)

Describes magnetic field line bending (Alfvén), gravity (RT), velocity difference (KH).

- Approximations for long wavelengths $(k_0 x \ll 1)$: $\operatorname{coth} k_0 x \approx (k_0 x)^{-1}$, short wavelengths $(k_0 x \gg 1)$: $\operatorname{coth} k_0 x \approx 1$.
- Solutions for short wavelengths (walls effectively at ∞ and $-\infty$):

$$\omega = \frac{\rho \Omega_0 + \hat{\rho} \hat{\Omega}_0}{\rho + \hat{\rho}} \pm \sqrt{-\frac{\rho \hat{\rho} (\Omega_0 - \hat{\Omega}_0)^2}{(\rho + \hat{\rho})^2} + \frac{\rho \omega_A^2 + \hat{\rho} \hat{\omega}_A^2}{\rho + \hat{\rho}} - \frac{k_0 (\rho - \hat{\rho})g}{\rho + \hat{\rho}}} \,. \tag{38}$$

 \Rightarrow Stable (square root real) if

$$(\mathbf{k}_0 \cdot \mathbf{B})^2 + (\mathbf{k}_0 \cdot \hat{\mathbf{B}})^2 > \frac{\rho \hat{\rho}}{\rho + \hat{\rho}} \left[\mathbf{k}_0 \cdot (\mathbf{v} - \hat{\mathbf{v}}) \right]^2 + k_0 (\rho - \hat{\rho}) g \,.$$
(39)
magnetic shear K–H drive R–T drive

Kelvin–Helmholtz instability: generic transitions

• Pure KH instability (
$$\mathbf{B} = \hat{\mathbf{B}} = 0, g = 0, \mathbf{k}_0 \| \mathbf{v} \| \hat{\mathbf{v}}$$
):

$$\omega = k_0 \left[\frac{\rho v + \hat{\rho} \hat{v}}{\rho + \hat{\rho}} \pm i \frac{\sqrt{\rho \hat{\rho}}}{\rho + \hat{\rho}} |v - \hat{v}| \right].$$
(40)

 \Rightarrow Degeneracy of Doppler mode $\omega = k_0 v$ lifted by $v \neq \hat{v}$.

• Doppler shifted RT instability ($\mathbf{B} = \hat{\mathbf{B}} = 0$, $\mathbf{v} = \hat{\mathbf{v}}$, $\mathbf{k}_0 \parallel \mathbf{v}$):

$$\omega = k_0 v \pm i \sqrt{\frac{k_0(\rho - \hat{\rho})g}{\rho + \hat{\rho}}}.$$
(41)

 \Rightarrow Degeneracy of Doppler mode $\omega = k_0 v$ lifted by $\rho \neq \hat{\rho}$.

• Hence, generic *transitions to instability* for (a) static, and (b) stationary plasmas:



Exp. growth: through origin

Overstability: through real axis

Kelvin–Helmholtz instability: generalizations

• Of course, the assumption of two homogeneous plasma layers with a velocity difference at the interface (made to make the analysis tractable for a relevant instability) evades the basic problems of **diffuse plasma flows:** continuous spectra, cluster points, and *eigenvalues on unknown paths in the complex* ω *plane.*

 \Rightarrow Further progress only by *linear computational methods:* finite differences and finite elements, spectral methods, linear system solvers, etc.

• Instabilities always grow towards amplitudes that necessitate consideration of the **nonlinear evolution**: *coupling of linear modes, nonlinear saturation, and turbulence* appear: see simulation of Rayleigh–Taylor instability with Versatile Advection Code, where secondary Kelvin–Helmholtz instabilities develop (sheet 6-42).

 \Rightarrow Further progress only by *nonlinear computational methods:* implicit and semiimplicit time stepping, finite volume methods, shock-capturing methods, etc.

Magneto-rotational instability

- Example of **cylindrical flow**. Original references:
 - Velikhov, Soviet Phys.-JETP Lett. 36, 995 (1959);
 - Chandrasekhar, Proc. Nat. Acad. Sci. USA 46, 253 (1960).
- Applied to accretion disks by Balbus and Hawley, Astrophys. J. **376**, 214 (1991). Problem: how can accretion on Young Stellar Object (mass $M_* \sim M_{\odot}$) or Active Galactic nucleus (mass $M_* \sim 10^9 M_{\odot}$) occur at all on a reasonable time scale?
 - Without dissipation impossible, because disk would conserve angular momentum; some form of viscosity needed to transfer angular momentum to larger distances.
 - However, ordinary molecular viscosity much too small to produce sizeable transfer, and for turbulent increase (small-scale instabilities) no HD candidates were found.
 - It is generally assumed that the resolution of this problem involves MHD instability: the magneto-rotational instability (MRI).
- Simplify the axi-symmetric (2D) representation of the disk (see sheet 4-9) even further by *neglecting vertical variations* so that a cylindrical (1D) slice is obtained.
 [One should object: but that is no disk at all anymore! Yet, this is how plasma-astrophysicists grapple with the problem of anomalous (turbulent) transport.]

MRI: cylindrical representation

• Generalization of Hain–Lüst equation, Book, Eq. (9.31), to cylindrical flow with normal modes $\boldsymbol{\xi} \sim \exp\left[i(m\theta + kz - \omega t)\right],$

again yields second order ODE for radial component of the plasma displacement:

$$\frac{d}{dr} \left[\frac{\widetilde{N}}{r\widetilde{D}} \frac{d\chi}{dr} \right] + \left[\widetilde{U} + \frac{\widetilde{V}}{\widetilde{D}} + \left(\frac{\widetilde{W}}{\widetilde{D}} \right)' \right] \chi = 0, \qquad \chi \equiv r\xi.$$
(42)

[Bondeson, Iacono and Bhattacharjee, Phys. Fluids **30**, 2167 (1987); extended with gravity: Keppens, Casse, Goedbloed, Astrophys. J. **569**, L121 (2002)]

• Assumption of *small magnetic field*,

$$\beta \equiv 2p/B^2 \gg 1\,,\tag{43}$$

justifies use of this spectral equation in the *incompressible limit*:

$$\frac{d}{dr} \left[\frac{\rho \widetilde{\omega}^2 - F^2}{m^2 / r^2 + k^2} \frac{1}{r} \frac{d\chi}{dr} \right] - \left[\frac{1}{r} (\rho \widetilde{\omega}^2 - F^2) + \left(\frac{B_{\theta}^2 - \rho v_{\theta}^2}{r^2} \right)' - \rho' \frac{\Phi_{\rm gr}}{r^2} - \frac{4k^2 (B_{\theta}F + \rho \widetilde{\omega} v_{\theta})^2}{r^3 (m^2 / r^2 + k^2) (\rho \widetilde{\omega}^2 - F^2)} - \left(\frac{2m (B_{\theta}F + \rho \widetilde{\omega} v_{\theta})}{r^3 (m^2 / r^2 + k^2)} \right)' \right] \chi = 0.$$
(44)



• Gravitational potential of compact object is approximated for cylindrical slice,

$$\Phi_{\rm gr} = -GM_*/\sqrt{r^2 + z^2} \approx -GM_*/r$$
, (45)

with short wavelengths fitting the disk in the vertical direction:

$$k\,\Delta z \gg 1\,.\tag{46}$$

• Incompressibility is consistent with *constant density* so that the only gravitational term, $-\rho' \Phi_{\rm gr}/r^2$, disappears from the spectral equation. However, $\Phi_{\rm gr}$ does not disappear from the equilibrium equation that ρ , p, B_{θ} , B_z , and v_{θ} have to satisfy,

$$(p + \frac{1}{2}B^2)' = \frac{1}{r}(\rho v_{\theta}^2 - B_{\theta}^2) - \rho \Phi_{\rm gr}',$$

so that stability will still be determined by gravity.

MRI: further approximations

• Assume purely vertical and constant magnetic field and purely azimuthal velocity,

$$B_{\theta} = 0, \quad v_z = 0 \quad \Rightarrow \quad \omega_A = k B_z / \sqrt{\rho} = \text{const}, \quad \Omega_0 = m v_{\theta} / r,$$
 (47)

and restrict analysis to *vertical wave numbers* k only,

$$m = 0 \quad \Rightarrow \quad \Omega_0 = 0 \quad \Rightarrow \quad \widetilde{\omega} = \omega \quad \text{(instability through } \omega = 0 \text{!)}$$
 (48)

The spectral equation then simplifies to:

$$\left(\omega^2 - \omega_A^2\right) \frac{d}{dr} \left(\frac{1}{r} \frac{d\chi}{dr}\right) - \frac{k^2}{r} \left[\omega^2 - \omega_A^2 - r \left(\frac{v_\theta^2}{r^2}\right)' - \frac{4\omega^2 v_\theta^2 / r^2}{\omega^2 - \omega_A^2}\right] \chi = 0.$$
(49)

• Introducing angular frequency $\Omega \equiv v_{\theta}/r$, and epicyclic frequency κ ,

$$\kappa^2 \equiv \frac{1}{r^3} (r^4 \Omega^2)' = 2r \Omega \Omega' + 4\Omega^2 \tag{50}$$

(~ deviation from const spec. ang. mom. $L \equiv \rho r v_{\theta} \equiv \rho r^2 \Omega$, $\kappa^2 = 0 \Rightarrow L' = 0$), the spectral equation becomes:

$$\left(\omega^2 - \omega_A^2\right) \frac{d}{dr} \left(\frac{1}{r} \frac{d\chi}{dr}\right) - \frac{k^2}{r} \left[\omega^2 - \omega_A^2 - \kappa^2 - \frac{4\omega_A^2 \Omega^2}{\omega^2 - \omega_A^2}\right] \chi = 0.$$
 (51)

MRI: criteria

• Recall construction of quadratic form (sheet 7-24e):

$$(P\chi')' - Q\chi = 0 \qquad \Rightarrow \quad \int (P\chi'^2 + Q\chi^2) \, r \, dr = 0 \,. \tag{52}$$

 \Rightarrow For eigenfunctions (oscillatory χ), we should have Q/P < 0 for some r.

• From Eq. (51), this gives the following *criteria for instability* ($\omega^2 < 0$):

(a) MHD ($\omega_A^2 \neq 0$): $\omega_A^2 + \kappa^2 - 4\Omega^2 < 0$ (b) HD ($\omega_A^2 \equiv 0$): $\kappa^2 < 0$ (for some range of r). (53)

• For Keplerian rotation (neglecting p and B on equilibrium motion):

$$\frac{1}{r}\rho v_{\theta}^2 = \rho \Phi_{\rm gr}' = \rho \frac{GM_*}{r^2} \quad \Rightarrow \quad \Omega^2 = \frac{GM_*}{r^3} \quad \Rightarrow \quad \kappa^2 = \frac{GM_*}{r^3} > 0 \,. \tag{54}$$

⇒ In HD limit, opposite of (53)(b) holds, *Rayleigh's circulation criterion is satisfied: the fluid is stable* to axi-symmetric disturbances (m = 0) if $\kappa^2 \ge 0$ everywhere. This explains interest in MHD instabilities as candidates for turbulent increase of the dissipation processes in accretion disks.

MRI: MHD versus HD

• MHD instability criterion in the limit $\omega_A^2 \rightarrow 0$ (magnetic field sufficiently small):

$$\kappa^2 - 4\Omega^2 \equiv 2r\Omega\Omega' < 0.$$
⁽⁵⁵⁾

This is **satisfied for Keplerian disks:** MRI works for astrophysically relevant cases! Stabilizing field contribution ($\omega_A^2 > 0$) should be small enough to maintain this effect.

- Discrepancy of HD and MHD stability results is due to *interchange of limits:* HD disk: ω_A² = 0, ω² → 0, MHD disk: ω² = 0, ω_A² → 0. This discrepancy is resolved when the *growth rates* of the instabilities are considered.
- Instead of numerically solving ODE (51), just consider radially localized modes, $\chi \sim \exp(iqr), \ q \Delta r \gg 1$, producing a *local dispersion equation:*

$$(k^{2} + q^{2})(\omega^{2} - \omega_{A}^{2})^{2} - k^{2}\kappa^{2}(\omega^{2} - \omega_{A}^{2}) - 4k^{2}\omega_{A}^{2}\Omega^{2} = 0.$$
 (56)

Solutions for $q^2 \ll k^2$:

$$\omega^{2} = \omega_{A}^{2} + \frac{1}{2}\kappa^{2} \pm \frac{1}{2}\sqrt{\kappa^{4} + 16\omega_{A}^{2}\Omega^{2}} \approx \begin{cases} \kappa^{2} + \omega_{A}^{2}(1 + 4\Omega^{2}/\kappa^{2}) \\ \omega_{A}^{2}(1 - 4\Omega^{2}/\kappa^{2}) \end{cases}, \quad (57)$$

Limit $\omega_A^2 \to 0$ gives: Rayleigh mode (HD), $\omega_+^2 \to \kappa^2 > 0$, MRI (MHD), $\omega_-^2 \to 0$.